Estimation under a Finite Mixture of Exponentiated Exponential Components Model and Balanced Square Error Loss

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ABSTRACT

By exponentiating each of the components of a finite mixture of two exponential components model by a positive parameter, several shapes of hazard rate functions are obtained. Maximum likelihood and Bayes methods, based on square error loss function and objective prior, are used to obtain estimators based on balanced square error loss function for the parameters, survival and hazard rate functions of a mixture of two exponentiated exponential components model. Approximate interval estimators of the parameters of the model are obtained.

Keywords: Finite Mixtures; Exponentiated Exponential Distribution; Maximum Likelihood Estimation; Bayes Estimation, Square Error and Balanced Square Error Loss Functions; Objective Prior

1. Introduction

The study of homogeneous populations was the main concern of statisticians along history. However, Newcomb [1] and Pearson [2] were two pioneers who approached heterogeneous populations with 'finite mixture distributions'.

With the advent of computing facilities, the study of heterogeneous populations, which is the case with many real World populations (see Titterington et al. [3]), attracted the interest of several researchers during the last sixty years. Monographs and books by Everitt and Hand [4], Titterington et al. [3], McLachlan and Basford [5], Lindsay [6] and McLachlan and Peel [7], collected and organized the research done in this period, analyzed data and gave examples of possible practical applications in different areas. Reliability and hazard based on finite mixture models were surveyed by AL-Hussaini and Sultan [8].

In this paper, concentration will be on the study of a finite mixture of two exponentiated exponential components. Due to the exponentiation of each component by a positive parameter, the model is so flexible that it shows different shapes of hazard rate function.

Maximum likelihood estimates (MLEs) and Bayes estimates (BEs), using square error loss (SEL) function are obtained and used in finding the estimates of the parameters, survival function (SF) and hazard rate function

(HRF) using the balanced square error loss (BSEL) function.

Approximate interval estimators of the parameters are obtained by first finding the approximate Fisher information matrix.

The cumulative distribution function (CDF), denoted by \( H(x|\theta) \), of a finite mixture of \( k \) components, denoted by \( H_\ell(x|\eta_\ell), \ell = 1,\cdots,k \), is given by

\[
H(x|\theta) = \sum_{\ell=1}^{k} p_\ell H_\ell(x|\eta_\ell),
\]

(1)

where, for \( \ell = 1,\cdots,k \), the mixing proportions \( p_\ell \geq 0 \) and \( \sum_{\ell=1}^{k} p_\ell = 1 \). The vector of parameters

\[
\theta = (p_1,\cdots,p_k,\eta_1,\cdots,\eta_k) \in \Theta, \quad \text{where } \Theta \text{ is a parameter space.}
\]

The case \( k = 2 \), in (1), is of practical importance and so, we shall restrict our study to this case. In such case, the population consists of two sub-populations, mixed with proportions \( p \) and \( q = 1 - p \). We shall write the CDF of a mixture of two components as

\[
H(x|\theta) = p H_1(x|\eta_1) + q H_2(x|\eta_2),
\]

(2)

where, for \( \ell = 1,2 \), \( H_\ell(x|\eta_\ell) \) is the CDF of the \( \ell \)th sub-population, \( \theta = (p,\eta_1,\eta_2) \) and \( q = 1 - p \).

AL-Hussaini and Ahmad [9] obtained the information matrix for a mixture of two Inverse Gaussian components. AL-Hussaini and Abd-El-Hakim ([10-12]) studied
the failure rate of a finite mixture of two components, one of which is Inverse Gaussian and the other is Weibull. They estimated the parameters of such model and studied the efficiency of schemes of sampling. AL-Hussaini [13] predicted future observables from a mixture of two exponential components. AL-Hussaini [14] obtained Bayesian predictive density function when the population density is a mixture of general components. Other references on finite mixtures may be found in AL-Hussaini and Sultan [8].

In this paper, the components are assumed to be exponential whose CDFs are of the form

\[ H_\ell (x|\eta) = (1 - e^{-\eta x})^{\alpha_\ell}, \quad \ell = 1, 2, \]

where \( \eta = (\alpha_\ell, \beta_\ell) \), \( \ell = 1, 2 \). So that the corresponding probability density function (PDF) components take, for \( \ell = 1, 2 \), the form

\[ h_\ell (x|\eta) = \alpha_\ell \beta_\ell e^{-\eta x} (1 - e^{-\eta x})^{\alpha_\ell - 1}. \]

The PDF, SF and HRF, of the mixture (2), denoted by \( h(x|\theta), R_\ell (x|\theta) \) and \( \lambda_\ell (x|\theta) \) are given by

\[
R_\ell (x|\theta) = \frac{p h_\ell (x|\eta) + q H_\ell (x|\eta)}{p R_\ell (x|\eta) + q R_\ell (x|\eta)} = P(X_1, \ldots, X_n), \quad \ell = 1, 2,
\]

where \( B(x|\theta, \lambda_\ell (x|\eta)) + [1 - B(x|\theta)] \lambda_\ell (x|\eta) \),

In (5)-(8), \( H_\ell (x|\eta) \) and \( h_\ell (x|\eta) \) shall be obtained by (3) and (4), respectively, so that \( \theta = (p, \eta_1, \eta_2) = (p, \alpha_1, \beta_1, \alpha_2, \beta_2) \).

