



ϕ -Pseudo Symmetric ϵ -Para Sasakian Manifolds

P. Somashekhar, Venkatesha

Department of Mathematics, Kuvempu University, Shimoga, India

Email: somumathrishi@gmail.com, vensmath@gmail.com

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Abstract

The present paper focuses on the study of ϕ -pseudo symmetric, ϕ -pseudo concircularly symmetric and ϕ -pseudo Ricci symmetric on ϵ -Para Sasakian Manifolds. Also interesting results are obtained.

Subject Areas

Geometry

Keywords

ϵ -Para Sasakian Manifolds, ϕ -Pseudo Symmetric and ϕ -Pseudo Ricci Symmetric

1. Introduction

Majority of present approaches to mathematical general relativity launch with the concept of a manifold. The standpoint of physics and relativity is to the investigation of manifolds with indefinite metrics. Several authors have studied manifold with indefinite matrices. Bejancu and Duggal [1] originated the concept of ϵ -Sasakian manifolds in 1993. De and Sarkar [2] pioneered (ϵ)-Kenmotsu manifolds and investigated some curvature conditions on it. Pandey and Tiwari [3] constructed the relation between semi-symmetric metric connection and Riemannian connection of (ϵ)-Kenmotsu manifolds and have studied several curvature conditions. The notion of (ϵ)-Para Sasakian Manifolds was pioneered by Tripathi *et al.* [4] in 2009.

The Riemannian symmetric spaces were introduced by French mathematician Cartan during the nineteenth century and play a main tool in differential geometry. A Riemannian manifold is locally symmetric [5], if $\nabla R = 0$, where R is the Riemannian curvature tensor of (M, g) . During the last five decades the notion of locally symmetric manifolds has been studied by many authors in sev-

eral ways to a different extent such as recurrent manifold by Walker [6], semi-symmetric manifold by Szabó [7], pseudosymmetric manifold in the sense of Deszcz [8], a non-flat Riemannian manifold (M^n, g) ($n > 2$) is said to be pseudosymmetric in the sense of Chaki [9] if it satisfies the relation

$$\begin{aligned} & (\nabla_W R)(X, Y, Z, U) \\ &= 2A(W)R(X, Y, Z, U) + A(X)R(W, Y, Z, U) + A(Y)R(X, W, Z, U) \\ &+ A(Z)R(X, Y, W, U) + A(U)R(X, Y, Z, W), \end{aligned} \quad (1.1)$$

i.e.,

$$\begin{aligned} & (\nabla_W R)(X, Y)Z \\ &= 2A(W)R(X, Y)Z + A(X)R(W, Y)Z + A(Y)R(X, W)Z \\ &+ A(Z)R(X, Y)W + g(R(X, Y)Z, W)\rho, \end{aligned} \quad (1.2)$$

for any $X, Y, Z, U, W \in T_p(M)$ and where R is the Riemannian curvature tensor of the manifold, A is a non-zero 1-form such that $g(X, \rho) = A(X)$ for every vector field X . Every recurrent manifold is pseudosymmetric in the sense of Chaki [9] but not conversely. The pseudosymmetry in the sense of Chaki is not equivalent to that in the sense of Deszcz [8]. However, the pseudosymmetry by Chaki will be the pseudosymmetry by Deszcz if and only if the non-zero 1-form associated with n -dimensional pseudosymmetry is closed. Pseudosymmetric manifolds also have been studied by Chaki and De [10], Özen and Altay [11], Tarafder [12], De, Murathan and Özgür [13], Tarafder and De [14] and others. Many authors have been weakened by Ricci symmetry that has been differently extended such as a Ricci recurrent, Ricci symmetric and pseudo Ricci symmetric for past two decades.

