Maximum Entropy and Maximum Likelihood Estimation for the Three-Parameter Kappa Distribution

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ABSTRACT
The two statistical principles of maximum entropy and maximum likelihood are investigated for the three-parameter kappa distribution. These two methods become equivalent in the discrete case with $0 < \alpha = 1/(2k+1) \leq 1, k = 0, 1, 2, \cdots$, for the maximum entropy method.

Keywords: Maximum Entropy; Maximum Likelihood; Kappa Distribution; Lagrange Multiplier

1. Introduction
Statistical entropy deals with a measure of uncertainty or disorder associated with a probability distribution. The principle of maximum entropy (ME) is a tool for inference under uncertainty [1,2]. This approach produces the most suitable probability distribution given the available information as seeks the probability distribution that maximizes the information entropy subject to the information constraints, typically via the method of Lagrange multipliers. More precisely, the result is a probability distribution that is consistent with the known constraints expressed in terms of averages or expected values of one or more quantities, but is otherwise as unbiased as possible—i.e., one obtains the least-biased estimate possible on the given information, maximally noncommittal with regard to missing information.

A family of positively skewed distributions known as kappa distributions introduced by Mielke [3] and Mielke and Johnson [4], is very popular for analyzing precipitation data (cf. Park et al. [5], Kysely and Picek [6], Dupuis and Winchester [7]). Various methods of estimation for this type of data include the L-moment, Moment, and Maximum Likelihood (ML) techniques. Many research papers have shown that the ML is too sensitive to extreme values, especially for small samples although but it may be satisfactory for large samples, and the final estimate is not always a global maximum because it can depend upon the starting values. The ME can remove this ambiguity, as various authors have shown—e.g., Hradil and Rehacek [8], and Papalexious and Koutsoyiannis [9]. Singh and Deng [10] considered the ME method for the four-parameter kappa distributions, which include the three-parameter kappa distribution (K3D) introduced by Meilke [3]. In this study, we investigate the theoretical background for parameter estimation by the ME method in the K3D case. The limitation of its performance compared to the ML method is also discussed.

2. Three-Parameter Kappa Distribution
Let a random variable be denoted by $X$. The distribution function of the three-parameter kappa distribution (K3D) is

$$f(x) = \frac{\alpha}{\beta} \left[ \frac{\alpha + \left( \frac{x - \mu}{\beta} \right)^{\alpha+1}}{\alpha+1} \right], \quad x, \alpha, \beta > 0 \quad (1)$$

where $\mu, \beta, \alpha$ denote the location, scale and shape parameters respectively (Park et al. [5]), and the corresponding cumulative distribution function of the K3D is

$$F(x) = \left( \frac{x - \mu}{\beta} \right)^{\frac{1}{\alpha}}, \quad x > 0. \quad (2)$$

It is notable that the K3D distribution function, Equation (1), involves adding the location parameter $\mu$ to the two-parameter kappa distribution (K2D), in contrast to Meilke [3] where only a new shape parameter $\alpha$ is introduced.

3. The Entropy Framework
3.1. Entropy Measure and the Principle of Maximum Entropy
The concept of entropy was originally developed by
Ludwig Boltzmann in statistical mechanics. A famous
and well justified measure is the Boltzmann-Gibbs-
Shannon (BGS) entropy
\[ S = -\int_0^\infty f(x) \ln f(x) \, dx \] (3)
for a continuous non-negative random variable \( X \), where
\( f(x) \) is the probability density function of \( X \). The given
information used in the principle of maximum entropy
(ME) is expressed as a set of constraints representing
expectations of functions \( g_j(X) \) — i.e.
\[ E[g_j(X)] = \int_0^\infty g_j(x) f(x) \, dx = c_j, \quad j = 1, 2, \ldots, n \] (4)
ME distributions emerge by maximizing the selected
form of entropy, subject to Equation (4) and the obvious
additional constraint
\[ \int_0^\infty f(x) \, dx = 1. \] (5)
As precisely mentioned, the maximization is usually
accomplished via the method of Lagrange multipliers,
such that the general solution form of the ME distributions
from maximizing the BGS entropy Equation (3)
(Levine and Tribus, [11]) is
\[ f(x) = \exp \left[ -\lambda_0 - \sum_{j=1}^n \lambda_j g_j(x) \right], \] (6)
where \( \lambda_j, j = 1, 2, \ldots, n \), are the Lagrange multipliers
linked to the constraints in Equation (4) and \( \lambda_0 \) is the
multiplier linked to the additional constraint Equation
(5).

