Uniform Difference Scheme on the Singularly Perturbed System

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ABSTRACT
This paper is concerned with the numerical solution for singular perturbation system of two coupled second ordinary differential equations with initial and boundary conditions, respectively. Fitted finite difference scheme on a uniform mesh, whose solution converges pointwise independently of the singular perturbation parameter is constructed and analyzed.

Keywords: Singular Perturbation; Linear System; Difference Scheme; Uniform Convergence

1. Introduction
We consider the following singularly perturbed initial/boundary value problem for the linear system of ordinary differential equations in the interval [0,1]:

\[ L_1 u := \varepsilon u''(x) + a_1(x)u'(x) + b_1(x)u(x) = c_1(x)v(x) + f_1(x), \]  
\[ L_2 u := -\varepsilon v''(x) + a_2(x)v(x) = c_2(x)u(x) + f_2(x), \]
\[ u(0) = A_1, u'(0) = \frac{B_1}{\varepsilon}, \]
\[ v(0) = A_2, v(1) = B_2, \]

where \( \varepsilon > 0 \) is a small parameter, \( \mu \geq 0 \), \( A_1, A_2, B_1, B_2 \) are given constants. The functions \( a_i(x), c_i(x), f_i(x) \) \( (i = 1, 2) \), \( b_i(x) \) are given functions satisfying certain regularity conditions which are specified whenever necessary.

The above type initial/boundary value problems arise in many areas of mechanics and physics [1,2].

Differential equations with a small parameter \( \varepsilon \) multiplying the highest order derivative terms are said to be singularly perturbed and normally boundary layers occur in their solutions. The numerical analysis of singular perturbation cases has always been far from trivial because of the boundary layer behavior of the solution. Such problems undergo rapid changes within very thin layers near the boundary or inside the problem domain. It is well known that standard numerical methods for solving such problems are unstable and fail to give accurate results when the perturbation parameter \( \varepsilon \) is small. Therefore, it is important to develop suitable numerical methods to these problems, whose accuracy does not depend on the parameter value \( \varepsilon \), i.e. methods that are \( \varepsilon \)-uniformly convergent. These include fitted finite difference methods, finite element methods using special elements such as exponential elements, and methods which use a priori refined or special non-uniform grids which condense in the boundary layers in a special manner. The various approaches to the design and analysis of appropriate numerical methods for singularly perturbed differential equations can be found in [3-8] (see also references cited in them).

In this present paper, we analyze the numerical solution of the initial/boundary problems (1)-(4). The numerical method presented here comprises a fitted difference scheme on an uniform mesh. Fitted operator method is widely used to construct and analyse uniform difference methods, especially for a linear differential problems (see, e.g., [4-7]). In the Section 2, we state some important properties of the exact solution. The derivation of the difference scheme and uniform convergence analysis have been given in Section 3. Uniform convergence is proved in the discrete maximum norm. The approach to the construction of the discrete problem and the error analysis for the approximate solution are similar to those in [8,9].

Difference schemes for singularly perturbed systems with another type of initial/boundary conditions was investigated in [9-14]. Throughout the paper, C will denote a generic positive constant independent of \( \varepsilon \) and of the mesh parameter.
2. Analytical Results

Here we give useful asymptotic estimates of the exact solution of (1.1)-(1.4), that are needed in later sections.

**Lemma 2.1**

Under the
\[ \rho = \varepsilon^u (\alpha, \alpha^{-1}) \exp (\|\beta\| \cdot \varepsilon^{-1}) < 1 \]  

the problem (1.1)-(1.4) has a unique solution, which satisfies
\[ \|u\| \leq C, \]
\[ |u'(x)| \leq C \left( 1 + \frac{1}{x} \exp (-\alpha_{x}/\varepsilon) \right), \quad 0 \leq x \leq 1, \]
\[ \|u'(x)\| \leq C \left[ 1 + \frac{1}{x} \exp \left( \sqrt{a_x(0)/\varepsilon} \right) \right] \]

where \( \|g\|_e = \max_{x \in [0,1]} |g(x)| \) for any continuous function \( g(x) \).

