

Development of Multi-Channel Data Logger for Indoor Environment

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Abstract

Environment monitoring has become a necessity because of global warming and climate change. All across the globe researchers are trying to monitor the environmental parameters of temperature, humidity and pollutants gases more precisely in real time. Sensing system using sensor arrays has been developed to monitor indoor environment, however, these systems are costly and have not gained wide acceptance. Precise monitoring of building environment has a huge potential in terms of energy savings. In this paper, an effort has been made to develop a 4-channel energy efficient and low cost data logger for indoor environment. The Data logger is proposed to be developed with the use of PIC 18F4458. Real Time Clock and EEPROM are interfaced for sampled data with the instance of sampling time and month/date/year; these sampled data will be stored in the EEPROM to the note pad tabular form with the help of graphical user interface (GUI).

Keywords: Gas Sensors, GUI, (Real Time Clock) RTC, ADC, Smart Transducer Interface

1. Introduction

Indoor environment and built-architecture are closely associated. The built environment affects indoor physical environments, and subsequently health and quality of life of occupants. There is evidence showing the pathways and mechanisms by which the built environment affects health and factor associated with specific aspects of physical and mental health. The problem has become acute in recent past because of the rapid industrial growth in last half century and has led to change in lifestyles (Become more dependent on indoor environment) [1]. The main factors of the environmental condition are the air quality and environmental parameter of the inside unconditioned environment. Across the world indoor air quality monitoring is gaining hotspot in present research works because recent study has put forth that 30 – 40% of total natural resources are exploited by the buildings and almost 50% of energy resources is used to condition buildings in industrialized countries. The reality is that indoor air can be up to 10 times more polluted than outdoor air [2]. The major contaminants of indoor environment pollution are CO₂, CO, O₃, SO₂ and NO₂. Many researchers are collect the data for different techniques,

in different fields are facing similar difficulty in data collection *i.e.*, needs a user friendly system is able to collect data from the work place and buildings environment. Pardo *et al.* developed a gas measurement system based on the IEEE 1451.2 standard. They have used the 4-gas sensors (tin oxide), 1-temperature and 1-humidity sensor; this prototype system will be work as electronic nose [3]. Camara *et al.* developed a STIM (smart transducer interface module) based on the IEEE 1451 standard. This prototype system will be work with a lot of different transducers without the necessity of change of the control hardware and software [4].

Available technologies for sensing these environmental parameters are developed by Onseal HOBO, Spectrum Technologies (Watch Dog weather conditions), TandD, Telaire (Wireless Monitoring Systems), Testo, Log Tag, Measurement Computing Corporation, Monarch Instruments, MSR Electronics GmbH, P3 International, Quality Thermistor, S3 Crop, Sensaphone, Sansatronics, Lascar, ICP, Graphtech, Extech Instruments, Dickson, Dent Instruments, Davis, ACR System Inc, 3M International, and Acumen [5].

But we found the developed system is not suitable for the real time monitoring of the indoor environment and

will be required to store the information and data collection for the long duration.

To focus on this problem we are trying to develop a low cost and energy efficient multi channel data logger for indoor environment. We face only 4-parameter such as temperature, relative humidity, SO₂, and NO₂. It can be summarized as follows-interface of LCD (to display the output of various modules), RTC and EEPROM with microcontroller and interface of the data logger to the personal computer by using the serial (RS-232) port, minimization of power consumption in order to enhance battery life and preparing the user friendly graphical user interface in visual language to operate the data logger.

2. Sensors

A sensor is a device that measures a physical quantity and converts it into an equivalent analog or digital signal which can be read by an observer or by an instrument. Monitoring of an indoor environment involves sensing the changes occurring inside it. The parameters which are of importance are the temperature, relative humidity, and concentration level of air pollutant SO₂, and NO₂ inside the building [6,7]. In this paper we have used a p type or n type resistive based semiconductor gas sensor.

