A Consistent Relaxation of the Consumption Invariant Rate in the Discounted-Utility Model

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ABSTRACT

The main theoretical contribution of this paper is a mechanical result that relates growth rates across n commodities. We examplify through a 2-commodity economy of health and money where the results of current health economic theory are confirmed using this technology. The applications are, however, broad; both with regards to spacial discount rates by making relevant assumptions about interpersonal/international comparability and to sustainable growth by envisioning scenarios for the future.

Keywords: Matrix Algebra; Discount Rate; Health-Economics

1. Introduction

Time preferences are common, important and often lifesaving. Sustainability of factors of production [1], ethical fairness towards future generations [2,3] and cost-effectiveness analyses of preventive programs [4] are a few of the well-known economic debates revolving around different approaches towards valuing of the future. The standard model of intertemporal choice is the discounted utility model (DU-model), which was first introduced by Samuelson [5]. Since then, the axiomatic derivation of the model has been numerous [6-10]. An important assumption of the DU-model is that the discount rate is positive and invariant across time and across all forms of consumptions [11]. However, it is often empirically remarked that individuals do not coordinate their intertemporal preferences with pricing choices [12-15]. Frederick and Loewenstein [13], among others, found that intertemporal preferences generally did not have the expected mapping properties on intertemporal willingnessto-pay. In the health sector, for example, current arguments in Health Technology Assessments (HTAs) concern the theoretical foundation of differential discounting for costs and health outcomes [16,17]. To that end, we relax the assumption of an invariant rate.

We assume a set of *n*-commodity-specific discount functions and provide a matrix-vector representation of marginal substitutions based on a model consistent ex-

pectation. Since we are concerned with marginals, one need not necessarily specify the "absolute" functions, per se, but rather the relative change of a function compared to another. Our model, being valid in cases of negative discount rates as well, derives from a more general concept. Our conceptualisation gained popularity, mostly among physicists, from Einstein's general theory of relativity in which he considered a set of coordinate system where the metric tensor defined the type of space, flat or curved etcetera. In our case, we note that some function of well-being across time for an *n*-commodity economy can be geometrically represented by a function of the *n*-dimensional commodity space where each coordinate changes with time according to some specific functions. With regards to the coordinate transformations, we shall assume that production processes of n different commodities are equivalent to some value-gaining processes such as Rae's instruments [18], where the value gaining processes are, possibly, dissimilar. Thus a single point can be infinitely characterised by alternative time-dependent coordinate systems. Section 2 provides a theorem of the representation which we prove by induction.

Using arguments such as consistency in intertemporal choices and intercommodity wise, we then have a cyclical representation of marginal valuations. Cyclical mechanisms describing the economy have, for the past few decades, gained the attention of several economists [19,20]. The simplicity of the mathematics of input-output systems has led to extending such systems to



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open ones as well as to intertemporal ones by adding an additional growth term. An important facet in inputoutput systems generally (if not always) includes some arguments of equivalence relation¹. In our case, we firstly equate commodity *i*'s current input quantities to its future quantity specified by some growth function. Although the quantities of commodities vary stochastically, as a first approach, we propose a model-consistent expectation that assumes that commodities evolve along deterministic (expected) functions of time². Section 3 provides a visual derivation based on some uniform measure of the commodities or purely on physical quantities of the commodities. Our representation however allows for differential discounting which is a major ethical debate in health economics. As such one might want to investigate the cost-effectiveness with regards to net-monetary gains as well as increased life expectancy or increased standards of life. Section 4 introduces illustrations with such marginal valuations and Section 5 concludes.

2. A Covariance Representation of **Coordinate Transformations**

Suppose that we have an *n*-dimensional function, say $\omega(\mathbf{q})$ described by two sets of coordinate systems, say $(q_1^0, q_2^0, \dots, q_n^0)$ and $(q_1^T, q_2^T, \dots, q_n^T)$ where the coordinate transformation is given by $q_i^T = f(q_i^0, T)$ with $i = 1, \dots, n$, say. Since a differential, $d\omega$, is uniquely characterised in the q^0 -frame of reference as well as uniquely characterised in the q^{T} -frame of reference, one could consider a differential, $d\mathbf{q}^0 \leftrightarrow dq_1^0, dq_2^0, \cdots, dq_n^0$ which can also be characterised by $dq_1^T, dq_2^T, \dots, dq_n^T$. Assuming that we know the set of partial derivatives in the q^0 -frame of reference, $\partial q_i^0 / \partial q_i^0$, $i, j = 1, \dots, n$, as well as in the q^{T} -frame of reference,

 $\partial q_i^T / \partial q_i^T$, $i, j = 1, \dots, n$, we can form a matrix with those known components such that the eigenvector of that matrix, corresponding to an eigenvalue 1, represents the bijective coordinate transformation components,

 $\frac{\partial q_i^T}{\partial q_i^0} = i = 1, \dots, n$, We then have a matrix-vector repre-

sentation of partial derivatives since we are simply concerned with the derivative of an axis with respect to another (not necessarily orthogonal here).