**Proof.** Consider the iterative process
\[
\begin{align*}
L_xu^{(n)} &= f_1(x) + c_1(x)u^{(n-1)} , \\
L_xv^{(n)} &= f_2(x) + \varepsilon c_1(x)u^{(n)} , \\
u^{(n)}(0) &= A, \quad v^{(n)}(0) = \frac{B_x}{e} , \\
v^{(n)}(1) &= B_x , 
\end{align*}
\]

where \( v^{(0)}(x) \in C[0,1] \) is an arbitrary function.

First we prove that for the solution of initial-value problem of the type
\[
\varepsilon u''(x) + a(x)u'(x) + b(x)u(x) = F(x),
\]
\[ u(0) = A, \quad u'(0) = \frac{B}{e} \]

the following estimates hold
\[ \|u'(x)\| \leq \exp \left( \|\beta\| \cdot \varepsilon^{-1} \right) \left( \|\beta\| + \varepsilon^{-1} \|F\| \right), \]
\[ |u''(x)| \leq \exp \left( \|\beta\| \cdot \varepsilon^{-1} \right) \|\beta\| \cdot \varepsilon^{-1} \|F\| \]

To prove (2.7), after some manipulations we have
\[ |u(x)| \leq |A| + |B| \cdot \varepsilon^{-1} \|\beta\| \cdot |F| \]
\[ |u'(x)| \leq |A| + |B| \cdot \varepsilon^{-1} \|\beta\| \cdot |F| \]

hence
\[ |u(x)| \leq A' + B' \int_0^x |u(\eta)| d\eta, \]

where
\[ A' = |A| + \left( |B| + \|\beta\| \right) \cdot \varepsilon^{-1} , \]
\[ B' = \varepsilon^{-1} \|\beta\| . \]

From here by virtue of integral inequality it follows that
\[ |u(x)| \leq A'e^{\varepsilon^{-1}} , \]

which leads to (2.7). Now we prove (2.8). Clearly
\[ |u'(x)| \leq \frac{|B|}{\varepsilon} \cdot \exp (-\alpha_{x}/\varepsilon) + \left( \|\beta\| \cdot \|F\| \right) \cdot \varepsilon^{-1} , \]

Then by using (2.7) we get
\[ |u'(x)| \leq \frac{|B|}{\varepsilon} \cdot \exp (-\alpha_{x}/\varepsilon) + \left( \|\beta\| \cdot \|F\| \right) \cdot \varepsilon^{-1} , \]

which arrive at (2.8).

Further, note that, by virtue of maximum principle the problem of the form
\[ L_xv = F(x), \quad F(x) \in C[0,1] \]
\[ v(0) = A, \quad v(1) = B \]

admits the estimate
\[ |v| \leq |A| + |B| + \varepsilon^{-1} \|F\| \cdot \varepsilon^{-1} . \]  

Denoting
\[ \delta^{(n)}(x) = u^{(n)}(x) - u^{(n-1)}(x), \]
\[ \theta^{(n)}(x) = v^{(n)}(x) - v^{(n-1)}(x) \]