A gas sensor detects particular gas molecules and produces an electrical signal whose magnitude is proportional to the concentration of the gas [8]. No single type of gas sensor is 100% selective to a single gas. A good sensor is sensitive to the measured quantity but less sensitive to other quantities. Available gas sensors are based on five basic principles. These can be electrochemical, infrared, catalytic bead, photo ionization and solid-state [9,10]. We have selected these sensors because they produce a strong signal for the selected variable especially at high gas concentrations with adequate sensitivity. They have a fast response time, high stability, long life, low cost, low dependency on humidity, low power consumption, and compact size [8]. **Table 1** represents the Specifications of the Sensors Used in the Multi-Channel Data Logging System and **Table 2** represents the measurement range of the developed system.

3. Signal Processing of the Sensors

Four sensors along with their signal conditioning circuit are used to sense the desired parameter. One is temperature, second is humidity, third is SO₂, and fourth is NO₂. Signal conditioning circuit for that sensor needs to be connected externally. In software we can select any of the analog channel and hence the sensor. Interfacing of temperature, humidity, SO₂, and NO₂ sensor with microcontroller PIC 18F4458 is as follows.

Table 1. Specifications of the sensors used in the multi-channel data logging system [8-10].

Sl. No.	Sensor Name/	Manufacturer	Range	Sensitivity	Response Time
1.	LM35CZ Precision Temp. sensor	National semiconductor, USA	-40 to 110°C	10 mV/°C	< 2 sec
2.	HIH-4000 Humidity sensor	Honeywell, USA	0 to 100%	0.60 pF/%RH	15 sec
3.	SO ₂ -BF	Alphasense, UK	0 to 100 ppm	300 to 440 nA/ppm (20 ppm SO ₂)	< 30 sec
4.	NO ₂ -A1	Alphasense, UK	0 to 20 ppm	-400 to -750 nA/ppm (10ppm NO ₂)	< 40 sec

Table 2. Represents the measurement range of the developed system.

Sl. No.	Measured	Minimum Range	Maximum Range
1.	Temperature	0°C	70°C
2.	Relative Humidity	0%	100%
3.	SO ₂	0 ppm	3 ppm
4.	NO ₂	0 ppm	2.5 ppm

3.1. Temperature Sensor

National semiconductor's LM 35 IC has been used for sensing the temperature. It is an integrated circuit sensor that can be used to measure temperature with an electrical output proportional to the temperature (in °C). The temperature can be measured more accurately with it than using a thermistor. The operating circuit of temperature sensor is shown in **Figure 1**. The output voltage of LM 35 is converted to temperature in °C is [10] as shown in Equation (1).

$$Temp.(^{\circ}C) = (V_{out} \times 100) / 7^{\circ}C \quad (1)$$

V_{OUT} = output voltage of the sensor (volts)

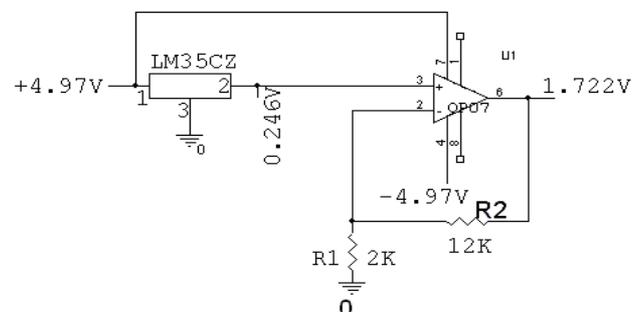


Figure 1. Operating circuit of temperature sensor (LM35 CZ).