Theorem 2.1. Suppose that we have an *n*-dimensional space characterized by 2 sets of n-dimensional coordinates, q^0 and q^T , then, defining v_{ij}^t by $\frac{\partial q_j^i}{\partial q_i^t}$, the matrix $\mathbf{X} = (x_{ij})i, j = 1, \cdots, n$ given by,

1)
$$x_{ij} = v_{ij}^{0}$$
 if $i < j$
2) $x_{ij} = v_{ij}^{T}$ if $i > j$
3) $x_{ij} = 1 - \sum_{i=z}^{j-1} v_{ij}^{0} - \sum_{j=j+1}^{n} v_{ij}^{T}$ if $i = 1$

has an eigenvalue of 1 that corresponds to the eigenvec-

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tor³
$$\mathbf{e} = \left(\frac{\partial q_1^T}{\partial q_1^0}, \frac{\partial q_2^T}{\partial q_2^0}, \cdots, \frac{\partial q_n^T}{\partial q_n^0}\right)$$

That is

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$$\begin{pmatrix} 1 - \sum_{j=2}^{n} v_{1j}^{T} & v_{12}^{0} & \cdots & v_{1n}^{0} \\ v_{12}^{T} & 1 - \sum_{i=1}^{1} v_{i2}^{0} - \sum_{j=3}^{n} v_{2j}^{T} & \cdots & v_{2n}^{0} \\ \vdots & \vdots & \ddots & \vdots \\ v_{1n}^{T} & v_{2n}^{T} & \cdots & 1 - \sum_{i=1}^{n-1} v_{in}^{0} \end{pmatrix} \begin{pmatrix} \frac{\partial q_{1}^{T}}{\partial q_{1}^{0}} \\ \frac{\partial q_{2}^{T}}{\partial q_{2}^{0}} \\ \vdots \\ \frac{\partial q_{n}^{n}}{\partial q_{n}^{0}} \end{pmatrix} = \begin{pmatrix} \frac{\partial q_{1}^{T}}{\partial q_{1}^{0}} \\ \frac{\partial q_{2}^{T}}{\partial q_{2}^{0}} \\ \vdots \\ \frac{\partial q_{n}^{T}}{\partial q_{n}^{0}} \end{pmatrix}$$

Proof. Suppose there exists a matrix, **X** that is non-zero and non-diagonal, given by

$$\begin{aligned} 1)x_{ij} &= v_{ij}^{0} \ if \ i < j \\ 2)x_{ij} &= v_{ji}^{T} \ if \ i > j \\ 3)x_{ij} &= 1 - \sum_{i=1}^{j-1} v_{ij}^{0} - \sum_{j=j+1}^{n} v_{ij}^{T} \ if \ i = j \\ \text{such } \mathbf{Xe'} &= \mathbf{e'} \quad \text{where } \mathbf{e} = \left(f\left(q_{1}^{T}\right), f\left(q_{2}^{T}\right), \cdots, f\left(q_{n}^{T}\right)\right) \\ \text{with } f\left(q_{j}^{T}\right) &= \partial q_{j}^{T} / \partial q_{j}^{0} \\ \text{and } v_{ij}^{t} &= \frac{\partial q_{i}^{t}}{\partial q_{i}^{t}}, i, j = 1, \cdots, n, t = 0, T . \\ \text{Then, } f\left(q_{1}^{T}\right) \quad \text{satisfies} \\ \sum_{j=1}^{n} x_{1j} f\left(q_{j}^{T}\right) &= f\left(q_{1}^{T}\right). \ i.e. \\ \sum_{j=1}^{n} x_{1j} f\left(q_{j}^{T}\right) \end{aligned}$$

$$= \left(1 - \sum_{j=2}^{n} v_{1j}^{T}\right) f\left(q_{1}^{T}\right) + v_{12}^{0} f\left(q_{2}^{T}\right) + \dots + v_{1n}^{0} f\left(q_{n}^{T}\right)$$