3.2. Justification of the Constraints
Samples are drawn from positively skew or heavy-tailed
distributions, located on the right far from the mean. Statistically,
such values are considered to be outliers and consequently
strongly influence the sample moments. The logarithm function is applied to the data set to
determine the influence of extreme values. The maximum
entropy distribution is uniquely defined by the chosen
constraints, which normally contain information from
observations or theoretical considerations. Thus in geophysical applications for example, important prior characteristics of the underlying distribution should be preserved—e.g. a J-shaped, Bell-shape or heavy-tailed distribution. The constraints should also be chosen based on the suitability of the resulting distribution in regard to the empirical evidence. More details on appropriate constraints are discussed in [11]. In this study, we choose a single constraint to express the features of the distribution given the empirical evidence.

3.3. The Estimation of Maximum Entropy
There are four steps in the ME method to estimate the
objective distribution—viz.
1) Specification of appropriate constraints;
2) Construction of the Lagrange multipliers;
3) Derivation of the entropy function of the distribution; and
4) Derivation of the relation between the Lagrange
multiplier and the constraints.

Step 1 Specification of Appropriate Constraints.
Taking the natural logarithm, from (1) we have
\[ \ln f(x) = \ln \frac{\alpha}{\beta} - \left( \alpha + 1 \right) \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha \right] \] (7)
To establish the entropy as expressed in Equation (3), multiply Equation (7) with \(-f(x)\) and integrate over
the entries space \((0, \infty)\) to obtain
\[ S = -\int_0^\infty \ln \frac{\alpha}{\beta} - \left( \alpha + 1 \right) \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha \right] f(x) \, dx \] (8)
which is to be subject to the constraints
\[ \int_0^\infty \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha \right] f(x) \, dx = E \left[ \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha \right] \right] \] (9)
\[ \int_0^\infty f(x) \, dx = 1. \] (10)

Step 2 Construction of the Lagrange Multipliers.
From Equation (6)
\[ f(x) = \exp \left[ -\lambda_0 - \lambda_i \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha \right] \right], \] (11)
where \( \lambda_0, \lambda_i \) are the Lagrange multipliers. Substituting Equation (11) into Equation (10) we have
\[ \int_0^\infty \left[ -\lambda_0 - \lambda_i \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha \right] \right] f(x) \, dx = 1, \] (12)
such that
\[ \exp(\lambda_0) = \int_0^\infty \exp \left[ -\lambda_i \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha \right] \right] \, dx \]
\[ = \int_0^\infty \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha \right]^{-\lambda_i} \, dx = \frac{\beta}{\alpha} \int_0^\infty z^{-\lambda_i} (z - \alpha)^{\alpha-1} \, dz \]
\[ = \frac{\beta}{\alpha} \left( (1 - \alpha)^{-1} - 1 \right) \alpha \int_0^\alpha u^{-\lambda_i} (1-u)^{\alpha-1} \, du \]
\[ = -\left( (1 - \alpha)^{-1} - 1 \right) \beta \alpha^{\alpha-1} \int_0^\alpha u^{-\lambda_i - \alpha} (1-u)^{\alpha-1} \, du \] (13)
On setting \( z = \alpha + \left( \frac{x - \mu}{\beta} \right)^{\alpha} \) such that \( \frac{d}{dz} \beta (z - \alpha)^{(1/\alpha) - 1} \) \( dz \), and \( u = \frac{z}{\alpha} \) such that \( dz = \alpha du \).

