

Nonsingular Positon Solutions of a Variable-Coefficient Modified KdV Equation

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ABSTRACT

The determinant representation of three-fold Darboux transformation for a variable-coefficient modified KdV equation is displayed based on the technique used to solve Ablowitz-Kaup-Newell-Segur system. Additionally, the nonsingular positon solutions of the variable-coefficient modified KdV equation are firstly discovered analytically and graphically.

Keywords: Variable-Coefficient KdV Equation; Lax Pair; Darboux Transformation; Positon; Soliton-Positon

1. Introduction

The differential nonlinear evolution equations (NLEEs) have been researched extensively in the past decades. Recently, investigators are shifting their focus in the NLEEs with variable coefficients as in [1]. It is found that NLEEs with variable coefficients can provide more powerful and realistic models than the ones with constant coefficients in describing more complex and real phenomenon. It is shown that solitons of NLEEs with variable coefficients can be effectively controlled through changing their variable parameters.

In this paper, we will concentrate on a variable-coefficient modified KdV (vc-mKdV) equation

$$u_t + \alpha(t)u_{xxx} + \beta(t)u^2u_x + \delta(t)u + \gamma(t)u_x = 0, \quad (1)$$

where $\alpha(t)$, $\beta(t)$, $\delta(t)$, $\gamma(t)$ are all time-dependent analytic functions.

In fact, much attention has been paid to research on different forms of vc-mKdV equations. Particularly, as long ago as 1996, K. Porsezian investigated the N-soliton solution of a vc-mKdV equation is derived through the Hirota method in [2]. And the double-Wronskian-typed soliton of the vc-mKdV Equation (1) are constructed recently in [3].

Besides the soliton solution of NLEEs, another kind of solution called positon, is researched in lots of papers as well, such as [4-6]. As we know, positon relates very closely to soliton, i.e. the interdependence among spectral parameters of soliton gives rise to positon, so we can also call positon “degenerate soliton” [7].

This letter is organized as follows. In Section 2, we construct the detailed Darboux Transformation and its determinant representation of Equation (1). Furthermore, the nonsingular positon and soliton-positon solutions of Equation (1) are derived firstly in Section 3, a series of

pictures are also displayed for the better understanding. Section 4 is devoted to the conclusions and discussions.

2. Darboux Transformation of the vc-mKdV Equation

2.1. Lax pair of the vc-mKdV Equation

It's known that the Lax pair plays a vital role in studying the integrable properties of NLEEs such as the Hamiltonian structures, conservation laws, symmetry and Darboux Transformations show in [7-10]. In the following research, we will use the lax pair presented in [3], which is constructed with the help of the Ablowitz-Kaup-Newell-Segur (AKNS) approach under the following constraint

$$\beta(t) = 6/C_0^2 \alpha(t)e^{2\int\delta(t)dt}, \quad (2)$$

where $C_0 \neq 0$ is an arbitrary constant. We will choose $C_0 = 1$ in this paper for simplicity.

Then the linear eigenvalue problems for Equation (1) can be expressed as

$$\Phi_x = M\Phi, \quad \Phi_t = N\Phi. \quad (3)$$

where $\Phi = (f_1, f_2)^T$, T denotes the transpose of the matrix, and M and N are shown as follows:

$$M = \begin{pmatrix} \lambda & e^{\int\delta(t)dt}u \\ e^{\int\delta(t)dt}v & -\lambda \end{pmatrix}, \quad N = \begin{pmatrix} A & B \\ C & -A \end{pmatrix}, \quad (4)$$

$$A = -4\alpha(t)\lambda^3 - \lambda[\gamma(t) - 2e^{2\int\delta(t)dt}\alpha(t)uv] + \alpha e^{2\int\delta(t)dt}(u_xv - v_xu)$$

with
$$B = -e^{\int\delta(t)dt}[4\lambda^2\alpha(t)u + 2\lambda\alpha(t)u_x + \alpha(t)u_{xx} - 2e^{2\int\delta(t)dt}\alpha(t)u^2v + \gamma(t)u]$$

$$C = e^{\int\delta(t)dt}[-4\lambda^2\alpha(t)v + 2\lambda\alpha(t)v_x - \alpha(t)v_{xx} + 2e^{2\int\delta(t)dt}\alpha(t)uv^2 - \gamma(t)v]$$

The spectral parameter λ is independent of x and t . With constraint (2), it is easy to prove that the compatibility condition (also called the zero curvature equation) of Equations (3) and (4).

$$M_t - N_x + [M, N] = 0 \tag{5}$$

gives rise to Equation (1) for $u = -v$ by direct computation. The bracket represents the usual matrix commutator, and the Lax pair (3) can guarantee the complete integrability of Equation (1).