2. Hazard Rate Function of the Mixture

It is well-known that the exponential distribution has a constant HRF on the positive half of the real line. A finite mixture of two exponential components has a decreasing hazard rate function (DHRF) on the positive half of the real line. See, for example, AL-Hussaini and Sultan [8]. If each of the exponential components is exponentiated by a positive parameter, more flexible model is obtained in that several shapes of the HRF of the mixture are obtained. Figure 1 shows six different shapes of CDFs and their corresponding HRFs of the vector of parameters. Examples of such shapes are given as follows:

DHR: \( (p = 0.9, \alpha_1 = 0.5, \alpha_2 = 1.5, \beta_1 = 2, \beta_2 = 3) \)

IHR: \( (p = 0.1, \alpha_1 = 1.5, \alpha_2 = 3, \beta_1 = 2, \beta_2 = 2) \)

BTHR: \( (p = 0.1, \alpha_1 = 0.5, \alpha_2 = 3, \beta_1 = 3, \beta_2 = 0.5) \)

UBTHR: \( (p = 0.1, \alpha_1 = 0.5, \alpha_2 = 3, \beta_1 = 2, \beta_2 = 3) \)

DIDHR: \( (p = 0.25, \alpha_1 = 0.5, \alpha_2 = 3, \beta_1 = 0.5, \beta_2 = 1.5) \)

IDIHR: \( (p = 0.1, \alpha_1 = 2, \alpha_2 = 3, \beta_1 = 3, \beta_2 = 0.5) \)

3. Point Estimation Using Balanced Square Error Loss Function

It is well-known that the Bayes estimator \( \hat{\theta}_{SEL} \) of a function \( u(\theta) \) of a vector of parameters \( \theta = (\theta_1, \ldots, \theta_n) \) under SEL is given by

\[ \hat{\theta}_{SEL} = E[u(\theta)|x] = \int \cdots \int u(\theta) \pi(\theta|x) d\theta_1 \cdots d\theta_n, \]

where the integrals are taken over the m-dimensional space and \( \pi(\theta|x) \) is the posterior PDF of \( \theta \) given \( x \).

The SEL function has probably been the most popular loss function used in literature. The symmetric nature of SEL function gives equal weight to over- and under-estimation of the parameters under consideration. However, in life-testing, over-estimation may be more serious than under-estimation or vice-versa. Consequently, research has been directed towards asymmetric loss functions. Varian [15] suggested the use of linear exponential (LINEX) loss functions. Thompson and Basu [16] suggested the use of quadratic exponential (QUADREX) loss function. Ahmad et al. [17] suggested the use of the so called balanced loss function (BLF), which was originated by Zellner [18], to be of the form

\[ L'(\theta, \delta) = \omega p(\delta_0, \delta) + (1 - \omega) r(\theta, \delta), \]

where \( \rho(\theta, \delta) \) is an arbitrary loss function, \( \delta_0 \) is a chosen “target” estimator of \( \delta \) and the weight \( \omega \in [0,1] \).

The BLF (10) specializes to various choices of loss functions such as the absolute error loss, entropy, LINEX and generalizes SEL functions.

If \( \rho(\theta, \delta) = (\delta - \delta_0)^2 \) is substituted in (10), we obtain the balanced square error loss (BSEL) function, given by

\[ L'(\theta, \delta) = \omega (\delta - \delta_0)^2 + (1 - \omega) (\delta - \delta_0)^2. \]

The estimator \( \hat{\theta}_{BSEL} \) of a function \( u(\theta) \), using BSEL may be given by

\[ \hat{\theta}_{BSEL} = \omega \hat{u}_{ML} + (1 - \omega) \hat{u}_{SEL}, \]

where \( \hat{u}_{ML} \) is the MLE of \( u(\theta) \) and \( \hat{u}_{SEL} \) its Bayes
Figure 1. Different shapes of PDFs and their corresponding HRFs. D = decreasing, I = increasing, BT = bathtub, UBT = upside down bathtub, DID = decreasing-increasing-decreasing, IDI = increasing-decreasing-increasing.
The estimator using SEL function. The estimator of a function, using BSEL is actually a mixture of the MLE of the function and the BE, using SEL. Other estimators, such as the least squares estimator may replace the MLE. Also, a LINEX or QUADREX loss function could be used for $\rho(\theta, \delta)$. Having obtained the MLE and BE based on SEL, the estimates based on BSEL function are given, from (11), by

$$
\hat{\theta}_{\text{BSEL}} = \omega \hat{\theta}_{\text{ML}} + (1-\omega) \hat{\theta}_{\text{SEL}},
$$

$$
\hat{\alpha}_{1,\text{BSEL}} = \omega \hat{\alpha}_{1,\text{ML}} + (1-\omega) \hat{\alpha}_{1,\text{SEL}},
$$