from (1.1)-(1.4) and (2.6) we have
\[ L_x\delta^{(n)} = c_1 \delta^{(n-1)}, \]
\[ L_x\theta^{(n)} = \varepsilon c_1 \delta^{(n-1)}, \]
\[ \delta^{(n)}(0) = \theta^{(n)}(0) = 0, \]
\[ \theta^{(n)}(1) = \theta^{(n)}(1) = 0. \]
Next, applying here (2.7), (2.8), (2.9) we arrive at
\[
\|\varphi^{(n)}\|_e \leq \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|\varphi\|_e \|\varphi^{(n-1)}\|_e ,
\]
\[
\|\varphi^{(n)}\|_e \leq \alpha_1 [\alpha_1 \exp(\|\varphi\|_e \alpha_1)+1] \|\varphi\|_e \|\varphi^{(n-1)}\|_e ,
\]
\[
\|\varphi^{(n)}\|_e \leq \frac{\mu}{\alpha_1} \|\varphi\|_e \|\varphi^{(n-1)}\|_e .
\]
Therefore
\[
\|\varphi^{(n)}\|_e \leq \rho_1 \|\varphi^{(n-1)}\|_e ,
\]
\[
\|\varphi^{(n)}\|_e \leq \rho_2 \|\varphi^{(n-1)}\|_e ,
\]
\[
\|\varphi^{(n)}\|_e \leq \rho_3 \|\varphi^{(n-1)}\|_e ,
\]
with
\[
\rho_1 = \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|\varphi\|_e ,
\]
\[
\rho_2 = \alpha_2 \exp(\|\varphi\|_e \alpha_2) \|\varphi\|_e ,
\]
\[
\rho_3 = \alpha_1 \alpha_2 \exp(\|\varphi\|_e \alpha_1) \|\varphi\|_e .
\]
From (2.10) we have
\[
\|\varphi^{(n)}\|_e \leq \rho_1 \rho_2 \|\varphi^{(n-1)}\|_e \leq (\rho_1 \rho_2)^{n-1} \|\varphi\|_e ,
\]
\[
\|\varphi^{(n)}\|_e \leq (\rho_1 \rho_2)^{n} \rho_1 \|\varphi\|_e ,
\]
\[
\|\varphi^{(n)}\|_e \leq \rho_3 (\rho_1 \rho_2)^{n} \|\varphi\|_e .
\]
From (2.12), (2.13), (2.14) follows that the sequences \{u^{(n)}\}, \{\varphi^{(n)}\}, \{v^{(n)}\} uniformly converges on \(x \in [0,1]\) for \(n \to \infty\). Replacing (2.6) by appropriate system of integral equations we conclude that for \(n \to \infty\) the limit functions are the solution of (1.1)-(1.4).

Now the using (2.7) and (2.8) with the function
\[
F(x) = c_1(x)v(x) + f_1(x)
\]
yield the following stability bounds
\[
\|v\|_e \leq \exp(\|\varphi\|_e \alpha_1) \|A\| + \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|B\|,
\]
\[
+ \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|f_1\|_e ,
\]
\[
\|u\|_e \leq \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|A\| + \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|B\|,
\]
\[
+ \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|f_1\|_e ,
\]
\[
+ \frac{1}{\alpha_1} \exp(-\alpha_1 x/h) \|B\|,
\]
\[
+ \alpha_1 \exp(-\alpha_1 x/h) \|B\|,
\]
\[
+ \alpha_1 \exp(-\alpha_1 x/h) \|B\|,
\]
\[
+ \alpha_1 \exp(-\alpha_1 x/h) \|B\|,
\]
\[
+ \frac{1}{\epsilon} \exp(-\alpha_1 x/h) \|B\|,
\]
\[
+ \frac{1}{\epsilon} \exp(-\alpha_1 x/h) \|B\|,
\]
\[
+ \alpha_1 \exp(-\alpha_1 x/h) \|B\|,
\]
\[
+ \alpha_1 \exp(-\alpha_1 x/h) \|B\|,
\]
\[
\|u\|_e \leq \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|A\| + \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|B\|.
\]
Next from (2.9), with \(F(x) = \epsilon c_2(x)u(x) + f_2(x)\)

it follows that
\[
\|v\|_e \leq \|A\| + \|B\| + e^\alpha \alpha_1 \|c_2\|_\infty + \alpha_1 \|f_2\|_e .
\]
From (2.13) and (2.15) obviously
\[
\|v\|_e \leq (1-\rho)^{-1} \{\exp(\|\varphi\|_e \alpha_1)\} \|A\| + \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|B\| + \alpha_1 \exp(\|\varphi\|_e \alpha_1) \|f_2\|_e ,
\]
\[
\|v\|_e \leq (1-\rho)^{-1} \{\|A\| + \|B\| + \alpha_1 \|f_2\|_e \},
\]
\[
\times \{\exp(\|\varphi\|_e \alpha_1)\} (1-\rho)^{-1} \{\|A\| + \|B\| + \alpha_1 \|f_2\|_e \}.
\]