$$= \frac{\partial q_{1}^{T}}{\partial q_{1}^{0}} - \sum_{j=2}^{n} \frac{\partial q_{j}^{T}}{\partial q_{1}^{0}} \frac{\partial q_{1}^{T}}{\partial q_{1}^{0}} + \left(\frac{\partial q_{2}^{0}}{\partial q_{1}^{0}}\right) f\left(q_{2}^{T}\right) + \dots + \left(\frac{\partial q_{n}^{0}}{\partial q_{1}^{0}}\right) f\left(q_{n}^{T}\right)$$

$$= \frac{\partial q_{1}^{T}}{\partial q_{1}^{0}} = f\left(q_{1}^{T}\right)$$
Assume that $\sum_{j=1}^{n} x_{n-2j} f\left(q_{1}^{T}\right) = f\left(q_{1}^{T}\right)$ is true

sume that $\sum_{j=1} x_{(i-1)j} J(q_j) = J(q_{(i-1)})$ Then $\sum_{j=1}^{n} x_{ij} f(q_j^T)$, given by

¹For example, Sraffa's system equates the value (price times quantity) of a product of each industry to the value of all goods and services absorbed by this same industry

²Throughout this paper, subscripts shall denote commodities and superscripts shall denote time.

³The vector might, as well, be representative of scalars, such as a tensor of rank 0.

$$\begin{split} &\sum_{j=1}^{n} x_{ij} f\left(q_{j}^{T}\right) \\ &= \sum_{j=1}^{i-1} x_{ij} f\left(q_{j}^{T}\right) + x_{ii} f\left(q_{i}^{T}\right) + \sum_{j=i+1}^{n} x_{ij} f\left(q_{j}^{T}\right) \\ &= \sum_{j=1}^{i-1} v_{ji}^{T} f\left(q_{j}^{T}\right) + \left(1 - \sum_{i=1}^{j-1} v_{ij}^{0} - \sum_{j=j+1}^{n} v_{ij}^{T}\right) f\left(q_{i}^{T}\right) \\ &+ \sum_{j=i+1}^{n} v_{ij}^{0} f\left(q_{j}^{T}\right) \\ &= \sum_{j=1}^{i-1} \frac{\partial q_{i}^{T}}{\partial q_{j}^{T}} \frac{\partial q_{j}^{T}}{\partial q_{j}^{0}} + \left(1 - \sum_{i=1}^{j-1} \frac{\partial q_{i}^{0}}{\partial q_{i}^{0}} - \sum_{j=j+1}^{n} \frac{\partial q_{j}^{T}}{\partial q_{i}^{T}}\right) \frac{\partial q_{i}^{T}}{\partial q_{i}^{0}} \\ &+ \sum_{j=i+1}^{n} \frac{\partial q_{j}^{0}}{\partial q_{i}^{0}} \frac{\partial q_{j}^{T}}{\partial q_{j}^{0}} \\ &= \sum_{j=1}^{i-1} \frac{\partial q_{i}^{T}}{\partial q_{j}^{0}} + \left(1 - \sum_{j=1}^{i-1} \frac{\partial q_{i}^{0}}{\partial q_{j}^{0}} - \sum_{j=j+1}^{n} \frac{\partial q_{j}^{T}}{\partial q_{i}^{T}}\right) \frac{\partial q_{i}^{T}}{\partial q_{i}^{0}} + \sum_{j=i+1}^{n} \frac{\partial q_{j}^{T}}{\partial q_{i}^{0}} \\ &= \sum_{j=1}^{i-1} \frac{\partial q_{i}^{T}}{\partial q_{j}^{0}} + \left(\frac{\partial q_{i}^{T}}{\partial q_{i}^{0}} - \sum_{j=1}^{i-1} \frac{\partial q_{i}^{T}}{\partial q_{j}^{0}} - \sum_{j=j+1}^{n} \frac{\partial q_{j}^{T}}{\partial q_{i}^{0}}\right) + \sum_{j=i+1}^{n} \frac{\partial q_{j}^{T}}{\partial q_{i}^{0}} \\ &= \frac{\partial q_{i}^{T}}{\partial q_{i}^{0}} = f\left(q_{i}^{T}\right) \end{split}$$

is also true. By induction, \mathbf{X} , given by the theorem is deduced.

We now note some properties of the matrix-vector system⁴ which makes the usage fairly attractive for economists.

1) All the elements of our matrix are partial differentials valued with time being constant (*i.e.* each components of the matrix are specific to one and only one time point, either t = 0 or t = T).