$$
\hat{\alpha}_{2,\text{BSEL}} = \omega \hat{\alpha}_{2,\text{ML}} + (1-\omega) \hat{\alpha}_{2,\text{SEL}},
$$

$$
\hat{\beta}_{1,\text{BSEL}} = \omega \hat{\beta}_{1,\text{ML}} + (1-\omega) \hat{\beta}_{1,\text{SEL}},
$$

$$
\hat{\beta}_{2,\text{BSEL}} = \omega \hat{\beta}_{2,\text{ML}} + (1-\omega) \hat{\beta}_{2,\text{SEL}},
$$

$$
\hat{R}_{\text{BSEL}}(x_i) = \omega \hat{R}_{\text{ML}}(x_i) + (1-\omega) \hat{R}_{\text{SEL}}(x_i),
$$

$$
\hat{\lambda}_{\text{BSEL}}(x_i) = \omega \hat{\lambda}_{\text{ML}}(x_i) + (1-\omega) \hat{\lambda}_{\text{SEL}}(x_i),
$$

Suppose that $r$ units have failed during the interval $(0, x_r):$ $r_1$ units from the first sub-population and $r_2$ units from the second such that $r_1 + r_2 = r$ and $n - r$ units, which cannot be identified as to sub-population, are still functioning. Let, for $\ell = 1, 2$ and $\ell = 1, \ldots, r_{\ell}$, $x_{i,\ell}$ denote the failure time of the $i$th unit belonging to the $\ell$th sub-population and that $x_{i,\ell} \leq x_\ell$. The likelihood function (LF) is given by Mendenhall and Hader [19], as

$$
L'(\theta, x) \propto p^r q^{n-r} e^\alpha \beta^\alpha \gamma^\beta \exp \left[ -\beta \sum_{i=1}^{n} x_{i,1} - \beta_1 \sum_{i=1}^{n} x_{i,2} \right] \prod_{i=1}^{n} \left( 1 - e^{-\beta_1 x_i} \right) \prod_{i=1}^{n} \left( 1 - e^{-\beta_2 x_i} \right)^{q} [R_{H}(x_i|\theta)]^{n-r}.
$$

### 3.1. Maximum Likelihood Estimation

The log-LF is given by

$$
\ell^* (\theta, x) = \ln L'(\theta, x) \propto r_1 \ln p + r_2 \ln q + r_1 \ln \alpha_1 + r_1 \ln \beta_1 + r_2 \ln \alpha_2 + r_2 \ln \beta_2 - \beta_1 \sum_{i=1}^{n} x_{i,1} - \beta_2 \sum_{i=1}^{n} x_{i,2} + (\alpha_1 - 1) \sum_{i=1}^{n} (1 - e^{-\beta_1 x_i}) + (\alpha_2 - 1) \sum_{i=1}^{n} (1 - e^{-\beta_2 x_i}) + (n-r) \ln R_{H}(x_i|\theta).
$$

The MLEs $\hat{\theta}_{\text{ML}}, \hat{\alpha}_{1,\text{ML}}, \hat{\alpha}_{2,\text{ML}}, \hat{\beta}_{1,\text{ML}}, \hat{\beta}_{2,\text{ML}},$ of the five parameters are obtained by solving the following system of likelihood equations

$$
0 = \frac{\partial \ell^*}{\partial \theta} = \frac{r_1}{\hat{\alpha}_1} + \sum_{i=1}^{n} \ln(1 - e^{-\beta_1 x_i}) - \frac{(n-r) \beta_1}{R_{H}(x_i|\theta)} (1 - e^{-\beta_1 x_i})^{\alpha_1 - 1},
$$

$$
0 = \frac{\partial \ell^*}{\partial \alpha_1} = \frac{r_1}{\alpha_1} + \sum_{i=1}^{n} (1 - e^{-\beta_1 x_i}) - \frac{(n-r) \beta_1}{R_{H}(x_i|\theta)} \ln(1 - e^{-\beta_1 x_i}),
$$

$$
0 = \frac{\partial \ell^*}{\partial \alpha_2} = \frac{r_2}{\alpha_2} + \sum_{i=1}^{n} (1 - e^{-\beta_2 x_i}) - \frac{(n-r) \beta_2}{R_{H}(x_i|\theta)} \ln(1 - e^{-\beta_2 x_i}),
$$

$$
0 = \frac{\partial \ell^*}{\partial \beta_1} = \frac{r_1}{\beta_1} + \sum_{i=1}^{n} (1 - e^{-\beta_1 x_i}) - \frac{(n-r) \alpha_1}{R_{H}(x_i|\theta)} (1 - e^{-\beta_1 x_i})^{\alpha_1 - 1},
$$

where

$$
R_{H}(x_i|\theta) = 1 - q \left[ p (1 - e^{-\beta_1 x_i}) + q (1 - e^{-\beta_2 x_i}) \right].
$$

The invariance property of MLEs enables us to obtain the MLEs $\hat{R}_{\text{ML}}(x_i)$ and $\hat{\lambda}_{\text{ML}}(x_i)$ by replacing the parameters by their MLEs in $R_{H}(x_i)$ and $\lambda_{H}(x_i)$. Remarks