The last three inequalities show the validity of (2.2)-(2.4). Now we prove (2.5). Since
\[
\|L\|_e \leq e^{\alpha_1} \|c_2\|_\infty \|f_2\|_e + e^{\alpha_1} \|c_2\|_\infty \|f_2\|_e \leq C,
\]
which leads to (2.5), which completes the proof.

3. The Difference Scheme and Convergence

Now we construct the difference scheme and investigate it. In what follows, we denote by \(\omega\) the uniform mesh in \([0,1]\):
\[
\omega = \{x_i = ih, i = 1,2,\cdots,N-1, h = 1/N\},
\]
and \(\sigma = \omega \cup \{x = 0,1\}\). Before describing our numerical method, we introduce some notation for the mesh functions. For any mesh function \(g(x)\), we use
\[
g_i = g(x_i),
\]
\[
g_{i+1} = g(x_{i+1})/h,
\]
\[
g_{i+1} = (g_{i+1} - g_i)/h,
\]
\[
g_{i+1} = (g_{i+1} - g_i)/(2h),
\]
\[
g_{i+1} = (g_{i+1} - g_i)/(2h),
\]
\[
g_{i+1} = (g_{i+1} - g_i)/(2h),
\]
\[
\|g\|_e = \|g\|_{\sigma,\infty} = \max_{0 \leq i \leq n} |g_i|.
\]

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On $\widehat{\sigma}$ we propose the following difference scheme for approximating (1.1)-(1.4):

$$L_1^n U_i = \varepsilon c_i^{(1)} U_{i-1} + a_{i+} U_{i+} + b_i U_i = c_i V_i + f_i,$$

$$L_2^n V_i = -\varepsilon c_i^{(2)} V_{i-1} + a_i V_i = \varepsilon c_i U_i + f_i,$$

$$U_0 = A_1,$$

$$U_{i,0} = \left[ 1 + a_{i+} \frac{h}{\varepsilon} \sigma^{(2)}_{i+} \right]^{-1} \left( e^{-\varepsilon B_i} - b_i - \frac{h}{\varepsilon} \sigma^{(2)}_{i+} f_i \right),$$

$$V_0 = A_2, \quad V_{i+} = B_2,$$

and

$$\sigma^{(1)}_i = \frac{a_{i+} h}{\varepsilon} \left( \sigma^{(2)}_{i+} + \sigma^{(1)}_{i+} \right) + \frac{h}{\varepsilon} a_{i+} \coth \left( \frac{a_{i+} h}{2\varepsilon} \right),$$

$$\sigma^{(2)}_i = \frac{\varepsilon}{a_{i+}} \left( \exp \left( \frac{a_{i+} h}{2\varepsilon} \right) - 1 \right)^{-1},$$

$$\sigma^{(2)}_{i+} = \frac{h^2 a_{i+}}{4\varepsilon \sinh^2 \left( \frac{a_{i+} h}{2\varepsilon} \right)}.$$

For solving of (3.1)-(3.4) we give the following iterative procedure:

$$L_1^n U_{i+} = c_{i+} V_{i+},$$

$$L_2^n V_{i+} = \varepsilon c_i U_{i+} + f_i,$$

$$U_{i+} = A_i,$$

$$V_{i+} = A_2, \quad V_{i+} = B_2,$$

where $V_{i+}^{(0)}$ is arbitrary.