3.2. Humidity Sensor

The sensor circuit develops a linear voltage vs. RH output that is ratio metric to the supply voltage. That is, when the supply voltage varies, the sensor output voltage follows in the same proportion. It can operate over a supply voltage range between 4.0 V to 5.8 V. At 5 V supply voltage (at room temperature) *i.e.*, the output voltage ranges from 0.8 to 3.9 V as the humidity varies from 0% to 100% (non-condensing). The humidity sensor functions with a resolution of up to 0.5% of relative humidity (RH), with a typical current draw of only 200 μ A, the HIH-4000 series is ideally suited for low drain, battery operated systems. The pin configuration of humidity sensor is shown in **Figure 2**. The change in the RH of the surroundings causes an equivalent change in the voltage output. The output is an analog voltage proportional to the supply voltage. Consequently, converting it to relative humidity (RH) requires that both the supply and sensor output voltages (At 25°C) [10] as shown in Equation (2).

$$RH = \left(\left(\frac{V_{out}}{V_{supply}} \right) - 0.16 \right) / 0.0062 \quad (2)$$

RH = Relative humidity (%); V_{supply} = Input voltage

3.3. Operating Circuit of the SO₂ and NO₂ Sensor

The SO₂ and NO₂ sensor operating circuit is shown in **Figure 3**. In general the output of the IC1 is connected to the microcontroller pin AN2 and AN1 respectively [9].

4. Analog to Digital Conversion and Interfacing of LCD with Microcontroller

We are using the on chip analog to digital converter

which is on the microcontroller PIC 18F4458. This analog to digital converter is having the 12 bit resolution with programmable acquisition time. It is sensing the analog signal from the sensor at the variable sampling rate (1 sec - 1 hour), the sensed value is converted to its digital equivalent. This digital value is displayed on the LCD (liquid crystal display) which is interfaced to the microcontroller [11-18]. Circuit diagram of LCD interfacing to the microcontroller is shown **Figure 6**.

5. Interfacing of Real Time Clock with Microcontroller

The DS1307 operates as a slave device on the I²C bus. Access is obtained by implementing a START condition and providing a device identification code followed by a register addresses. Subsequent registers can be accessed sequentially until a STOP condition is executed. When V_{CC} falls below $1.25 V_{BAT}$, the device terminates an access in progress and resets the device address counter.

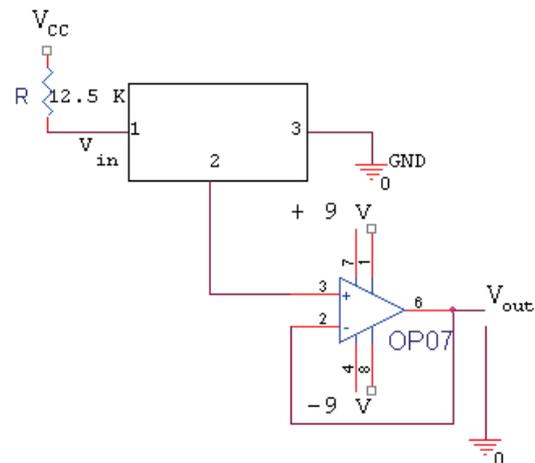


Figure 2. Operating circuit of humidity sensor (HIH4000).

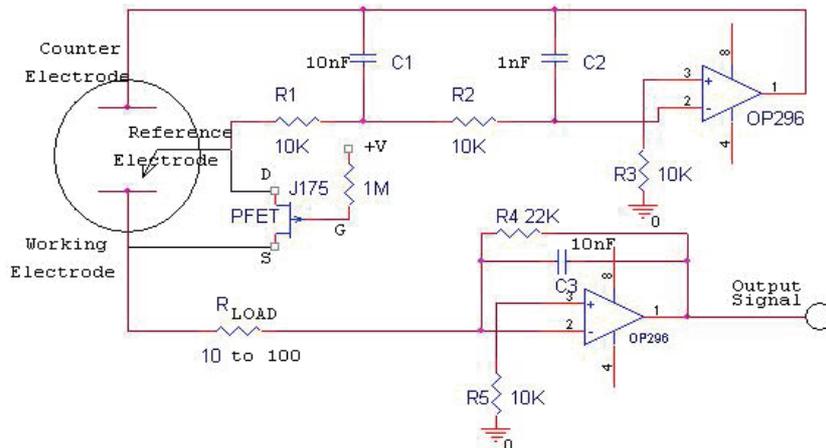


Figure 3. Operating circuit of the SO₂ and NO₂ gas sensor [9].