1) If $n = r$ (complete sample case),
\[
\hat{p}_{ML} = \frac{r_i}{n}, \quad \hat{\alpha}_{1ML} = \frac{-r_i}{\sum_{i=1}^{n} \ln \left(1 - e^{-\hat{\beta}_{11}}\right)}, \\
\hat{\alpha}_{2ML} = \frac{-r_i}{\sum_{i=1}^{n} \ln \left(1 - e^{-\hat{\beta}_{21}}\right)}, \\
\hat{\beta}_{1ML} = \frac{r_i}{\sum_{i=1}^{n} x_{ij} \left[1 - (\hat{\alpha}_{1ML} - 1) \left(\frac{e^{-\hat{\beta}_{11}}}{1 - e^{-\hat{\beta}_{11}}}\right)\right]}, \\
\hat{\beta}_{2ML} = \frac{r_i}{\sum_{i=1}^{n} x_{ij} \left[1 - (\hat{\alpha}_{2ML} - 1) \left(\frac{e^{-\hat{\beta}_{21}}}{1 - e^{-\hat{\beta}_{21}}}\right)\right]},
\]

2) It can be numerically shown that the vector of parameters \( \theta = (p, \alpha_1, \beta_1, \alpha_2, \beta_2) \), satisfying the likelihood equations actually maximizes the LF (14). This is done by applying Theorem (7-9) on p. 152 of Apostol [20].

3) The parameters of the components are assumed to be distinct, so that the mixture is identifiable. For the concept of identifiability of finite mixtures and examples, see Everitt and Hand [4], Al-Hussainiand Ahmad [21] and Ahmad and Al-Hussaini [22].

3.2. Bayes Estimation Using SEL Function

Suppose that an objective (non-informative) prior is used, in which \( p, \alpha_1, \beta_1, \alpha_2, \beta_2 \) are independent and that \( p \)-Uniform on \( (0, 1) \), so that the prior PDF is given by

\[
\pi(\theta) \propto \frac{1}{\alpha_1 \beta_1 \alpha_2 \beta_2^*}. \tag{16}
\]

The following theorem gives expressions for the Bayes estimators using the SEL function.

Theorem

The Bayes estimators of the parameters, SF and HRF, assuming that the prior belief of the experimenter has PDF (16), are given by

\[
\hat{p}_{SE} = \frac{S_1}{S_0}, \hat{\alpha}_{1SEL} = \frac{r_1 S_2}{S_0}, \hat{\alpha}_{2SEL} = \frac{r_2 S_1}{S_0}, \hat{\beta}_{SEL} = \frac{S_1}{S_0}, \\
\hat{\beta}_{2SEL} = \frac{S_2}{S_0}, \hat{\beta}_{SEL} = \frac{S_1}{S_0}, \hat{\beta}_{SEL} = \frac{S_1}{S_0}, \\
\hat{\beta}_{SEL} = \frac{S_0}{S_0}, \hat{\beta}_{SEL} = \frac{S_1}{S_0}, \hat{\beta}_{SEL} = \frac{S_1}{S_0},
\]

where

\[
S_0 = \sum_{\ell = 0}^{n} \sum_{j = 0}^{n} C_{i,j} B\left(\kappa_j, \kappa_{h,j}\right) I_0, \\
S_1 = \sum_{\ell = 0}^{n} \sum_{j = 0}^{n} C_{i,j} B\left(\kappa_j + 1, \kappa_{h,j}\right) I_0, \\
S_2 = \sum_{\ell = 0}^{n} \sum_{j = 0}^{n} C_{i,j} B\left(\kappa_j, \kappa_j + 1\right) I_0, \\
S_3 = \sum_{\ell = 0}^{n} \sum_{j = 0}^{n} C_{i,j} B\left(\kappa_j, \kappa_{h,j}\right) I_0, \\
S_4 = \sum_{\ell = 0}^{n} \sum_{j = 0}^{n} C_{i,j} B\left(\kappa_j + 1, \kappa_{h,j}\right) I_0, \\
S_5 = \sum_{\ell = 0}^{n} \sum_{j = 0}^{n} C_{i,j} B\left(\kappa_j, \kappa_{h,j}\right) I_0, \\
S_6 = \sum_{\ell = 0}^{n} \sum_{j = 0}^{n} C_{i,j} B\left(\kappa_j + 1, \kappa_{h,j}\right) I_0, \\
S_7 = \sum_{\ell = 0}^{n} \sum_{j = 0}^{n} C_{i,j} B\left(\kappa_j, \kappa_{h,j}\right) I_0.
\]