Since \( \exp(\lambda_b) > 0 \) from Equation (13) we require \( (1/\alpha) - 1 = 2k, k = 0, 1, 2, \cdots \), implying \( 0 < \alpha = 1/(2k + 1) \leq 1, k = 0, 1, 2, \cdots \).

Consequently,

\[
\exp(\lambda_a) = \beta \alpha^{(1/\alpha) - 1} \int_0^{1-\lambda_b} (1-u)^{(1/\alpha) - 1} du
= \beta \alpha^{(1/\alpha) - 1} \Gamma(1-\lambda_b) \Gamma\left( \frac{1}{\alpha} \right) \Gamma\left(1-\lambda_a + \frac{1}{\alpha} \right) \tag{14}
\]

Then on taking logarithms we have

\[
\lambda_a = \ln \beta + ((1/\alpha) - 1 - \lambda_b) \ln \alpha + \ln \Gamma(1-\lambda_b)
+ \ln \Gamma\left( \frac{1}{\alpha} \right) - \ln \Gamma\left(1-\lambda_a + \frac{1}{\alpha} \right).
\]

**Step 3. Derivation of the Entropy Function of the Distribution.**

Substituting Equation (14) into Equation (11) gives

\[
f(x) = \frac{\Gamma(1-\lambda_a + \frac{1}{\alpha}) \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^{\alpha} \right]^{\lambda_a}}{\Gamma(1-\lambda_b) \Gamma\left( \frac{1}{\alpha} \right) \beta \alpha^{(1/\alpha) - 1}}
\]

and again taking the natural logarithms, we have

\[
\ln f(x) = \ln \Gamma\left(1-\lambda_a + \frac{1}{\alpha} \right) - \ln \Gamma(1-\lambda_b)
- \ln \Gamma\left( \frac{1}{\alpha} \right) - \ln \beta - \left( \frac{1}{\alpha} - 1 - \lambda_b \right) \ln \alpha
- \lambda_b \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^{\alpha} \right],
\]

and hence from the definition of entropy, Equation (3),

\[
S = -\ln \Gamma\left(1-\lambda_a + \frac{1}{\alpha} \right) + \ln \Gamma(1-\lambda_b)
+ \ln \Gamma\left( \frac{1}{\alpha} \right) + \ln \beta + ((1/\alpha) - 1 - \lambda_b) \ln \alpha
+ \lambda_b \ln \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^{\alpha} \right] \tag{15}
\]

**Step 4. Derivation of the Relation between the Lagrange Multipliers and Constraints.**

Let \( \alpha = \frac{1}{\alpha} \) such that \( da = -\frac{1}{\alpha^2} d\alpha \), \( b = 1 - \lambda_b \) such that \( db = -d\lambda_b \), and \( c = 1 - \lambda_b + \frac{1}{\alpha} \) such that \( \frac{dc}{d\lambda_b} = -1 \)

\[
\frac{dc}{d\alpha} = -\frac{1}{\alpha^2}.
\]

Since \( \frac{d}{dt} \ln \Gamma(t) = \psi(t) \) is the digamma function, it follows that

\[
\frac{\partial}{\partial \alpha} \ln \Gamma\left( \frac{1}{\alpha} \right) = -\frac{1}{\alpha^2} \psi\left( \frac{1}{\alpha} \right),
\]

\[
\frac{\partial}{\partial \lambda_b} \ln \Gamma\left(1-\lambda_a + \frac{1}{\alpha} \right) = -\frac{1}{\alpha^2} \psi\left( c \right),
\]

and

\[
\frac{\partial}{\partial \lambda_b} \ln \Gamma(1-\lambda_b) = -\psi\left( b \right).
\]