2) The elements of the vector are partial differentials relating to a single axis (*i.e.* each of the elements of the vector is specific to one and only one commodity *i*, *i* = either 1 or 2 or \cdots or *n*). Furthermore, the growth vector,

say $f(q_i^T) = \frac{\partial q_i^T}{\partial q_i^0}$ is not specified and the chain rule

allows $f(q_1^T)$ to be, say, an exponential growth while $f(q_2^T)$ to be, say, a linear growth, and the general solution of the system of equations is given by:

$$\frac{v_{ij}^{T}}{v_{ij}^{0}} = f\left(q_{j}^{T}\right) / f\left(q_{i}^{T}\right)$$

$$\tag{1}$$

3. A Derivation with Commodities

Suppose that we have an *n*-commodity economy where the measures of each commodity evolve through time *t*, each according to specific growth functions, $f(q_i^t)$, $i = 1, \dots, n$. Without loss of generality, we suppose that

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the commodity bundle is $\kappa^t \in \Omega^n$, the *n*-dimensional Euclidean orthant and the physical quantity of commodity *i* at time *t* is denoted q_i^t . Given that we have a closed economy, the ratio of any arbitrary commodity *i* to another arbitrary commodity *j*, *i*, *j* = 1,...,*n* is fully specified at all times. Alternatively, given a system of ratios of all commodities to other commodities at different times, a unique vector of growths exists for each of the *n* commodities through time. Our quest in this section is to specify a matrix whose entries are the ratios of commodity *i* to commodity *j*, *i*, *j* = 1,...,*n* at specific times, say t = 0 and t = T that would correspond to the growth functions $f(q_i^T), i = 1, \dots, n$.

Suppose that we now, time t = 0, have q_i^0 of commodity i, $i = 1, \dots, n$ which grows up to time T to q_i^T . We define the growth function, $f(q_i^T), i = 1, \dots, n$ to be the ratio of the future quantity of commodity i to its current quantity.

$$f\left(q_{i}^{T}\right) = \frac{q_{i}^{T}}{q_{i}^{0}} \tag{2}$$

Let Δq_{ij}^0 be the quantity of commodity *i* at time t = 0 that will exchanged for (used in the production of) commodity *j*, at time t = T. Splitting commodity *i* into *n* parts at the present time, we have

$$q_i^0 = \sum_{j=1}^n \Delta q_{ij}^0 \tag{3}$$

where Δq_{ij}^0 is the part of commodity *i* now that will make up for the part commodity *j* in the future. At that future time, *T*, the quantity of commodity *j*, q_j^T , $j = 1, \dots, i, \dots, n$, is composed of the total parts from all *n* commodities, which at time t = 0 were allocated to its future production, Δq_{ij}^0 , $i = 1, \dots, n$, each forwarded to time *T* at their respective growth rates,

 $f(q_i^T), i = 1, \dots, n$. The quantity of commodity *j* at time *t* = *T* is then given by

$$q_j^T = \sum_{i=1}^n f\left(q_i^T\right) \Delta q_{ij}^0 \tag{4}$$

Now, from Equations (2) and (3), we have

$$f(q_{i}^{T}) = \frac{f(q_{i}^{T})\sum_{j=1}^{n} \Delta q_{ij}^{0}}{\sum_{j=1}^{n} \Delta q_{ij}^{0}} = \frac{\sum_{j=1}^{n} f(q_{i}^{T}) \Delta q_{ij}^{0}}{\sum_{j=1}^{n} \Delta q_{ij}^{0}}$$
(5)

and from Equations (2) and (4), we have

$$f(q_i^T) = \frac{\sum_{j=1}^n f(q_j^T) \Delta q_{ji}^0}{q_i^0} = \frac{\sum_{j=1}^n f(q_j^T) \Delta q_{ji}^0}{\sum_{j=1}^n \Delta q_{ij}^0}$$
(6)

Equating Equation (5) with (6),

TEL

⁴Note that the theorem is consistent with Cramer's rule.

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$$\sum_{j=1}^{n} f\left(q_{i}^{T}\right) \Delta q_{ij}^{0} = \sum_{j=1}^{n} f\left(q_{j}^{T}\right) \Delta q_{ji}^{0}$$

$$\rightarrow \sum_{j=1}^{n} f\left(q_{i}^{T}\right) \Delta q_{ij}^{0} - \sum_{j=1}^{n} f\left(q_{j}^{T}\right) \Delta q_{ji}^{0} = 0$$

$$\rightarrow \sum_{j=1}^{n} \left(f\left(q_{i}^{T}\right) \Delta q_{ij}^{0} - f\left(q_{j}^{T}\right) \Delta q_{ji}^{0}\right) = 0$$