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\[ I_2 = \int_0^\infty \int_0^\infty R_{\theta \beta} \beta_2 \beta_2 \exp \left[ -\frac{T^{* \star}_{\theta \beta} (\beta, \beta) + T^{\star}_{\theta \beta} (\beta, \beta) - T^{\star}_{\theta \beta} (\beta, \beta) \right] \frac{1}{\beta_2} \frac{1}{\beta_2} \exp \left[ \frac{-T^{\star}_{\theta \beta} (\beta, \beta)}{T^{\star}_{\theta \beta} (\beta, \beta)} \right] \frac{1}{\beta_2} \frac{1}{\beta_2} d\beta_2 \frac{d\beta_2}{d\beta_2} , \tag{29} \]

\[ I_3 = \int_0^\infty \int_0^\infty R_{\theta \beta} \beta_2 \beta_2 \exp \left[ -\frac{T^{* \star}_{\theta \beta} (\beta, \beta) + T^{\star}_{\theta \beta} (\beta, \beta) - T^{\star}_{\theta \beta} (\beta, \beta) \right] \frac{1}{\beta_2} \frac{1}{\beta_2} \exp \left[ \frac{-T^{\star}_{\theta \beta} (\beta, \beta)}{T^{\star}_{\theta \beta} (\beta, \beta)} \right] \frac{1}{\beta_2} \frac{1}{\beta_2} d\beta_2 \frac{d\beta_2}{d\beta_2} , \tag{30} \]

\[ T_{h,2}(\beta_1) = \left[ \left( j_1 - j_2 \right) \ln \left( 1 - e^{-\beta_1 x_{12}} \right) + \sum_{i=1}^{n} \left( 1 - e^{-\beta_1 x_{ij}} \right) \right] , \tag{31} \]

\[ T_{h,2}(\beta_2) = \left[ \left( j_1 - j_2 \right) \ln \left( 1 - e^{-\beta_2 x_{12}} \right) + \sum_{i=1}^{n} \left( 1 - e^{-\beta_2 x_{ij}} \right) \right] , \tag{32} \]

\[ T_{h,2}(\beta_1) = T_{h,2}^{\star}(\beta_1) - (j_1 - j_2) \ln \left( 1 - e^{-\beta_1 x_{12}} \right) , \tag{33} \]

\[ T_{h,2}(\beta_2) = T_{h,2}^{\star}(\beta_2) - (j_1 - j_2) \ln \left( 1 - e^{-\beta_2 x_{12}} \right) , \tag{34} \]

\[ V = F^{-1} = \left( \sigma_{\theta \theta} \right) , \tag{35} \]

where \( \sigma_{\theta \theta} = \text{Cov} \left( \hat{\theta}, \hat{\theta} \right) \).

The observed Fisher information matrix enables us to construct confidence intervals for the parameters based on the limiting normal distribution. Following the general asymptotic theory of MLEs, the sampling distribution of \( \left( \hat{\theta} - \theta \right) \sqrt{V^{-1} (\hat{\theta})} \), \( i = 1, \ldots, 5 \), can be approximated by a standard normal distribution, where \( V^{-1} (\hat{\theta}) \) is the \( i \)th diagonal element of the matrix \( V \), given by (34).

An approximate two-sided \( 100(1-\tau)\% \) confidence interval for \( \hat{\theta} \), is given for \( i = 1, \ldots, 5 \), by

\[ \hat{\theta} - z_{1-\tau/2} \sqrt{V^{-1} (\hat{\theta})} < \hat{\theta} < \hat{\theta} + z_{1-\tau/2} \sqrt{V^{-1} (\hat{\theta})} , \tag{35} \]

where \( z_{\tau} \) is the percentile of the standard normal distribution with right—tail probability of \( \tau \).

5. Numerical Example

5.1. Point Estimation of the Parameters, SF and HRF

A sample is generated from the mixture in such a way that \( x_{ij} < x_{ij}, \ell = 1,2,i = 1,\ldots,r \). We generate 100 samples of size \( n = 50 \) each, from a finite mixture of two exponentiated exponential components, whose PDF is given by (5) and (4), as follows:

1) Generate \( u_i \) and \( u_j \) from Uniform (0,1) distribution.

2) For given values of \( p, \alpha_1, \alpha_2, \beta_1, \beta_2 \), generate \( x \) according to the expression:

\[ x = \begin{cases} \frac{1}{\beta_1} \ln \left( 1 - u_1^{\alpha_1} \right), & u_1 \leq p, \\ \frac{1}{\beta_2} \ln \left( 1 - u_2^{\alpha_2} \right), & u_1 > p, \end{cases} \]

An observation \( x_{ij} \) belongs to sub-population 1, if \( u_{ij} \leq p \) and to sub-population 2, if \( u_{ij} > p \), where the sample is generated from the mixture in such a way that \( x_{ij} < x_{ij}, \ell = 1,2,i = 1,\ldots,r \).

3) Repeat until you get a sample of size \( n \).

The observations are ordered and the first \( r = 45 \) (90% of \( n \)) out of the \( n = 50 \) observations are assumed to be known. Now we have \( r_1 \) observations from the first component of the mixture and \( r_2 \) observations from the second component \( (r = r_1 + r_2 = 45) \).

The value of \( \lambda_0 \) is chosen to be equal to 1.

The estimates of \( p, \alpha_1, \alpha_2, \beta_1, \beta_2, R_{ij} (x_0) \) and \( \lambda_{ij} (x_0) \) and absolute biases are computed by using the ML and Bayes methods. The Bayes estimates are obtained under SEL function. An estimator of a function, using BSEL, is actually a mixture (\( \omega = 0.2, 0.4, 0.6, 0.8 \)) of the MLE of the function and the BE, using SEL.