A non-flat Riemannian manifold (M^n, g) is said to be pseudo-Ricci symmetric [15] if its Ricci tensor S of type $(0, 2)$ is not identically zero and satisfies the condition

$$(\nabla_X S)(Y, Z) = 2A(X)S(Y, Z) + A(Y)S(X, Z) + A(Z)S(Y, X), \quad (1.3)$$

for any $X, Y, Z \in T_p(M)$ where A is a nowhere vanishing 1-form and ∇ refers the operator of covariant differentiation with respect to the metric tensor g . Such a n -dimensional manifold is denoted by $(PRS)_n$. The pseudo-Ricci symmetric manifolds have also been studied by Arslan *et al.* [16], De and Mazumder [17] and many others. The notion of locally ϕ -symmetric Sasakian manifold was introduced by Takahashi [18] due to a weaker version of locally symmetry. Generating the notion of locally ϕ -symmetric Sasakian manifolds, De *et al.* [19], introduce the notion of ϕ -recurrent Sasakian manifolds also Shukla *et al.* [20] studied ϕ -symmetric and ϕ Ricci symmetric para Sasakian manifolds.

Inspired by above studies this paper makes an attempt to study of ϕ -pseudo symmetric and ϕ -pseudo Ricci symmetric ϵ -para Sasakian manifolds. It is organized as follows. Section 2 is related with ϵ -para Sasakian manifolds. Section 3 is dealt with the study of ϕ pseudo symmetric ϵ -para Sasakian manifolds. In Section 4, we study of ϕ -pseudo Concircularly symmetric ϵ -para Sasakian manifold.

In Section 5, we study ϕ -pseudo Ricci symmetric ϵ -para Sasakian manifold. The relation (1.3) can be written as

$$(\nabla_x Q)(Y) = 2A(X)Q(Y) + A(Y)Q(X) + S(Y, X)\rho, \tag{1.4}$$

where ρ is the vector field associated to the 1-form A such that $A(X) = g(X, \rho)$ and Q is the Ricci operator, *i.e.*, $g(QX, Y) = S(X, Y)$.

2. Preliminaries

Let (M^n, g) be an almost paracontact manifold is equipped with an almost paracontact structure (ϕ, ξ, η) consisting of a tensor field ϕ of type $(1, 1)$, a vector field ξ and a 1-form η satisfying

$$\phi^2 X = X - \eta(X)\xi, \tag{2.1}$$

$$\eta(\xi) = -1, \phi\xi = 0, \eta \circ \phi = 0, \tag{2.2}$$

$$g(\phi X, \phi Y) = g(X, Y) - \epsilon\eta(X)\eta(Y), \tag{2.3}$$

where $\epsilon = \pm 1$, in this case (M^n, g) is called an (ϵ) -almost paracontact metric manifold equipped with an (ϵ) -almost paracontact structure (ϕ, ξ, η, g) [21]. In particular, $\text{index}(g) = 1$, then (ϵ) -almost paracontact metric manifold will be called a Lorentzian almost paracontact metric manifold. In view of equation [22] [23], we have

$$g(\phi X, Y) = g(X, \phi Y), \tag{2.4}$$

$$g(x, \xi) = \epsilon\eta(X), \tag{2.5}$$

for any $X, Y \in T_p M$, the structure of a vector field ξ is a never light like. An (ϵ) -almost paracontact metric manifold (respectively a Lorentzian almost paracontact manifold $(M^n, \phi, \xi, g, \epsilon)$ is said to be space-like (ϵ) -almost paracontact metric manifold (respectively a space-like Lorentzian almost paracontact manifold), if $\epsilon = 1$ and (M^n, g) is said to be a time-like (ϵ) -almost paracontact metric manifold (respectively a Lorentzian almost paracontact manifold), if $\epsilon = -1$. An (ϵ) -almost paracontact metric structure is called an (ϵ) -Para Sasakian structure if