2.2. Three-fold Darboux Transformation for the vc-mKdV Equation

First of all, we need to introduce the eigenfunctions which stasify the Lax pair (3)

$$\Phi_k = \Phi(\lambda_k) = \begin{pmatrix} f_{k1} \\ f_{k2} \end{pmatrix} \tag{6}$$

of all the eigenvalues $\lambda_k, k = 1, 2, \dots, 6$, we let $\lambda_k \neq \lambda_m$ if $k \neq m$ and $\lambda_k \neq \lambda$. Additionally, the eigenfunctions are linearly independent i.e. Φ_k and Φ_m are linearly independent if $k \neq m$. According to the knowledge of DT, with the help of Cramer's rule and iterative computations, the explicit new solutions $u^{[3]}$ and $v^{[3]}$ of the vc-mKdV Equation (1) can be derived as

$$\begin{aligned} u^{[3]} &= u - 2U_6 / \sigma W_6, \\ v^{[3]} &= v + 2V_6 / \sigma W_6. \end{aligned} \tag{7}$$

where

$$U_6 = \begin{vmatrix} f_{11} & f_{12} & \lambda_1 f_{11} & \lambda_1 f_{12} & \lambda_1^2 f_{11} & \lambda_1^3 f_{11} \\ f_{21} & f_{22} & \lambda_2 f_{21} & \lambda_2 f_{22} & \lambda_2^2 f_{21} & \lambda_2^3 f_{21} \\ f_{31} & f_{32} & \lambda_3 f_{31} & \lambda_3 f_{32} & \lambda_3^2 f_{31} & \lambda_3^3 f_{31} \\ f_{41} & f_{42} & \lambda_4 f_{41} & \lambda_4 f_{42} & \lambda_4^2 f_{41} & \lambda_4^3 f_{41} \\ f_{51} & f_{52} & \lambda_5 f_{51} & \lambda_5 f_{52} & \lambda_5^2 f_{51} & \lambda_5^3 f_{51} \\ f_{61} & f_{62} & \lambda_6 f_{61} & \lambda_6 f_{62} & \lambda_6^2 f_{61} & \lambda_6^3 f_{61} \end{vmatrix},$$

$$V_6 = \begin{vmatrix} f_{11} & f_{12} & \lambda_1 f_{11} & \lambda_1 f_{12} & \lambda_1^2 f_{12} & \lambda_1^3 f_{12} \\ f_{21} & f_{22} & \lambda_2 f_{21} & \lambda_2 f_{22} & \lambda_2^2 f_{22} & \lambda_2^3 f_{22} \\ f_{31} & f_{32} & \lambda_3 f_{31} & \lambda_3 f_{32} & \lambda_3^2 f_{32} & \lambda_3^3 f_{32} \\ f_{41} & f_{42} & \lambda_4 f_{41} & \lambda_4 f_{42} & \lambda_4^2 f_{42} & \lambda_4^3 f_{42} \\ f_{51} & f_{52} & \lambda_5 f_{51} & \lambda_5 f_{52} & \lambda_5^2 f_{52} & \lambda_5^3 f_{52} \\ f_{61} & f_{62} & \lambda_6 f_{61} & \lambda_6 f_{62} & \lambda_6^2 f_{62} & \lambda_6^3 f_{62} \end{vmatrix}.$$

Next, it's very easy to turn out that if $f_{k+1,1} = -f_{k,2}$, $f_{k+1,2} = f_{k,1}$, $\lambda_{k+1} = -\lambda_k$ ($k = 1, 3, 5$), then $u^{[3]} = -v^{[3]}$ will be realized, so the three-fold DT of the vc-mKdV equation (1) is accomplished completely. Additionally, we can get the analogous expressions of $u^{[2]}$ and $v^{[2]}$ when $k=1,2,3,4$, so the two-soliton can be arrived as well.

3. Positon and Soliton-positon Solutions of the vc-mKdV Equation

Matveev expounded "positon" in [4] for the KdV equations. As we know, most of the known positon solutions are singular. For various important integrable systems such as the KdV equations and the mKdV equations, there is no nonsingular positon found, though [6] gives the nonsingular positon for the coupled KdV system. In this section, the positon solutions of the vc-mKdV Equation (1) will be displayed for the first time using the result obtained in section 2. It's happy that they are nonsingular.

Choosing the zero seed solution of Equation (1), Equation (3) is solved by

$$\Phi_k = \Phi(\lambda_k) = \begin{pmatrix} f_{k1} \\ f_{k2} \end{pmatrix}, \tag{8a}$$

$$f_{k1} = e^{\int(-4\lambda_k^3\alpha(t) - \lambda_k\gamma(t))dt + \lambda_k x}, \tag{8b}$$

$$f_{k2} = e^{\int(4\lambda_k^3\alpha(t) + \lambda_k\gamma(t))dt - \lambda_k x}. \tag{8c}$$

with $\lambda_k (k = 1, 2, \dots, 6)$ are arbitrary spectral Parameters.