**Lemma 3.1**

$$\left\| U^{(n)} - U \right\|_{e_0} \leq \frac{\rho \rho^{n-1}}{1 - \rho} \left\| V^{(n-1)} - V \right\|_{e_0},$$

$$\left\| V^{(n)} - V \right\|_{e_0} \leq \frac{\rho^{n-1}}{1 - \rho} \left\| V^{(n-1)} - V \right\|_{e_0},$$

where $\left\| \cdot \right\|_{e_0}$ implies the discrete maximum norm on $\omega_h$; $\rho$ and $\rho_i$ are defined by (2.1) and (2.11) appropriately.

**Proof.** Denoting $\delta^{(n)}_i = U_{i+} - U_{i+}^{(n-1)}$, $\delta^{(n)}_i = V_{i+} - V_{i+}^{(n-1)}$ we will have

$$L_1^n \delta^{(n)}_i = c_{i+} \delta^{(n-1)}_{i+},$$

$$L_2^n \delta^{(n)}_i = \varepsilon c_i \delta^{(n)}_{i+},$$

$$\delta^{(n)}_0 = \delta^{(n)}_{i+} = 0,$$

$$\delta^{(n)}_0 = \delta^{(n)}_{i+} = 0.$$
The limit case for \( m \to \infty \) leads to (3.5). The inequality (3.6) is being proved analogously.

**Lemma 3.2** The solution of the difference problem (3.1)-(3.4) satisfies

\[
\|f\|_{p,d} \leq (1 - \rho)^{-1} \gamma \left( \varepsilon \sigma, \|U_{x,0}\|_{p,d} + \sum_{i=1}^{N} |f_i| \right) + \|f\|_{p,d} \left( |A_i| + |B_i| + \|f\|_{\alpha_d} \right) (32)
\]

\[
\|f\|_{p,d} \leq (1 - \rho)^{-1} \left( |A_i| + |B_i| + \|f\|_{\alpha_d} \right) (33)
\]

where \( \sigma = \frac{h \alpha}{2 \varepsilon \cosh \left( \frac{h \alpha}{2 \varepsilon} \right) } \), \( p = 1, 2, \ldots, N - 1 \).

**Proof:** Using the estimates for the difference equations

\[ L_i^h U_j = F_i \]

and

\[ L_i^h V_i = G_i \]

with conditions (3.3) and (3.4) appropriately, which is being obtained analogously in differential case, after setting \( F_i = f_i + c_{0i} V_i \) and \( G_i = f_2 + \varepsilon \alpha c_{2i} U_i \) we will get

\[
\|f\|_{p,d} \leq \gamma \left( \varepsilon \sigma, \|U_{x,0}\|_{p,d} + \|V_{x,0}\|_{p,d} + \sum_{i=1}^{N} |f_i| \right) (34)
\]

\[
\|f\|_{p,d} \leq |A_i| + |B_i| + \|f\|_{\alpha_d} + \alpha_d^{-1} \|f\|_{\alpha_d} (35)
\]

The using each of these into another immediately leads to (3.11) and (3.12).

**Lemma 3.3** For the truncation errors,

\[
R_{i1} = f_i - L_i^h u(x_i) + c_{0i} v(x_i),
\]

\[
R_{i2} = f_2 - L_i^h v(x_i) + c_{2i} u(x_i),
\]

\[
r = \left( 1 + a_i(0) \frac{h}{\varepsilon} \sigma^{(2)}_{i2} \right)^{-1}
\]

\[
\cdot \left( |A_i| + |B_i| - \frac{h}{\varepsilon} \sigma^{(2)}_{i2} + \frac{h}{\varepsilon} \sigma^{(2)}_{i2} f(0) \right) - u_{x,0}
\]

the following estimates hold

\[
|R_{i1}| \leq Ch \left( 1 + h^{-1} \int_{x_i}^{x_{i-1}} |u'(x)| \, dx + h^{-1} \int_{x_i}^{x_{i-1}} |v'(x)| \, dx \right),
\]

\[
|R_{i2}| \leq Ch \left( 1 + e^{-\nu} \|u'(x)\|_{x_i[x_{i+1},x_{i-1}]} \right),
\]

(38)