The MLEs are computed using the built-in MATLAB® function “ga” to find the maximum of the log-LF (15) using the genetic algorithm. This is better than solving the system of five likelihood equations in the five unknowns, by using some iteration scheme. Nevertheless,
the system is needed for the computations of the asymptotic variance-covariance matrix.

The (arbitrarily) chosen actual population values are $p = 0.4$, $\alpha_1 = 2$, $\alpha_2 = 3$, $\beta_1 = 2$, and $\beta_2 = 3$. For $x_0 = 1$, the actual values for $R_p(x_0)$ and $\lambda(x_0)$ are given, respectively, by 0.1862 and 2.3096.

The estimates of the parameters, SF and HRF under the BSEL function are given in Table 1, for different weights $\omega$. It may be noticed that when $\omega = 1$, we obtain the MLEs while the case $\omega = 0$, yields the Bayes estimates under SEL(B-SEL) function.

### Table 1. Estimates of the parameters, SF and HRF under BSEL function and absolute biases.

<table>
<thead>
<tr>
<th>Estimate</th>
<th>$\omega = 0$ “B-SEL”</th>
<th>$\omega = 0.2$</th>
<th>$\omega = 0.4$</th>
<th>$\omega = 0.6$</th>
<th>$\omega = 0.8$</th>
<th>$\omega = 1$ “MLE”</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\hat{p}$</td>
<td>0.416229</td>
<td>0.416139</td>
<td>0.416049</td>
<td>0.415959</td>
<td>0.415869</td>
<td>0.415779</td>
</tr>
<tr>
<td>$\hat{\alpha}_1$</td>
<td>2.380074</td>
<td>2.432918</td>
<td>2.485761</td>
<td>2.538598</td>
<td>2.591441</td>
<td>2.644284</td>
</tr>
<tr>
<td>$\hat{\alpha}_2$</td>
<td>0.380074</td>
<td>0.432918</td>
<td>0.485761</td>
<td>0.538598</td>
<td>0.591441</td>
<td>0.644284</td>
</tr>
<tr>
<td>$\hat{\beta}_1$</td>
<td>2.712658</td>
<td>2.840706</td>
<td>2.968753</td>
<td>3.096802</td>
<td>3.224850</td>
<td>3.352898</td>
</tr>
<tr>
<td>$\hat{\beta}_2$</td>
<td>0.287342</td>
<td>0.159294</td>
<td>0.031247</td>
<td>0.096802</td>
<td>0.224850</td>
<td>0.352898</td>
</tr>
<tr>
<td>$\hat{R}_p(x_0)$</td>
<td>2.712658</td>
<td>2.840706</td>
<td>2.968753</td>
<td>3.096802</td>
<td>3.224850</td>
<td>3.352898</td>
</tr>
<tr>
<td>$\hat{\lambda}(x_0)$</td>
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<td>0.236527</td>
<td>0.219444</td>
<td>0.202361</td>
<td>0.185277</td>
<td>0.168194</td>
</tr>
</tbody>
</table>

It then follows that the approximate 95% confidence intervals of the parameters $p$, $\alpha_1$, $\alpha_2$, $\beta_1$ and $\beta_2$, given by (35), are given, respectively, by: $(0.271 < p < 0.561)$, $(0.5287 < \alpha_1 < 4.7599)$, $(1.3832 < \alpha_2 < 5.3226)$, $(0.9294 < \beta_1 < 4.18)$ and $(1.8039 < \beta_2 < 4.56)$.

### 6. Concluding Remarks

In this article, we have considered point and interval estimation. Point estimation, of the parameters of a finite mixture of two exponentiated exponential components, SF and HRF is based on BLEF which is a weighted average of two losses: one of which reflects precision of estimation and the other reflects goodness-of-fit. This asymmetric loss function may be considered as a compromise between Bayesian and non-Bayesian estimates. We have also estimated the parameters of the mixture by obtaining the asymptotic variance-covariance matrix and hence the approximate confidence intervals.

### REFERENCES


Appendix 1

Proof of the Theorem

By expanding the last term in LF (14), using the binomial expansion, it can be seen that

\[
\left[ R_H (x) \right]^{n-r} = \left[ 1 - \left\{ p(1 - e^{-\beta x_1})^q + q(1 - e^{-\beta x_2})^q \right\} \right]^{n-r} = \sum_{j_1=0}^{\infty} \sum_{j_2=0}^{\infty} C_{j_1 j_2} p^{j_1} q^{j_2} \exp \left[ \alpha_1 j_1 \ln(1 - e^{-\beta x_1}) + \alpha_2 (j_1 - j_2) \ln(1 - e^{-\beta x_2}) \right],
\]

where \( C_{j_1 j_2} = (-1)^j \binom{n-r}{j_1 j_2} \).