Inputs to the device will not be recognized at this time to prevent erroneous data from being written to the device from an out of tolerance system. When V_{CC} falls below V_{BAT} , the device switches into a low-current battery-backup mode. Upon power-up, the device switches from battery to V_{CC} when V_{CC} is greater than $V_{BAT} + 0.2$ V and recognizes inputs when V_{CC} is greater than $1.25 V_{BAT}$. **Figure 6** shows the interfacing of real time clock (RTC). We are using the DS1307 real time clock which is having the following features - real time clock counts Hours, Minutes, Seconds, of the Month, Day, Year with Leap-Year Compensation valid up to 2100, 56-Byte, Battery-Backed, Nonvolatile (NV) RAM for data storage, I²C serial interface, programmable square-wave output signal, automatic power fail detect and switch circuitry, consumes less than 500 nA in battery-backup mode oscillator running, and temperature range -40°C to $+85^{\circ}\text{C}$ [14,15].

6. Interfacing of EEPROM with Microcontroller

The EEPROM will store the digital value which is coming from analog to digital converter. We will require the 52.73 MB of EEPROM if we are sampling all analog channels at the rate of 1 sample/Second. We are using the EEPROM AT24C256 of ATMEL. This will store the sample data at different instants. This EEPROM having the following features - low voltage and standard voltage operation 5.0 ($V_{CC} = 4.5$ V to 5.5 V), 2.7 ($V_{CC} = 2.7$ V to 5.5 V), and 1.8 ($V_{CC} = 1.8$ V to 5.5 V); 1 MHZ (5 V), 400 KHZ (2.7 V) and 100 KHZ (1.8 V) compatibility, and 64-Byte page write mode [15,17,18]. **Figure 6** shows the interfacing of EEPROM. We are using the I²C to interface the real time clock (RTC) and EEPROM to the microcontroller. The IC bus is the most popular of the 3 serial EEPROM protocols. **Figure 6** shows the typical pin out of an I²C device, showing pins 1-3 as address pins A0, A1 and A2. Pin 4 is V_{SS} , or ground. Pin 5 is SDA, the data line. Pin 6 is SCL, the clock signal. Pin 7 is write protect, and pin 8 is voltage, or V_{CC} . Finally, many I²C chips include address pins as an easy way to have multiple chips on a single bus while still only using two connections to the microcontroller [14].

7. PC Interfacing with Microcontroller Using RS232 Serial Communication

Personal computer is interfaced with PIC 18F4458 using MAX232. It is the IC used to convert the TTL logic level to the RS232 logic level. RS232 is the serial communication protocol that does not require the clock along with data lines. Two data lines are there one is T_X and another is R_X for serial communication. MAX432 has two re-

ceivers (converts RS-232 logic level to TTL logic) and two drivers (converts TTL logic to RS232 level). Following **Figure 6** shows the hardware interface of PIC with personal computer. Separate power supply has been provided because minimum power supply needed is 5 V and MAX232 consumes a lot of current for operation. External capacitors are required for internal voltage push to convert TTL logic level to RS232 level. For battery operated application MAX232 can be used as level converter instead of MAX232, it is low power consumption logic converter IC for RS232. It is pin compatible with MAX232 [14].