Let us consider the solution

 $f(q_i^T)\Delta q_{ij}^0 = f(q_j^T)\Delta q_{ji}^0 \forall i, j$. This solution is the equivalence relation that we shall investigate. In the next section, the continuous version of the equivalence relation, $\Delta q_{ij}^T = \Delta q_{ji}^T \forall i, j$, is shown to be a direct conesquence of a major assumption in time preferences, namely the welfare-preserving rate. However, restricting ourselves to physical quantities for the time being, assuming that $f(q_i^T)\Delta q_{ij}^0 = f(q_j^T)\Delta q_{ij}^0 \forall j$, we

have
$$\frac{f(q_1^T)\Delta q_{1i}^0}{\Delta q_{i1}^0} = \frac{f(q_2^T)\Delta q_{2i}^0}{\Delta q_{i2}^0} = \dots = \frac{f(q_n^T)\Delta q_{ni}^0}{\Delta q_{in}^0}$$

implying that we can write $f(q_i^T)$, rather than a ratio of sums, as a sum of ratios⁵, *i.e.* Equation (6) becomes $f(q_i^T) = \sum_{j=1}^n (\Delta q_{ji}^0 / \Delta q_{ij}^0) f(q_j^T)$. Thus, with $\frac{f(q_j^T) \Delta q_{ji}^0}{\Delta q_{ij}^0} = f(q_i^T) \forall j$, we have a system of linear equ-

ations which we can write in terms of a matrix of ratios,

say
$$X = (x_{ij})$$
 where $x_{ij} = \frac{\Delta q_{ji}^0}{\Delta q_{ij}^0} i, j = 1, \dots, n$

and a vector of growths, say

 $\mathbf{e} = (e_1, e_2, \dots, e_n) = (f(q_1^T), f(q_2^T), \dots, f(q_n^T)),$ such that $\mathbf{X}\mathbf{e}' = \mathbf{e}'$. We shall use the transpose notation to denote column vectors. Further, note that all elements of the Matrix X are ratios valued in the present time only, that is time t = 0.

Furthermore, given that we have a closed economy,

with
$$\frac{f(q_i^T)\Delta q_{ji}^0}{\Delta q_{ij}^0} = f(q_i^T) \rightarrow \frac{f(q_i^T)\Delta q_{ij}^0}{\Delta q_{ji}^0} = f(q_j^T),$$

our columns are also specified⁶. That is, given an entry in the upper triangular matrix, say x_{ij} , j > i, an entry in the lower triangular matrix, x_{ij} , is also specified such that $x_{ij}f(q_j^T) = x_{ji}f(q_i^T) \forall i, j$. Since it is more of our interest to consider how a single ratio changes, we wish to maintain the numerator and denominator so that they represent the ratio of the same commodities; but at different such as the transformation of the same commodities.

ferent times. Thus if $x_{ij} = \frac{\Delta q_{ji}^0}{\Delta q_{ij}^0} j > i$, and remembering

that
$$x_{ij} f\left(q_{j}^{T}\right) = x_{ji} f\left(q_{i}^{T}\right) \forall i, j$$
, we let
 Δq_{ji}^{T}

 $x_{ji} = \frac{\Delta q_{ji}}{\Delta q_{ij}^T}$ so that it is only the time at which we consi-

the ratios that is changed⁷. Next, with

 $f(q_j^T) = 1$. $f(q_j^T)$ implying that a unit of commodity *j* grows to $f(q_j^T)$, we add a further constraint on the diagonal entries. Given that we have $\mathbf{Ie} = \mathbf{e}'$, then we firstly require that $\mathbf{X} = (x_{ij})i, j = 1, \dots, n$ has an eigenvalue of one corresponding to the eigenvector, $\mathbf{e} = (f(q_1^T), f(q_2^T), \dots, f(q_n^T))$. We thus require that each of the columns of our matrix sum to 1, which is a consequence of equation 3. We therefore condition on the diagonal entries so that x_{jj} equal to $1 - \sum_{i, i \neq j} x_{ij}$. Thus we have specified all entries of our matrix of ratios such that $\mathbf{Xe} = \mathbf{e}'$. That is