**Proof:** We may write

\[
R_{i1} = f_i - L_i^h u(x_i) + c_{0i} v(x_i)
\]

\[
- h^{-1} \int_{x_i}^{x_{i+1}} [L_i u(x) - c_i(x) v(x) - f_i(x)] \phi_i(x) \, dx
\]

\[
+ h^{-1} \int_{x_i}^{x_{i+1}} [a_i(x) - a_i(x)] u'(x) \phi_i(x) \, dx
\]

\[
+ h^{-1} \int_{x_i}^{x_{i+1}} [b_i(x) u(x) - b_i(x) u(x)] \phi_i(x) \, dx
\]

\[
+ h^{-1} \int_{x_i}^{x_{i+1}} [c_i(x) v(x) - c_i(x) v(x)] \phi_i(x) \, dx,
\]

(39)

\[
R_{i2} = f_2 - L_i^h v(x_i) + e^{-\nu} c_{2i} u(x_i)
\]

\[
- \lambda h^{-1} \int_{x_i}^{x_{i+1}} [L_i v - a_i(x)] u(x) - f_2(x) \phi_i(x) \, dx
\]

\[
= h^{-1} \lambda \int_{x_i}^{x_{i+1}} [a_i(x) - a_i(x)] v(x) \phi_i(x) \, dx
\]

\[
+ \lambda h^{-1} \int_{x_i}^{x_{i+1}} [f_2(x) - f_2(x)] \phi_i(x) \, dx
\]

\[
+ h^{-1} \lambda e^{-\nu} \int_{x_i}^{x_{i+1}} [c_i(x) u(x) - c_i(x) u(x)] \phi_i(x) \, dx,
\]

(40)

\[
r = \left( 1 + a_i(0) \frac{h}{\varepsilon} \sigma^{(2)}_{i2} \right)^{-1}
\]

\[
\cdot \left( \int_{x_i}^{x_{i+1}} [b_i(x) u(x) - b_i(0) u(0)] \phi_i^{(2)}(x) \, dx
\]

\[
+ \int_{x_i}^{x_{i+1}} [a_i(x) - a_i(0)] u'(x) \phi_i^{(2)}(x) \, dx
\]

\[
+ \int_{x_i}^{x_{i+1}} [c_i(x) v(x) \phi_i^{(2)}(x) \, dx
\]

\[
= \int_{x_i}^{x_{i+1}} f_i(x) - f_i(0) \phi_i^{(2)}(x) \, dx,
\]

(41)
and are the so-

properties of

where approximate from Lemma (3.15)-(3.17).

Proof. We note that

\[ \psi_i(x) = \begin{cases} 
\psi_i^{(1)}(x) = \frac{\sinh a_i(x_i)/\varepsilon (x - x_{i-1})}{\sinh a_i(x_i)/\varepsilon}, & x_{i-1} < x < x_i, \\
\psi_i^{(2)}(x) = \frac{\sinh a_i(x_i)/\varepsilon (x_{i+1} - x)}{\sinh a_i(x_i)/\varepsilon}, & x_i < x < x_{i+1}, \\
0, & x \not\in (x_{i-1}, x_{i+1}), 
\end{cases} \]

where

\[ \lambda_i = \left( h^{-1} \frac{\psi_i(x)}{x_{i+1} - x_{i-1}} \right)^{-1} = \frac{h a_i(x_i)/\varepsilon}{2 \tanh a_i(x_i)/\varepsilon}. \]

We note that \( \psi_i^{(1)}, \psi_i^{(2)} \) and \( \psi_i^{(1)}, \psi_i^{(2)} \) are the solutions of following problems respectively:

\[ -\varepsilon \psi^\prime(x) + a_i(x) \psi(x) = 0, x_{i-1} < x < x_i, \]

\[ \psi(x_{i-1}) = 0, \psi(x_i) = 1, \]

\[ -\varepsilon \psi^\prime(x) + a_i(x) \psi(x) = 0, x_i < x < x_{i+1}, \]

\[ \psi(x_i) = 0, \psi(x_{i+1}) = 0. \]

The relations (3.18)-(3.20), by using also the above properties of \( \varphi(x) \) and \( \psi(x) \) leads immediately to (3.15)-(3.17).