$$(\nabla_x \phi)(Y) = -g(X, \phi Y)\xi - \epsilon\eta(Y)\phi^2 X, \tag{2.6}$$

where ∇ is the Levi-Civita connection. A manifold (M^n, g) endowed with an (ϵ) -para Sasakian structure is called an (ϵ) -para Sasakian manifold. For $\epsilon = 1$ and g is a Riemannian, (M^n, g) is the usual para Sasakian manifold [24]. For $\epsilon = -1$, g Lorentzian and ξ replaced by $-\xi$, (M^n, g) becomes a Lorentzian para Sasakian manifold [23]. In an (ϵ) -para Sasakian manifold, we have

$$\nabla_x \xi = \epsilon\phi X, \tag{2.7}$$

$$g(\xi, \xi) = \pm 1 = \epsilon, \tag{2.8}$$

$$(\nabla_x \eta)(Y) = \epsilon g(\phi X, Y) = \Omega(X, Y), \tag{2.9}$$

for any $X, Y \in T_p M$, where Ω is the fundamental 2-form. In an (ϵ) -almost

para Sasakian manifold (M^n, g) , the following relations are hold.

$$\eta(R(X, Y)Z) = \epsilon[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)], \tag{2.10}$$

$$R(\xi, X)Y = -\epsilon g(X, Y)\xi - \epsilon\eta(Y)X, \tag{2.11}$$

$$R(X, Y)\xi = -\epsilon\eta(Y)X + \epsilon\eta(X)Y, \tag{2.12}$$

$$(\nabla_X R)(Y, Z)\xi = \epsilon^2[g(\phi X, Y)Z - g(\phi X, Z)Y]. \tag{2.13}$$

In an n -dimensional (ϵ) -para Sasakian manifold (M^n, g) , the Ricci tensor satisfies

$$S(\phi X, \phi Y) = S(X, Y) + (n-1)\eta(X)\eta(Y), \tag{2.14}$$

$$S(X, \xi) = S(\xi, X) = -(n-1)\eta(X). \tag{2.15}$$

3. ϕ -Pseudo Symmetric on ϵ -Para Sasakian Manifold

Definition 3.1. A ϵ -Para Sasakian manifold $(M^n)(\phi, \xi, \eta, g)$ is said to be a ϕ -pseudo symmetric if the curvature tensor R satisfies

$$\begin{aligned} &\phi^2((\nabla_W R)(X, Y)Z) \\ &= 2A(W)R(X, Y)Z + A(X)R(W, Y)Z + A(Y)R(X, W)Z \\ &\quad + A(Z)R(X, Y)W + g(R(X, Y)Z, W)\rho, \end{aligned} \tag{3.1}$$

for any $X, Y, Z, W \in T_p M$. If $A = 0$ the manifold is said to be ϕ -symmetric.

By virtue of (2.1), it follows that

$$\begin{aligned} &(\nabla_W R)(X, Y)Z - \eta((\nabla_W R)(X, Y)Z)\xi \\ &= 2A(W)R(X, Y)Z + A(X)R(W, Y)Z + A(Y)R(X, W)Z \\ &\quad + A(Z)R(X, Y)W + g(R(X, Y)Z, W)\rho, \end{aligned} \tag{3.2}$$

from which it follows that

$$\begin{aligned} &g((\nabla_W R)(X, Y)Z, U) - \eta((\nabla_W R)(X, Y)Z)\eta(U) \\ &= 2A(W)g(R(X, Y)Z, U) + A(X)g(R(W, Y)Z, U) \\ &\quad + A(Y)g(R(X, W)Z, U) + A(Z)g(R(X, Y)W, U) \\ &\quad + g(R(X, Y)Z, W)A(U). \end{aligned} \tag{3.3}$$

Taking an orthonormal frame field and contracting (3.3) over X and U , then by using (2.2) and (2.5), we get

$$\begin{aligned} &(\nabla_W S)(Y, Z) - g((\nabla_W R)(\xi, Y)Z, \xi) \\ &= 2A(W)S(Y, Z) + A(Y)S(W, Z) + A(Z)S(Y, W) \\ &\quad + A(R(W, Y)Z) + A(R(W, Z)Y). \end{aligned} \tag{3.4}$$