8. Graphical User Interface

A program interfaced that takes advantage of the computer graphics capabilities to make the program easier to use. In this paper, the GUI is one of the important parts it displays the data from microcontroller for data monitoring and analysis. However, the main objective is to display data received in graphical form. As a transducer detects and translate an analog signal, the data will go through a conversion at the ADC and become a digital format. This digital data is converted in a 12 bit data. This data will be stored to the EEPROM chip with the help of Visual Basic 6.0 software. Since the data used the serial RS232 communication, therefore an initialization needs to be done which are the baud rate, data bits, parity, stop bit and the COM port at the PC. The baud rate is the number of signal changes per second or transition speed between Mark (negative) and Space (positive) which range from 110 to 19200, data bits is the length of data in bit which has one least significant bit (LSB) and one most significant bit (MSB), the parity bit is an optional bit mainly for bit error checking. It can be odd, even, none Mark and Space. Stop bit is used to frame up the data bits and usually combined with the start bit. These bits are always represented by a negative voltage and can be 1, 1.5 and 2 stop bits. The commonly used setting to establish a serial RS232 communication is 9600 baud rate, none parity, 8 data bits, and 1 stop bit. As this paper relates with data collection, thus the data obtained from the microcontroller needs to be collected and saved. This can be done by using the GUI monitoring system where it automatically saves the data received in a note pad. The data being saved is the date and time during the data collected and data value it self. **Figures 4** and **5**, represents the graphical user interface and logged data in file [17,18].

9. Schematic of the Data Logger

Figure 6 shows, the full schematic diagram of the data logger for indoor environment. This data logger has four

embedded sensor module and other four channels are open to be used for the measurement of other environmental parameters.

10. Software Design of Data Logger

This subsection includes the software design for all the modules interfaced with PIC 18F4458. It covers complete software design for data logger. The programs have been written to the environmental parameters and concentration level of SO₂ and NO₂ gases are monitored for 24 hours and save the data of EEPROM corresponding to the time and date.

10.1. Programming Steps for I²C Interface

I²C is also bi-directional. This is implemented by an “Acknowledge” system or “ACK” system allows data to

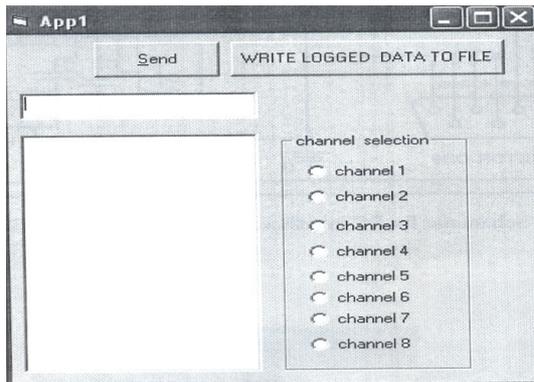


Figure 4. GUI for the data logger.