**Theorem 3.1** Let \( a_i(x), b_i(x), c_i(x), f_i(x) \in C[0,1], f_2(x) \in C^1[0,1], \mu \geq 1, (k = 1, 2). \) Then the solution of the difference problem (3.1)-(3.4) converges uniformly in \( \varepsilon \) to the solution of (1.1)-(1.4) with rate \( O(h) \).

Proof. Let \( z_{i0} = U_i - u_i, z_{i0} = V_i - v_i. \) Then for the errors of the approximate solution \( z_k(k = 1, 2; i = 0, 1, 2, \ldots, N) \) we have

\[ L^*_k z_{io} = c_i z_{i0} + R_{i0}, i = 1, 2, \ldots, N-1, \]

\[ L^*_2 z_{20} = \varepsilon e^{c_2 z_{10}} + R_{20}, i = 1, 2, \ldots, N-1, \]

\[ z_{10} = 0, z_{10,0} = r_0, \]

\[ z_{20} = z_{20}, \]

where \( R_{i0}, R_{20}, R_0 \) are approximating errors from Lemma

\[ 3.3. \text{Using Lemma 3.2, we obtain:} \]

\[ \|z_{i0}\|_{n,d} \leq C \left( \varepsilon \sigma, \|R_{i0}\| + h \sum_{i=1}^{N} \|R_{20}\| + \|R_{20}\|_{n,d} \right). \]

By virtue that of (3.15)-(3.17) all terms in right-hand side of this inequality have the rate \( O(h) \) and hence the proof follows immediately.

**4. Numerical Example**

Consider the particular problem with

\[ a_1 = x + 2, b_1 = \varepsilon^{-1}/2, c_1 = \sin \pi x, f_1 = x^2, \]

\[ a_2 = \varepsilon^{-1}, c_2 = x/2, f_2 = \sqrt{x^2 + 1}, \mu = 1, \]

\[ A_i = B_i = 1, A_2 = -1, B_2 = 0. \]

The initial guess is chosen as

\[ V_{i0}^{(0)} = x_i - 1 \]

and stopping criterion is

\[ \left| U_{i}^{(a)} - U_{i+1}^{(a)} \right| < 10^{-5}, \]

\[ \left| V_{i}^{(a)} - V_{i+1}^{(a)} \right| < 10^{-5}. \]

We calculate an experimental rates of convergence \( p_k(k = 1, 2) \) using double mesh method as follows [4,5]:

\[ p_{k}^{e,h} = \ln \left( e^{\varepsilon e^{h^{k-2}}}/e^{h^{k-2}} \right)/\ln 2, \]

where

\[ e^{c_k} = \max_i \left| U_{i}^{e,h} - U_{i+1}^{e,h} \right|, \]

\[ e^{c_k} = \max_i \left| V_{i}^{e,h} - V_{i+1}^{e,h} \right|. \]

The convergence is uniform, i.e., rate of convergence independently of perturbation parameter. Some obtained values for

\[ p_k^{e,h} = \max_{\varepsilon} p_k^{e,h} \left( \varepsilon = 0.5, 10^{-2}, 10^{-4}, 10^{-6} \right) \]

are listed in the table

<table>
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<th>( h )</th>
<th>0.1</th>
<th>0.05</th>
<th>0.025</th>
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<td>1.61, 1.58</td>
<td>1.32, 1.26</td>
<td>1.01, 0.99</td>
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</table>

**5. Conclusion**

The singularly perturbed initial-boundary value problem for a linear second order differential system is considered. To solve this problem, an exponentially fitted difference scheme on a uniform mesh is presented. First order convergence in the discrete maximum norm, independently of the perturbation parameter is obtained. Obtained in numerical example experimental rates of convergence in
agreement with theoretical values.

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REFERENCES