So that LF (14) can be written in the form

\[
L' (\theta, x) \propto \sum_{j_1=0}^{\infty} \sum_{j_2=0}^{\infty} C_{j_1 j_2} p^{j_1} q^{j_2} \alpha_1^r \alpha_2^s \beta_1^r \beta_2^s \exp \left[ -\alpha_1 T_{j_1} (\beta_1) - \alpha_2 T_{j_2} (\beta_2) - T_0 (\beta_1, \beta_2) \right],
\]

where \( T_{j_1} (\beta_1), T_{j_2} (\beta_2), T_0 (\beta_1, \beta_2) \) are given by (31). Suppose that the prior PDF is as in (16). It then follows that the posterior PDF is given by

\[
\pi (\theta | x, \lambda) \propto L' (\theta, x) \pi (\theta) = A \sum_{j_1=0}^{\infty} \sum_{j_2=0}^{\infty} C_{j_1 j_2} p^{j_1} q^{j_2} \alpha_1^r \alpha_2^s \beta_1^r \beta_2^s \exp \left[ -\alpha_1 T_{j_1} (\beta_1) - \alpha_2 T_{j_2} (\beta_2) - T_0 (\beta_1, \beta_2) \right],
\]

where \( \kappa_{j_1} = r_1 + j_1, \kappa_{j_2} = r_2 + j_2, T_{j_1} (\beta_1) \) and \( T_{j_2} (\beta_2) \) are given by (32). The normalizing constant \( A \) is given by

\[
A^{-1} = \int \pi (\theta | x, \lambda) d \theta = \sum_{j_1=0}^{\infty} \sum_{j_2=0}^{\infty} C_{j_1 j_2} \beta_1^{r_1} \beta_2^{r_2} e^{-T_0 (\beta_1, \beta_2)} d \beta_1 d \beta_2 = \Gamma (r_1) \Gamma (r_2) S_0,
\]

where \( S_0 \) is given by (17), in which \( I_0 \) is given by (22).

Applying (9) when

\[
u (\theta) = p, \alpha_1, \alpha_2, \beta_1, \beta_2, R_H (x), \lambda_H (x),
\]

their Bayes estimates using SEL function are given by

\[
\hat{\beta}_{SEL} (x) = E (\beta | x) = \frac{S_1}{S_0}, \quad S_1 \text{ is given in (17)},
\]

\[
\hat{\alpha}_{SEL} (x) = E (\alpha | x) = \frac{S_2}{S_0}, \quad S_2 \text{ is given in (18)}, \text{ in which } I_2 \text{ is given by (24)}.
\]

\[
R_{ISEL} (x) = E \left[ R_H (x) | x \right] = 1 - \left\{ p \exp \left[ \alpha_1 \ln(1 - e^{-\beta x_1}) \right] + q \exp \left[ \alpha_2 \ln(1 - e^{-\beta x_2}) \right] \right\} \pi (\theta | x) d \theta = 1 - \frac{S_6}{S_0},
\]

where \( S_6 \) is given in (20), in which \( I_6 \) is given by (27) and \( I_6 \) by (28).

\[
\hat{\lambda}_{ISEL} (x) = E \left[ \lambda_H (x) | x \right],
\]

where

\[
\hat{\lambda}_H (x) = \frac{h(x)}{R_H (x)} = \left[ ph_1 (x) + qh_2 (x) \right] \left[ 1 - \left\{ pH_1 (x) + qH_2 (x) \right\} \right]^{-1}.
\]

Since \( p \leq 1 \), then

\[
pH_1 (x) + qH_2 (x) = H_2 (x) + p \left[ H_1 (x) - H_2 (x) \right] \leq H_1 (x) \leq 1,
\]

so that...
\[
\left[1 - \{pH_1(x_0) + qH_2(x_0)\}\right]^{-1} = \sum_{j_1=0}^{\infty} \sum_{j_2=0}^{\infty} C_{j_1} p^{j_1} q^{j_2} [H_1(x_0)]^{j_1} [H_2(x_0)]^{j_2},
\]
where \( C_{j_1} = \left( \frac{f_3}{f_4} \right) \). It then follows that

\[
\lambda_H(x_0) = \sum_{j_1=0}^{\infty} \sum_{j_2=0}^{\infty} C_{j_1} p^{j_1} q^{j_2} [H_1(x_0)]^{j_1} [H_2(x_0)]^{j_2} \left\{ p h_1(x_0) + q h_2(x_0) \right\}
\]

\[
= \sum_{j_1=0}^{\infty} \sum_{j_2=0}^{\infty} C_{j_1} \left\{ p^{j_1+1} q^{j_2} h_1(x_0) [H_1(x_0)]^{j_1} [H_2(x_0)]^{j_2} + p^{j_1} q^{j_2+1} h_2(x_0) [H_1(x_0)]^{j_1} [H_2(x_0)]^{j_2} \right\}
\]