Date Time	Temp. (°F)	Temp. (°C)	RH (%)	SO2 (ppm)	NO2 (ppm)
06/01/09 06:00:00.0	89.48	31.93	49.04	0.022	0.004
06/01/09 06:10:00.0	89.48	31.93	49.04	0.022	0.004
06/01/09 06:20:00.0	89.48	31.93	49.04	0.022	0.004
06/01/09 06:30:00.0	89.48	31.93	49.04	0.022	0.004
06/01/09 06:40:00.0	89.48	31.93	49.04	0.022	0.004
06/01/09 06:50:00.0	89.48	31.93	49.04	0.022	0.004
06/01/09 07:00:00.0	89.48	31.93	49.04	0.022	0.004
06/01/09 07:10:00.0	89.48	31.93	49.04	0.022	0.004
06/01/09 07:20:00.0	89.48	31.93	49.04	0.024	0.004
06/01/09 09:10:00.0	88.74	31.52	48.32	0.025	0.004
06/01/09 09:20:00.0	88.74	31.52	48.32	0.025	0.004
06/01/09 09:30:00.0	88.74	31.52	48.32	0.025	0.004
06/01/09 09:40:00.0	88.74	31.52	48.32	0.025	0.004
06/01/09 09:50:00.0	88.74	31.52	48.32	0.025	0.004
06/01/09 10:00:00.0	88.74	31.52	48.32	0.025	0.004
06/01/09 10:10:00.0	89.48	31.93	49.04	0.025	0.004
06/01/09 10:20:00.0	89.48	31.93	49.04	0.025	0.004
06/01/09 10:30:00.0	89.48	31.93	49.04	0.025	0.004
06/01/09 10:40:00.0	89.48	31.93	49.04	0.025	0.009
06/01/09 10:50:00.0	89.48	31.93	49.04	0.027	0.009
06/01/09 11:00:00.0	89.48	31.93	49.04	0.027	0.009
06/01/09 11:10:00.0	89.48	31.93	49.04	0.027	0.009
06/01/09 11:20:00.0	90.22	32.34	49.78	0.027	0.009
06/01/09 11:30:00.0	89.48	31.93	49.04	0.027	0.009
06/01/09 11:40:00.0	90.22	32.34	49.78	0.027	0.009
06/01/09 11:50:00.0	90.22	32.34	49.78	0.030	0.009
06/01/09 12:00:00.0	90.22	32.34	49.78	0.030	0.009
06/01/09 12:10:00.0	90.22	32.34	49.78	0.030	0.009
06/01/09 12:20:00.0	90.22	32.34	49.78	0.030	0.010
06/01/09 12:30:00.0	90.22	32.34	49.78	0.030	0.010
06/01/09 12:40:00.0	90.22	32.34	49.78	0.030	0.010
06/01/09 12:50:00.0	90.22	32.34	49.78	0.030	0.010
06/01/09 13:00:00.0	90.22	32.34	49.78	0.030	0.010
06/01/09 13:10:00.0	90.96	32.76	50.54	0.030	0.010

Figure 5. Representation of the logged data in file.

be sent in one direction to one item on the I²C bus, than, that item will “ACK” to indicate the data was received. Normally, the master device controls the clock line, SCL. This line dictates the timing of all transfers on the I²C bus. Other devices can manipulate this line, but they can only force the line low. This action means that item on the bus cannot deal with more data in to any device.

10.1.1. Writing to a I²C Chip

The function of writing to the EEPROM is shown here as “Control IN”, which represents putting the EEPROM in an “input” mode. Since we are only sending data to the EEPROM, we use the “Control IN” byte. We will use “Control OUT” later. **Figure 7** shows the display of data saver memory (data writing of the memory).

Next, the EEPROM acknowledges this byte; this is shown by the “A” after the byte. It is put on the next line to indicate this is transmitted by the EEPROM. Next the PIC microcontroller sends the address byte. The address byte contains the address of the location of the EEPROM; we want to write data. Since the address is valid the data is acknowledged by the EEPROM. Finally, we send the data we want to write. The data is then acknowledged by the EEPROM. When that finishes, we send a stop condition to complete the transfer. Remember the “STOP” is represented as the “T” block on the end. Once the EEPROM gets the “STOP” condition it will begin writing to its memory. The write will not occur until it receives the “STOP” condition.

10.1.2. Reading from an I²C Chip

The transfer will use the “Control IN” byte to load the address into the EEPROM. This sends data to the EEPROM which is why we use the “Control IN” byte. Once the address is loaded, we want to retrieve the data. So, we send a “Control OUT” byte to indicate to the EEPROM that we want data from it. The EEPROM will acknowledge this and then send the data we requested. When we are done getting data, we send a “NACK” to tell the EEPROM that we do not want more data. If we were to send an ACK at this point, we could get the next byte of data from the EEPROM. Since we only want to read one byte, we send a “NACK”. This is detailed in the specifications for the EEPROM. **Figure 8** shows the display of outcome data saver memory (data reading and save outcome data in note pad form).