Without loss of generality, we could consider partial dif-

$$\begin{pmatrix} 1 - \sum_{j=2}^{n} \frac{\Delta q_{j1}^{T}}{\Delta q_{1j}^{T}} & \frac{\Delta q_{21}^{0}}{\Delta q_{12}^{0}} & \cdots & \frac{\Delta q_{n1}^{0}}{\Delta q_{1n}^{0}} \\ \frac{\Delta q_{21}^{T}}{\Delta q_{12}^{T}} & 1 - \sum_{i=1}^{1} \frac{\Delta q_{2i}^{0}}{\Delta q_{i2}^{0}} - \sum_{j=3}^{n} \frac{\Delta q_{j2}^{T}}{\Delta q_{2j}^{T}} & \cdots & \frac{\Delta q_{n2}^{0}}{\Delta q_{2n}^{0}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\Delta q_{n1}^{T}}{\Delta q_{1n}^{T}} & \frac{\Delta q_{n2}^{T}}{\Delta q_{2n}^{T}} & \cdots & 1 - \sum_{i=1}^{n-1} \frac{\Delta q_{n0}^{0}}{\Delta q_{in}^{0}} \end{pmatrix} \begin{pmatrix} f\left(q_{1}^{T}\right) \\ f\left(q_{2}^{T}\right) \\ \vdots \\ f\left(q_{n}^{T}\right) \end{pmatrix} = \begin{pmatrix} f\left(q_{1}^{T}\right) \\ f\left(q_{2}^{T}\right) \\ \vdots \\ f\left(q_{n}^{T}\right) \end{pmatrix}$$

⁷To maintain numerator and denominator of x_{ij} and x_{ji} , note that $\frac{\Delta q_{ij}^{T}}{\Delta q_{ij}^{0}}$ can be achieved by forwarding the numerator of the time zero ratio or by

discounting the denominator of the time t ratio, *i.e.* $\frac{\Delta q_{ji}^{T}}{\Delta q_{ij}^{0}} = \frac{\Delta q_{ji}^{0}}{\Delta q_{ij}^{0}} f\left(q_{j}^{T}\right) = \frac{\Delta q_{ji}^{T}}{\Delta q_{ij}^{T}} f\left(q_{i}^{T}\right).$

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⁵This follows from Euclid's proposition 12, The Elements, Book V. That is: "If any number of magnitudes be proportional, as one of the antecedents is to one of the consequents, so will all the antecedents be to all the consequents".

⁶Analogous to Sraffa's note relating to a system in a self-replacing state (page 5 of the production of commodity by means of commodity), our formulation presupposes a system undergoing indefinite growth. As a result such a state is feasible merely by changing the ratios in which the individual equations enter it.

ferentials rather than ratio of quantities⁸. Furthermore, such continuity assumptions often allow the incorporation of some economic definitions fairly well. So, we shall let $f(q_i^t) = \partial q_i^t / \partial q_i^0$, $i = 1, \dots, n, t = 0, T$ and consequently redefine the terms of our matrix,

 $\frac{\Delta q_{j_i}^t}{\Delta q_{i_j}^t}, i, j = 1, \cdots, n, t = 0, T \text{ in the traditional partial dif-}$

ferential sense. Since the entries of X, only involve the Δq_{ii}^{t}

pairwise exchanges,
$$\frac{\Delta q_{ji}}{\Delta q_{ij}^t}$$
, $i, j = 1, \dots, n, t = 0, T$,

i.e. the change in quantity of commodity i at time t that comes from commodity j at time 0 divided by the change in quantity of commodity j at time t that comes from commodity i at time 0, then given that

 $\partial q_j^t / \partial q_j^0 = f(q_j^t), \frac{\Delta q_{ji}^t}{\Delta q_{ij}^t}$ can effectively be stated in a

much simpler fashion; *i.e.* the change in commodity j

with respect to commodity *i* at time t^9 , $\frac{\partial q_j^i}{\partial q_i^i}$.

Next, suppose we wish to find the matrix inputs at a given time t = T that corresponds to the vector **e**. Letting

 $v_{ij}^{T} = \frac{\partial q_{i}^{T}}{\partial q_{i}^{T}}$, the partial derivative of commodity *j* with

respect to commodity i at the specific time T, we have the representation theorem.

4. An Illustration in Welfare

The non-specificity of a functional "absolute" form opens doors for the use of the matrix system in various other sectors and for different other purposes. The mathematics of marginal rate of transformation and of marginal rate of substitution, being simply that of marginals or partial differentials, in this subsection, we wish to consider the term "marginal value" as input in our system. In order to justify the matrix approach for marginal substitutions, it is necessary to make various simplifying assumptions: we recall firstly that we have an economy that is closed and is composed of *n* commodities only; and we further require that our fictitious society satisfies the necessary assumptions required for the existence of an intercommodity and intertemporal indifference curve such as the Von Newman and Morgenstern [21] rationality axioms and the axioms presented by Ok and Masatlioglu [22], for

⁸For example $\frac{q_j^T}{q_i^T}q_i^T/q_i^0 \equiv \frac{\partial q_j^T}{\partial q_i^T}\partial q_i^T/\partial q_i^0$.

intercommodity and intertemporal conditions respectively.

Definition 4.1. Let the social welfare function, at time t, be $W^t \equiv W(q_1^t, q_2^t, \dots, q_n^t)$ where the commodity bundle is $\kappa^t \in \Omega^n$, the *n*-dimensional Euclidean orthant defined before.