By substituting, for \( \ell = 1, 2, H_{\ell}(x_0) = (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}}, \) and using \( \pi(\theta|x) \) given by (34), it can be shown that

\[
\lambda_H(x_0) \pi(\theta|x) = A \sum_{j_1=0}^{\infty} \sum_{j_2=0}^{\infty} \sum_{j_3=0}^{\infty} C_{j_1j_2j_3} \left[ p^{j_1+1} q^{j_2+1} \alpha_{\ell\ell} \beta_{\ell\ell}^{j_3-1} \beta_{\ell\ell}^{j_3} e^{-\tau_{\ell\ell}^{j_3} (\beta_{\ell\ell})_{01} (\beta_{\ell\ell})_{01} - \tau_{\ell\ell}^{j_3} (\beta_{\ell\ell})_{01}} \right]
\]

where \( T_{\ell\ell}^{j_3} (\beta_{\ell\ell}) - T_{\ell\ell}^{j_3} (\beta_{\ell\ell}) \) are given by (33). By integrating both sides of (35) with respect to the five parameters, we obtain \( \hat{\lambda}_{HSEL}(x_0) = E[\lambda_H(x_0) | x] = \frac{S}{S_0} \), where \( S \) is given by (21), in which \( I_1 \) is given by (29) and \( I_4 \) by (30).

**Appendix 2**

Second Partial Derivatives of the Log-likelihood Function

\[
\frac{\partial^2 \ell^*}{\partial p^2} = -\frac{p - q}{p - q} \left[ \frac{n - r}{R_H(x, \theta)} \right]^2 \left[ (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} - (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell-1}} \right]^2,
\]

\[
\frac{\partial^2 \ell^*}{\partial p \partial \alpha_i} = -\frac{(n - r) (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} \ln(1 - e^{-\beta_{\ell\ell}})}{[R_H(x, \theta)]^2} \left[ 1 - (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell-1}} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial p \partial \alpha_2} = \frac{(n - r) \alpha_i x e^{-\beta_{\ell\ell}} (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}}}{[R_H(x, \theta)]^2} \left[ 1 - (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell-1}} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial p \partial \beta_1} = \frac{(n - r) \alpha_i x e^{-\beta_{\ell\ell}} (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell} - 1}}{[R_H(x, \theta)]^2} \left[ 1 - (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial p \partial \beta_2} = \frac{(n - r) \alpha_i x e^{-\beta_{\ell\ell}} (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell} - 1}}{[R_H(x, \theta)]^2} \left[ 1 - (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial \alpha_i^2} = -\frac{1}{\alpha_i^2} \left[ \frac{p \left[ (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} \ln(1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} \right]^2}{[R_H(x, \theta)]^2} \right] - q \left[ 1 - (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial \alpha_i \partial \alpha_2} = \frac{-pq \left[ (1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} \ln(1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}} \right] \ln(1 - e^{-\beta_{\ell\ell}})^{\alpha_{\ell\ell}}}{[R_H(x, \theta)]^2},
\]
\[
\frac{\partial^2 \ell^*}{\partial \alpha_i \partial \beta_1} = \sum_{i=1}^{n} \left( x_i e^{-\beta_{2u}} - \frac{(n-r) px_i e^{-\beta_{2v}}}{\left[ R \left( x_i, \theta \right) \right]^2} \left[ R \left( x_i, \theta \right) + \alpha_1 \ln \left( 1 - e^{-\beta_{1v}} \right) \right] \right) \left[ \frac{1}{\left( 1 - e^{-\beta_{2u}} \right)} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial \alpha_i \partial \beta_2} = \sum_{i=1}^{n} \left( x_i e^{-\beta_{2u}} - \frac{(n-r) px_i e^{-\beta_{2v}}}{\left[ R \left( x_i, \theta \right) \right]^2} \left[ R \left( x_i, \theta \right) + \alpha_1 \ln \left( 1 - e^{-\beta_{1v}} \right) \right] \right) \left[ \frac{1}{\left( 1 - e^{-\beta_{1u}} \right)} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial \alpha_1 \partial \beta_1} = \sum_{i=1}^{n} \left( x_i e^{-\beta_{1u}} - \frac{(n-r) px_i e^{-\beta_{1v}}}{\left[ R \left( x_i, \theta \right) \right]^2} \left[ R \left( x_i, \theta \right) + \alpha_1 \ln \left( 1 - e^{-\beta_{1v}} \right) \right] \right) \left[ \frac{1}{\left( 1 - e^{-\beta_{1u}} \right)} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial \alpha_1 \partial \beta_2} = \sum_{i=1}^{n} \left( x_i e^{-\beta_{1u}} - \frac{(n-r) px_i e^{-\beta_{1v}}}{\left[ R \left( x_i, \theta \right) \right]^2} \left[ R \left( x_i, \theta \right) + \alpha_1 \ln \left( 1 - e^{-\beta_{1v}} \right) \right] \right) \left[ \frac{1}{\left( 1 - e^{-\beta_{2u}} \right)} \right],
\]

\[
\frac{\partial^2 \ell^*}{\partial \beta_1 \partial \beta_2} = \sum_{i=1}^{n} \left( x_i e^{-\beta_{2u}} - \frac{(n-r) px_i e^{-\beta_{2v}}}{\left[ R \left( x_i, \theta \right) \right]^2} \left[ R \left( x_i, \theta \right) + \alpha_1 \ln \left( 1 - e^{-\beta_{1v}} \right) \right] \right) \left[ \frac{1}{\left( 1 - e^{-\beta_{2u}} \right)} \right].
\]