10.2. Programming Steps for LCD Interface

10.2.1. LCD Module is Initialization and Configuration to Work in 4 Bit Module

Set RS = 0 to send command; send 0b0010 to data lines

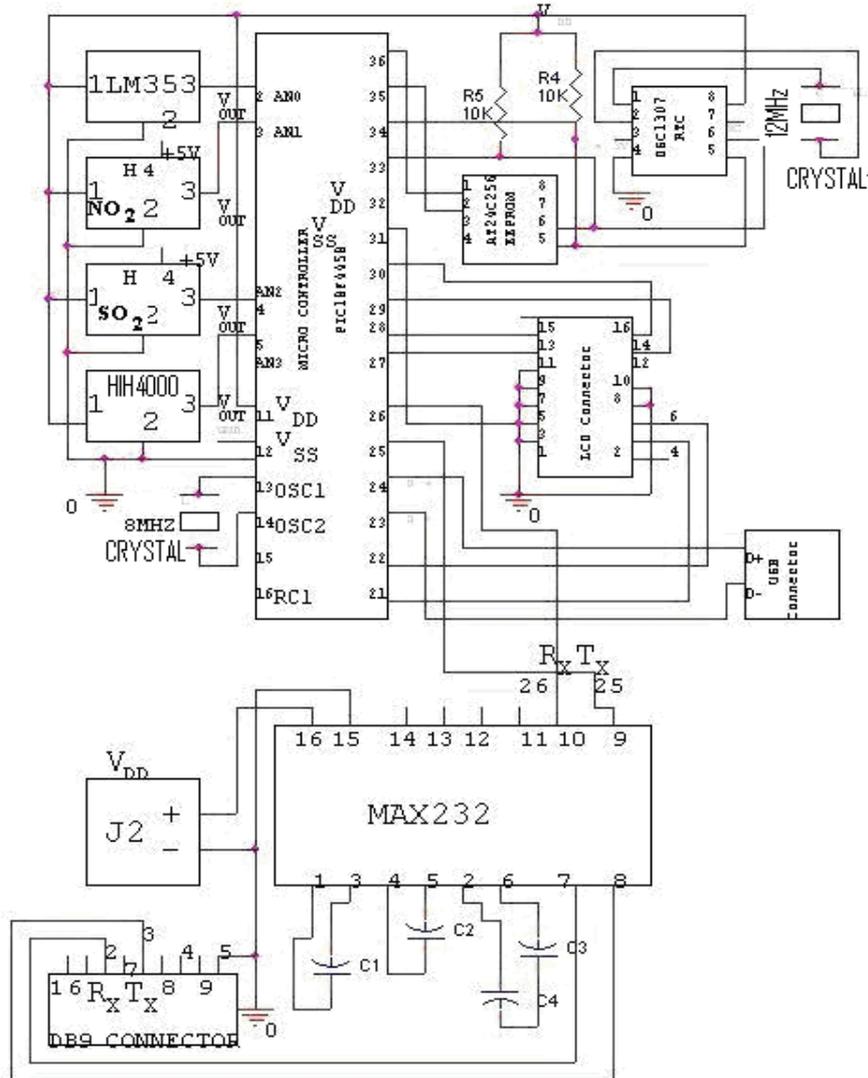


Figure 6. Full schematic of the data logger.

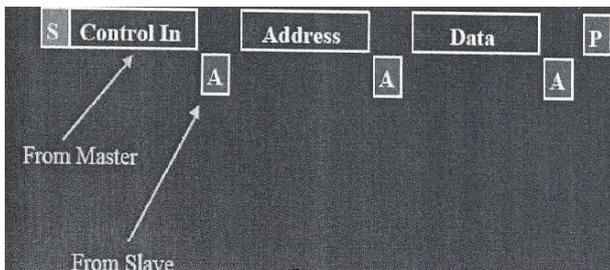


Figure 7. Display of data saver memory.