There are four parameters in Equation (15)—viz. \( \mu, \alpha, \beta \) and \( \lambda_b \). To maximize Equation (15), we need to set the following partial derivative to zero:

\[
\frac{\partial S}{\partial \lambda_b} = -\frac{\partial}{\partial \alpha} \ln \Gamma\left(1-\lambda_a + \frac{1}{\alpha} \right) + \frac{\partial}{\partial \alpha} \ln \Gamma\left( \frac{1}{\alpha} \right)
+ \left( \frac{1}{\alpha} - 1 - \lambda_b \right) \ln \alpha
+ \lambda_b E \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^{\alpha} \right] \ln \left( \frac{x - \mu}{\beta} \right) \right] \tag{16}
\]

\[
= \psi\left( c \right) - \ln \alpha - \frac{1}{\alpha^2} \psi\left( \frac{1}{\alpha} \right) + \frac{1}{\alpha} \ln \left( \frac{1}{\alpha} - 1 - \lambda_b \right) \frac{1}{\alpha}
+ \lambda_a E \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^{\alpha} \right] \ln \left( \frac{x - \mu}{\beta} \right).
\]

\[
\frac{\partial S}{\partial \lambda_a} = -\frac{\partial}{\partial \lambda_b} \ln \Gamma\left(1-\lambda_a + \frac{1}{\alpha} \right) + \frac{\partial}{\partial \lambda_b} \ln \Gamma(1-\lambda_b)
- \ln \alpha + E \left[ 1 + \left( \frac{x - \mu}{\beta} \right)^{\alpha} \right]
= \psi\left( c \right) - \psi\left( b \right) - \ln \alpha + E \left[ \alpha + \left( \frac{x - \mu}{\beta} \right)^{\alpha} \right]
= 0
\]
\[
\frac{1}{\alpha^2} (\psi(c) - \ln \alpha) = \frac{1}{\alpha^2} \psi(b) - \frac{1}{\alpha^2} E \left[ \ln \left(1 + \left( \frac{x - \mu}{\beta} \right)^\alpha \right) \right],
\]
(17)

\[
\frac{\partial S}{\partial \mu} = -\lambda_\alpha E \left[ \frac{\left( \frac{x - \mu}{\beta} \right)^\alpha}{\alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha} \right] = -(\alpha + 1) E \left[ \frac{\left( \frac{x - \mu}{\beta} \right)^{\alpha-1}}{\alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha} \right],
\]
(18)
and

\[
\frac{\partial S}{\partial \beta} = -\frac{\lambda}{\beta} \alpha E \left[ \frac{\left( \frac{x - \mu}{\beta} \right)^\alpha}{\alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha} \right] = \frac{1}{\beta} \left( \alpha + 1 \right) E \left[ \frac{\left( \frac{x - \mu}{\beta} \right)^{\alpha-1}}{\alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha} \right],
\]
(19)

Assuming \( \lambda_i = \frac{\alpha + 1}{\alpha} \), Equations (16) and (17) yield

\[
\frac{\partial S}{\partial \alpha} = \frac{\psi(b)}{\alpha^2} - \frac{1}{\alpha^2} E \left[ \ln \left(1 + \left( \frac{x - \mu}{\beta} \right)^\alpha \right) \right] - \frac{\psi(a)}{\alpha^2} \left( 2 + \frac{\alpha + 1}{\alpha} \right) E \left[ \frac{\left( \frac{x - \mu}{\beta} \right)^{\alpha-1}}{\alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha} \right] \left[ 1 + \left( \frac{x - \mu}{\beta} \right)^\alpha \ln \left( \frac{x - \mu}{\beta} \right) \right] \]

\[= C \left( \frac{1}{\alpha^2} - \frac{2}{\alpha} \right) E \left[ \ln \left(1 + \left( \frac{x - \mu}{\beta} \right)^\alpha \right) \right] + \left( \frac{\alpha + 1}{\alpha} \right) E \left[ \frac{\left( \frac{x - \mu}{\beta} \right)^{\alpha-1}}{\alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha} \right] \left[ 1 + \left( \frac{x - \mu}{\beta} \right)^\alpha \ln \left( \frac{x - \mu}{\beta} \right) \right]
\]

(20)

where \( C = \frac{1}{\alpha^2} (\psi(b) - \psi(a)) - \frac{2}{\alpha} \) is a constant.