Definition 4.2. Let the (negative) marginal substitution for commodity j between its future quantity and its cur-

rent quantity be denoted as
$$f(Q_i^T) = \frac{W_i^t}{W_i^0} = -\frac{\partial q_i^0}{\partial q_i^t}\Big|_{dW=0}$$

where $W_i^t = \partial W / \partial q_i^t$.

Definition 4.3. We further denote the (negative) social marginal rate of substitution between commodity *j* and commodity *i* at time τ , as, $v_i^{\tau} \equiv \frac{\partial W / \partial q_i^{\tau}}{\partial q_i^{\tau}}$

summodify *i* at time
$$\tau$$
, as, $v_{ij} \equiv \frac{1}{\partial W / \partial q_j^{\tau}}$

Remarks. Definition 4.3, having a bijective nature, should remind us of the equivalence relation from the previous section; $f(q_i^T)\Delta q_{ij}^0 = f(q_j^T)\Delta q_{ji}^0 \forall i, j$. However, in order to use the representation for preferences, we shall require an independence condition introduced by Leontief [23]. To do so, we impose the equivalence lemma of Stigum [24]:

Definition 4.4. Let (K^{τ}, K^{τ}) be a partition of the set of variables, K, and let \hat{K}^{τ} be any set of non-negative quantities of the variables in K^{τ} . The group of variables, K^{τ} is separable in W from a variable K_k , if and only if the correspondence, β , defined by

the correspondence, β , defined by $\beta(\hat{\mathbf{K}}^{r}, \mathbf{K}^{T}) = \{K^{r} | W(\mathbf{K}^{r}, \mathbf{K}^{T}) > W(\hat{\mathbf{K}}^{r}, \mathbf{K}^{T})\}$, is independent of q_{k} , the quantity of the variable \mathbf{K}_{k} .

Remarks. This definition is equivalent to the condition that the marginal rates of substitution at time τ ,

$$v_{ij}^{\tau} = \frac{\partial W/\partial q_i^{\tau}}{\partial W/\partial q_j^{\tau}}$$
, is independent of $q_k^{t} \forall t, i, j \neq k$ [25]. If

W(K) is twice differentiable, then the condition is

equivalent to
$$\frac{\partial v_{ij}^{\tau}}{\partial q_k^t} = 0$$
.

Since we again have two sets of partial differentials where each set, in turn, relate to each other through partial differentials¹⁰, we can write, with such definitions,

$$\sum_{j=1}^{n} x_{ij} f(q_{j}^{T}) = \sum_{j=1}^{i-1} x_{ij} f(q_{j}^{T}) + x_{ii} f(q_{i}^{T}) + \sum_{j=i+1}^{n} x_{ij} f(q_{j}^{T})$$

where x_{ij} is defined as in theorem 2.1. and we have a consistent representation of marginal substitutions. Although the above definitions assume the welfare preserving rate, with other welfare models, adjustments for dw can be made ex-ante since our representation builds on the basis differential, dq.

⁹The use of partial differentials in the system provides a broader set of possibilities of definitions. However, restricting ourselves to the purpose of this paper, we treat the usage as being a continuity of proportional change.

¹⁰It is necessary for the chain-rule to hold.

A Representation for Health Economists

Although there have been several debates in literature regarding differential time preferences, we focus on discounting of health outcomes in this subsection and validate our representation with current health-economic literature. While education, for example, is commonly known, with several empirical evidences, to boost both health and income, other economic activities are known, on the one hand, to be favourable to economic growth, while, on the other hand, to impact negatively on the population's health. As Myrdal stated, production is a circular and cumulative sequence of causations [26]. Historians such as [27], for example, also noted that "all forms of economic growth exert intrinsically negative population health effects among the communities that are most directly involved in the transformations which they entail".

Consequently, in order to represent current health economic discounting with our system, we shall restrict ourselves to a 2-commodity economy; namely income and the QALY, a unique measure of health outcome which is the combination of quality of life and life years. To restricting ourselves, again, to welfare preserving rates for money and health, In order to illustrate our matrix approach, we let commodity 1 and 2 be health, h, and money, *m*, respectively and use a one year time period, (t = 0, t = T = 1), for this illustration. Let our social welfare function be summarised over only money streams and health streams, say $W(m^t, h^t)$. Letting the marginal value of future money in terms of current money be de-

noted by $\frac{W_m^1}{W_m^0} = -\frac{\partial m^0}{\partial m^1}\Big|_{dW=0} = \frac{1}{(1+r_m)}$ and let the marginal value of future health in terms of current health be

denoted by $\frac{W_h^1}{W_h^0} = -\frac{\partial h^0}{\partial h^1}\Big|_{dW=0} = \frac{1}{(1+r_h)}$, we denote the