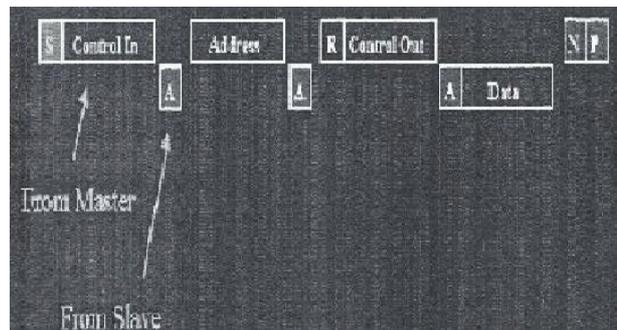


Figure 8. Display of outcome data saver memory.

three times with a delay of 2 ms; to send a byte on 4 data line. Send higher nibble first and give a RE pulse of 100 us at RE. Send a set of instruction one after another with a delay of 2 ms between each command to configure various setting as given in instruction set of LCD data-sheet. Send instruction set again.

10.2.2. Display a Character

Set RS = 1; send higher nibble at 4 data lines. Send 100uS RE pulse; send lower nibble at data lines. Send RE pulse; keep track of number of character already dis-

played on display panel using LCD count up. Go to line 2 or line 1 according to that.

10.3. Programming Steps for Sensor Data Collection

There are connected four sensors temperature, humidity, SO₂, and NO₂. Data is collected by the ADC inbuilt in PIC. ADC provides 10 bit of data after the conversion is completed.

10.3.1. Data Collection of Temperature Sensor

Select the analog channel AN0, alignment of bits for ADRESH and ADRESL, sampling frequency, Vref, power on the ADC module by setting ADCON0, ADCON1 and ADCON2 registers. Start A to D conversion by setting ADGO bit high and wait till ADIF flag will not indicate the completion of conversion and copy the results from ADRESH and ADRESL to variables.

10.3.2. Data Collection of Humidity Sensor

Select the AN3 and set other features of ADC as temperature sensor and after completion of conversion copies the result in variable.

10.3.3. Data Collection of NO₂ and SO₂ Sensor

Data collection from the NO₂ sensor needs following actions to be carried out 1) Selecting the analog channel AN₁, sampling frequency, and alignment of bits for ADRESH and ADRESL, 2) Vref and power on the ADC module by setting ADCON₀, ADCON₁ and ADCON₂ registers, 3) starting analog to digital conversion by setting ADGO bit high (wait till ADIF flag will not indicate the completion of conversion), and 4) copy of results from ADRESH and ADRESL to variables.

Now repeat the same process to collect the SO₂ data on the channel number AN₂.

11. Results and Discussion

Sensors module, EEPROM, RTC, and LCD have been successfully interfaced to the microcontroller. EEPROM is successfully storing the logged data with time and date tag. The sensors data is being displayed on LCD module. A simple GUI has been designed to store a logged data to a text file, so that it can be analyzed further. The developed system is lowest cost and energy efficient system. The power consumption of the developed system is minimum (< 250 mA).

12. Conclusions

We have developed a low cost, 12 bit resolution data

logger and successfully measured temperature, humidity, and concentration of SO₂ and NO₂ gases. The GUI designed gives a lucratively look to the functioning of data logger. Initial results of the data logger are encouraging and we are working on to improve the GUI model as well as the accuracy of data logger.

13. Future Scope

We can improve the data logger by incorporating the wireless communication in it. There fore, by combining the term data acquisition and wireless communication, it becomes wireless data acquisition. This new innovation technology has become the trend for most industries and companies around the world to gather information due to its reliability and outstanding outcome. The advantage of this technology is that it did not use any physical components or wires to transfer the data obtained from sensor at transmitter side to the receiver side. As a result, an effective system is developed where it is not only removes all the conventional hardware and replace with a transceiver modem for data transfer but also a cost effective system as well. Moreover, the data transmission range can be extended into longer range depending on the transceiver modem capability. With this feature, information from the transducer could be transmitted faster and acts as an early alert in case of accident or disaster such as fire, food and earthquake. By modifying the GUI we can display the waveforms of the data on the computer console where as presently we are logging the data to the file. We also can incorporate the USB communication so that we can transfer the data at high data rates.

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