Using (2.11) and (2.13), we have

$$g((\nabla_W R)(\xi, Y)Z, \xi) = 0, \tag{3.5}$$

by virtue of (3.5), it follows from (3.4) that

$$(\nabla_w S)(Y, Z) = 2A(W)S(Y, Z) + A(Y)S(W, Z) + A(Z)S(Y, W) + A(R(W, Y)Z) + A(R(W, Z)Y), \tag{3.6}$$

This leads to the following:

Theorem 3.1. *A ϕ -pseudo symmetric on a ϵ -para Sasakian manifold is Pseudo-Ricci symmetric if and only if $A(R(W, Y)Z) + A(R(W, Z)Y) = 0$.*

Putting $Z = \xi$ in (3.2), by using (2.10), (2.12) and (2.13), we have

$$\begin{aligned} & A(\xi)R(X, Y)W \\ &= \epsilon^2 [g(\phi W, Y)X - g(\phi W, X)Y] + \epsilon \{2A(W)[\eta(Y)X - \eta(X)Y] \\ & \quad + A(X)[\eta(Y)W - \eta(W)Y] + A(Y)[\eta(X)W - \eta(W)X] \\ & \quad + [\eta(Y)g(X, W) - \eta(X)g(Y, W)]\rho\}. \end{aligned} \tag{3.7}$$

This leads to the following:

Theorem 3.2. *A ϕ -pseudo symmetric on a ϵ -para Sasakian manifold, the curvature tensor satisfies the relation (3.7).*

From (3.7) follows that

$$\begin{aligned} A(\xi)S(Y, W) &= \epsilon^2 (n-1)\Omega(W, Y) + \epsilon \{(n-1)\eta(Y)A(W) \\ & \quad + (n-1)\eta(W)A(Y) + \eta(Y)\eta(W) + g(Y, W)\}, \end{aligned} \tag{3.8}$$

replacing Y by ϕY and W by ϕW and using (2.3), (2.14), we have

$$S(Y, W) = \frac{1}{A(\xi)} \{ \epsilon g(Y, W) - [\epsilon^2 + (n-1)A(\xi)]\eta(Y)\eta(W) + \epsilon^2 (n-1)\Omega(Y, W) \}. \tag{3.9}$$

Hence we can state the following:

Theorem 3.3. *A ϕ -pseudo symmetric on a ϵ -para Sasakian manifold, the curvature tensor satisfies the relation (3.9), provided $A(\xi) \neq 0$.*

4. ϕ -Pseudo Concircularly Symmetric ϵ -Para Sasakian Manifold

Definition 4.2. *A n -dimensional ϵ -para Sasakian manifold is said to be ϕ -pseudo Concircularly symmetric, if its Concircular curvature tensor \tilde{C} is given by [25]*

$$\tilde{C}(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)} [g(Y, Z)X - g(X, Z)Y]. \tag{4.1}$$

Satisfies the relation

$$\begin{aligned} & \phi^2 ((\nabla_w \tilde{C})(X, Y)Z) \\ &= 2A(W)\tilde{C}(X, Y)Z + A(X)\tilde{C}(W, Y)Z + A(Y)\tilde{C}(X, W)Z \\ & \quad + A(Z)\tilde{C}(X, Y)W + g(\tilde{C}(X, Y)Z, W)\rho, \end{aligned} \tag{4.2}$$

for any $X, Y, Z, W \in T_p M$, where A is a non-zero 1-forms, such that $A(X) = g(X, \rho)$.