The parameter estimation for the K3D (i.e. of \( \mu, \beta, \alpha \)) from the ME for \( \beta > 0 \) and
\( 0 < \alpha = 1/(2k+1) \leq 1 \) \( k = 0, 1, 2, \ldots \), are obtained from Equations (18)-(20), respectively. By the definition of expectation of random variable \( E(Y) = \sum_{x_i} y \cdot P(Y = y) \)
assume that \( P(Y = y) \) equal to 1, thus Equation (18),

\[ E \left[ \frac{\left( \frac{x - \mu}{\beta} \right)^{\alpha-1}}{\alpha + \left( \frac{x - \mu}{\beta} \right)^\alpha} \right] \approx \sum_{i=1}^{n} \left[ \frac{\left( \frac{x_i - \mu}{\beta} \right)^{\alpha-1}}{\alpha + \left( \frac{x_i - \mu}{\beta} \right)^\alpha} \right], \]
(21)

and apply this assumption to Equations (19) and (20).

4. The Maximum Likelihood Estimation

From Equation (1), the log-likelihood function can be written as

\[\ln L(\mu, \alpha, \beta) = n \ln \left( \frac{\alpha + 1}{\alpha} \right) \sum_{i=1}^{n} \ln \left[ \frac{\left( \frac{x_i - \mu}{\beta} \right)^\alpha}{\alpha + \left( \frac{x_i - \mu}{\beta} \right)^\alpha} \right], \]
(22)

where \( x_i \) is the i-th value of the random variable \( X \) and \( n \) is a sample size. Multiply with \(-1\) and differentiating Equation (22) partially with respect to each parameter, we obtain the MLE by equating each of the following partial derivatives to zero:

\[\frac{\partial \ln L}{\partial \mu} = -(\alpha + 1) \sum_{i=1}^{n} \left[ \frac{\left( \frac{x_i - \mu}{\beta} \right)^{\alpha-1}}{\alpha + \left( \frac{x_i - \mu}{\beta} \right)^\alpha} \right], \]
(23)

\[\frac{\partial \ln L}{\partial \beta} = n \left( \frac{\alpha + 1}{\beta} \right) \sum_{i=1}^{n} \left[ \frac{\left( \frac{x_i - \mu}{\beta} \right)^\alpha}{\alpha + \left( \frac{x_i - \mu}{\beta} \right)^\alpha} \right], \]
(24)
By Equation (21), a comparison of the equations of the ME and the MLE immediately reveals that Equation (18) is equivalent to Equation (23), Equation (19) to Equation (24) and Equation (20) to Equation (25), where \( x, \beta > 0 \) and \( 0 < \alpha = 1/(2k+1) \leq 1 \quad k = 0, 1, 2, \cdots \). Consequently, the two methods become equivalent for discrete random variables.

5. Conclusion

A positive skewness distribution, the three-parameter kappa distribution, is considered. Parameter estimation by the maximum likelihood method requires a certain cutoff in the parameter space or a best starting value, for otherwise the solution may appear under-determined instead of a unique answer (there can exist a concave set). The principle of maximum entropy is another tool to address this problem under constraints that show the characteristic of the distribution given the empirical evidence, using the method of Lagrange multipliers. For \( 0 < \alpha = 1/(2k+1) \leq 1 \quad k = 0, 1, 2, \cdots \), and \( x, \beta > 0 \) the principle of maximum entropy method is equivalent to the maximum likelihood method for the discrete case.

REFERENCES