(negative) social marginal rate of substitution between

money and health by
$$\frac{W_m^t}{W_h^t} = -\frac{\partial m^t}{\partial h^t}\Big|_{dW=0} = v^t$$
;

where $W_h^t = \partial W / \partial h^t$ is the marginal social welfare from an infinitesimal increase in health at time t and $W_{m}^{t} = \partial W / \partial m^{t}$ is the marginal social welfare from an infinitesimal increase in money at time t. From above theorem, in the case n = 2, we get the following system:

$$\begin{bmatrix} (1-v^1) & v^0 \\ v^1 & (1-v^0) \end{bmatrix} \begin{bmatrix} 1+r_h \\ 1+r_m \end{bmatrix} = \begin{bmatrix} 1+r_h \\ 1+r_m \end{bmatrix}$$

with solution,

$$\frac{v^0}{v^1} = \frac{1+r_h}{1+r_m}.$$
 (7)

that is, "The marginal value of one good (health or in-

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come) in terms of another is the same whatever the route by which they are compared", as gravelle stated. By considering the NPV of an intervention from two equivalent ways, Gravelle and Smith showed in a very straight forward way that v^0 and v^1 are related in the same linear fashion as above. They considered a single one year period¹¹ example where an intervention changes present and future costs by Δc^0 and Δc^1 respectively and the quantities of present and future health by Δh^0 and Δh^1 respectively. Firstly, they valued health effects in each period in terms of income and then discounted the future value at the rate of interest on income, r_m . Secondly, they converted the change in future health into an equivalent change in current health and then applied the value of current health in terms of current income. Then, by their consistency argument, equating the two NPV's yields Equation (7).

The reason why the matrix method is similar to the NPV method is that they are both solutions to the same problem. The aim was to find a relationship between v^0 and v^1 with the given constraints that $\partial h^1 = \partial h^0 (1 + r_h)$, $\partial m^1 = \partial m^0 (1 + r_m)$, and $v^t = \frac{W_m^t}{W_h^t}$. Thus in order to be indifferent to the gain of $(1 + r_h)$ of future health at time t = 1, consistency requires that we could now, at time zero, hold either 1 unit of health only or $\left(\frac{v^0}{v^1}\right)$ units of income only or, in our case, we hold both income and health in the proportions: $(1 - v^1)$ units of health and v^0 units of wealth. We see that, in the example given by Gravelle and Smith, in order to have Δh^1 of health at

time t = 1, they either hold $v^0 \Delta h^1 \frac{1}{(1 + r_m)}$ of health now

or $v^{l}\Delta h^{l} \frac{1}{(1+r_{h})}$ of income now. Thus, our 2 × 2 matrix

and the NPV approaches provide the same results.

5. Discussion

Our approach resembles, to some degree, that of the original cyclical mechanisms that were proposed by Quesnay Tableau economique [28]. We, however, rather than equating the "physical quantity on the side of the means of production to that on the side of the product, both of which consist of the same product" [20], allow for a non-fixed timing of the production process similar to Rae's instruments, which we equate through Euclid's proposition 12. It might not be unimportant to note that,

¹¹Gravelle and Smith considered a period of time t = 0 and a period of time t = 1 and the definition they used was two-period while we use specific times t = 0 and t = 1 and hence assume a single period. The derivation however follows.

while this paper addresses consistency in preferences, using growths in physical quantities of a single product, investigations on a sustainable production-consumption cycle seem fairly attractive. Alternatively, plugging in rates of time preferences as growth parameters of different commodities might aid in investigating consistency among social discount rates.

As Riccardo's methodology in devising rates of profits of a farmer by singling out corn as a 'basic' commodity, we choose to, rather, single out health measures as basic commodity. Analogous to Riccardo's conclusion with that regards, we propose that "it is the growth in health that regulate the growth in other trades/commodities". As a generic measure for health, the quality-adjusted life year (QALY) is often used. While the QALY is a multiplicative combination of health quality and life duration which is also consistent with health states that are worse than death or have zero duration of life, the assumption of linear utility of duration is often weakened for simplicity and challenges the actual discounting of the generic concept. We therefore suggest that the QALY be treated as its two different constituents, namely quality of life and the life years; which also strengthens the idea of an array-cost-effectiveness analysis. As such, our representation theorem opens the route to formally investigate potentially different discount rates for quality of life and life years which could especially be important for evaluating cost-effectiveness of life saving and life improving medical interventions differently.

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