by virtue of (2.1), it follows from (4.2)

$$\begin{aligned} & (\nabla_w \tilde{C})(X, Y)Z - \eta((\nabla_w \tilde{C})(X, Y)Z)\xi \\ &= 2A(W)\tilde{C}(X, Y)Z + A(X)\tilde{C}(W, Y)Z + A(Y)\tilde{C}(X, W)Z \\ & \quad + A(Z)\tilde{C}(X, Y)W + g(\tilde{C}(X, Y)Z, W)\rho, \end{aligned} \tag{4.3}$$

which follows that

$$\begin{aligned} & g((\nabla_w \tilde{C})(X, Y)Z, U) - \eta((\nabla_w \tilde{C})(X, Y)Z)\eta(U) \\ &= 2A(W)g(\tilde{C}(X, Y)Z, U) + A(X)g(\tilde{C}(W, Y)Z, U) \\ & \quad + A(Y)g(\tilde{C}(X, W)Z, U) + A(Z)g(\tilde{C}(X, Y)W, U) \\ & \quad + g(\tilde{C}(X, Y)Z, W)A(U). \end{aligned} \tag{4.4}$$

Taking an orthonormal frame field and contracting (4.4) over X and U , by using (2.1) and (4.1), we get

$$\begin{aligned} & (\nabla_x S)(Y, Z) - \frac{dr(W)}{n}g(Y, Z) + g((\nabla_w \tilde{C})(\xi, Y)Z, \xi) \\ &= 2A(W)S(Y, Z) + A(Y)S(W, Z) + A(Z)S(Y, W) - \frac{r}{n}[2A(W)g(Y, Z) \\ & \quad + A(Y)g(W, Z) + A(Z)g(Y, W)] + A(\tilde{C}(W, Y)Z) + A(\tilde{C}(W, Z)Y), \end{aligned} \tag{4.5}$$

by virtue of (3.5) and from (4.1), yields

$$g((\nabla_w \tilde{C})(\xi, Y)Z, \xi) = -\frac{dr(W)}{n(n-1)}[g(Y, Z) - \eta(Y)\eta(Z)]. \tag{4.6}$$

In view of (4.6) from (4.5), we have

$$\begin{aligned} & (\nabla_x S)(Y, Z) - \frac{dr(W)}{n}g(Y, Z) - \frac{dr(W)}{n(n-1)}[g(Y, Z) - \eta(Y)\eta(Z)] \\ &= 2A(W)S(Y, Z) + A(Y)S(W, Z) + A(Z)S(Y, W) - \frac{r}{n}[2A(W)g(Y, Z) \\ & \quad + A(Y)g(W, Z) + A(Z)g(Y, W)] + A(\tilde{C}(W, Y)Z) + A(\tilde{C}(W, Z)Y). \end{aligned} \tag{4.7}$$

This leads to the following:

Theorem 4.4. *A ϕ -pseudo Concircularly symmetric ϵ -para Sasakian manifold is pseudo-Ricci symmetric if and only if*

$$\begin{aligned} & \frac{dr(W)}{n}g(Y, Z) + \frac{dr(W)}{n(n-1)}[g(Y, Z) - \eta(Y)\eta(Z)] \\ & - \frac{r}{n}[2A(W)g(Y, Z) + A(Y)g(W, Z) + A(Z)g(Y, W)] \\ & + A(\tilde{C}(W, Y)Z) + A(\tilde{C}(W, Z)Y) = 0. \end{aligned} \tag{4.8}$$

Putting $Z = \xi$ in (4.3) and using (2.10), (2.12), (2.15) and (4.1), we obtain

$$\begin{aligned}
 & \epsilon^2 [\Omega(W, X)Y - \Omega(W, Y)X] - \epsilon \frac{dr(W)}{n(n-1)} [\eta(Y)X - \eta(X)Y] \\
 & + \epsilon \left[1 - \frac{r}{n(n-1)} \right] [\eta(Y)g(X, W) - \eta(X)g(Y, W)] \rho \\
 & \frac{r}{n(n-1)} A(\xi) [g(Y, W)X - g(X, W)Y] \\
 & + \epsilon \left[1 - \frac{r}{n(n-1)} \right] \{ 2A(W) [\eta(Y)X - \eta(X)Y] \\
 & + A(X) [\eta(Y)W - \eta(W)Y] + A(Y) [\eta(W)X - \eta(X)W] \} \\
 & = A(\xi)R(X, Y)W.
 \end{aligned} \tag{4.9}$$

Hence we can state the following:

Theorem 4.5. *In a ϕ -pseudo Concircularly symmetric ϵ -para Sasakian manifold, the curvature tensor satisfies the relation (4.9).*

Next, we take inner product of (4.9) with U and taking an orthonormal frame field and contracting (4.9) over X and U , yields

$$\begin{aligned}
 A(\xi)S(Y, W) &= \epsilon^2 (1-n)\Omega(Y, W) - \epsilon \frac{dr(W)}{n} \eta(Y) \\
 & + \epsilon \left[1 - \frac{r}{n(n-1)} \right] [\eta(Y)\eta(W) - g(Y, W)] + \frac{r}{n} A(\xi)g(Y, W) \\
 & + \epsilon \left[1 - \frac{r}{n(n-1)} \right] (n-1) [2A(W)\eta(Y) + A(Y)\eta(W)].
 \end{aligned} \tag{4.10}$$

Replacing Y by ϕY and W by ϕW , we obtain

$$\begin{aligned}
 S(Y, W) &= \frac{\epsilon^2 (1-n)}{A(\xi)} \Omega(Y, W) + \left[\frac{r}{n} - \frac{\epsilon}{A(\xi)} \left[1 - \frac{r}{n(n-1)} \right] \right] g(Y, W) \\
 & + \left[\frac{\epsilon^2}{A(\xi)} \left[1 - \frac{r}{n(n-1)} \right] - \frac{\epsilon}{A(\xi)} - (n-1) \right] \eta(Y)\eta(W).
 \end{aligned} \tag{4.11}$$

This leads to the following:

Theorem 4.6. *A ϕ -pseudo Concircularly symmetric ϵ -para Sasakian manifold, the curvature tensor satisfies the relation (4.11).*

5. ϕ -Pseudo Ricci Symmetric ϵ -Para Sasakian Manifold

Definition 5.3. *A n -dimensional ϵ -para Sasakian manifold is said to be ϕ -pseudo Ricci symmetric, if the Ricci operator Q satisfies*

$$\phi^2 ((\nabla_w Q)(Y)) = 2A(X)QY + A(Y)QX + S(Y, X)\rho, \tag{5.1}$$

for any $X, Y \in T_p M$, where A is a non zero 1-form.

In particular if $A = 0$, then (5.1) turns into ϕ -Ricci symmetric ϵ -para Sasakian manifold.

In view of (2.1), then (5.1) becomes

$$(\nabla_w Q)(Y) - \eta((\nabla_w Q)(Y))\xi = 2A(X)QY + A(Y)QX + S(Y, X)\rho, \quad (5.2)$$

which follows

$$\begin{aligned} g((\nabla_w Q)(Y), Z) - S(\nabla_w Y, Z) - \eta((\nabla_w Q)(Y))\eta(Z) \\ = 2A(X)S(Y, Z) + A(Y)S(X, Z) + S(Y, X)A(Z)\eta, \end{aligned} \quad (5.3)$$

putting $Y = \xi$ in (5.3), using (2.7) and (2.15), we get

$$\begin{aligned} A(\xi)S(X, Z) + \epsilon S(\phi X, Z) \\ = (n-1)[\epsilon g(\phi X, Z) + 2A(X)\eta(Z) + \eta(X)A(Z)]. \end{aligned} \quad (5.4)$$

Replacing X by ϕX , Z by ϕZ in (5.4) and using (2.14), we get

$$S(X, Z) = \frac{\epsilon}{A(\xi)}[(n-1)\Omega(X, Z) - S(\phi X, Z)] - (n-1)\eta(X)\eta(Z). \quad (5.5)$$

This leads to the following:

Theorem 5.7. *A ϕ -pseudo Ricci symmetric ϵ -para Sasakian manifold, the curvature tensor satisfies the relation (5.5).*

Conflicts of Interest

The authors declare no conflicts of interest regarding the publication of this paper.

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