In the construction of two-soliton solutions, if the second spectral parameter λ_3 is colse to the first spectral parameter λ_1 , then the one-positon solution of vc-mKdV Equation (1) can be generated by doing the Taylor expansion of the wave function (8b) to the first order up to λ_1 . That is to say, firstly, taking $\lambda_3 = \lambda_1 + \epsilon$ in the used eigenvalue of the two-fold DT. Secondly, using the Taylor expansion of f_3 and f_4 up to the first order of ϵ in terms of λ_1 . Finally, substituting these manipulations into the two-fold DT, we get the one-positon solution in the form of

$$\begin{aligned} u_{pos} &= e^{-\int\delta(t)dt} [8\lambda_1(-2\lambda_1 h_1 \sinh(P_1) - 2\lambda_1 x \sinh(P_1) \\ &\quad + \cosh(P_1))] / (1 + 8\lambda_1^2 (h_1 + x)^2 + \cosh(2P_1)) \end{aligned} \tag{9}$$

with

$$h_1 = \int(-12\alpha(t)\lambda_1^2 - \gamma(t))dt,$$

$$P_k = 2\int(-4\lambda_k^3\alpha(t) - \lambda_k\gamma(t))dt + 2\lambda_k x, \quad k = 1, 3$$

From Equation (9), we can know that $\delta(t)$ will change the amplitude of the positon solution, just as the plot (a) in **Figure 1** vividly shown. What's more, there is no zero point in the denominator of Equation (9), that means this one-positon solution is nonsingular. Positons of KdV are defined as long-range analogues of solitons and are slowly decreasing, oscillating solutions in [5]. From **Figure 1**, it is clear that two peaks in one-positon separate according to a different way in the two soliton.

Using the same method in the process of the positon above, fixing λ_5 , and calculating the limit $\lambda_3 \rightarrow \lambda_1$, we obtain the soliton-positon solution of vc-mKdV Equation

(1). Letting $\lambda_3 = \lambda_1 + \epsilon$, $\lambda_5 = \lambda_1 + \epsilon$, and using the Taylor expansion of f_3 and f_4 up to the first order, f_5 and f_6 to the second order of ϵ in terms of λ_1 , we get the two-positon solution of vc-mKdV Equation (1). Here the specific expressions of the soliton-positon and two-positon solutions aren't given out for saving space.

Comparing (a) in **Figure 2** with (a) in **Figure 3**, we can clearly see that two parts of the soliton-positon are propagating in a close way, and the third one is independent, while each part of the two-positon will separate finally during their propagating, but the separation velocity is extraordinary slow. Comparing the plots (b) in **Figures 1-3**, it's easy to learn that the presences of solutions are changeable by choosing the variable coefficients $\delta(t)$, $\alpha(t)$, $\gamma(t)$ to be different functions of t . Particularly, from **Figures 2** and **Figure 3**, we know that the soliton-positon and two-soliton solutions are nonsingular as well.

4. Conclusions and Discussions

In this paper, considering the vc-mKdV Equation (1), which is interesting both physically and mathematically, we derived its three-fold Darboux transformation in the form of determinant. Then the positon solutions, which have never been discovered in other papers are obtained.

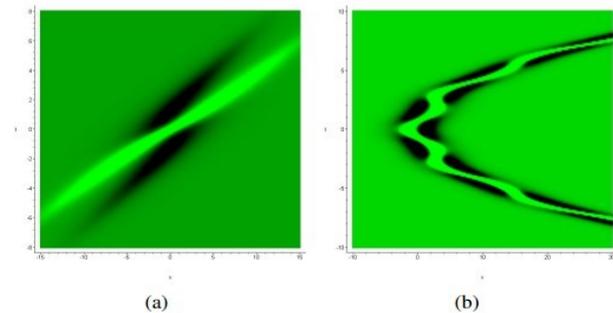


Figure 1. The density plots of one-positon of the vc-mKdV Equation (1) with (a) $\lambda_1 = 0.5, \delta = 0.1t, \alpha = 1, \gamma = 1$; (b) $\lambda_1 = 0.6, \delta = 0, \alpha = \sin(2t), \gamma = t$.

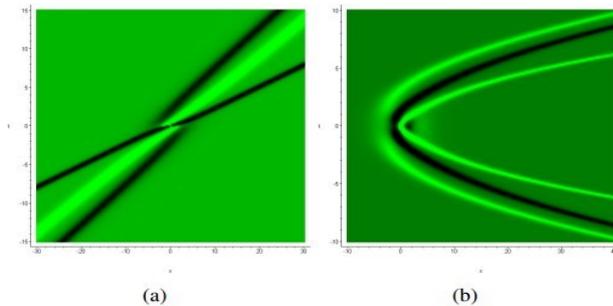


Figure 2. The density plots of soliton-positon of the vc-mKdV Equation (1) with (a) $\lambda_1 = -0.5, \lambda_5 = -1, \delta = 0, \alpha = 1, \gamma = 1$; (b) $\lambda_1 = 0.51, \lambda_5 = 0.71, \delta = 0, \alpha = t, \gamma = 0$.

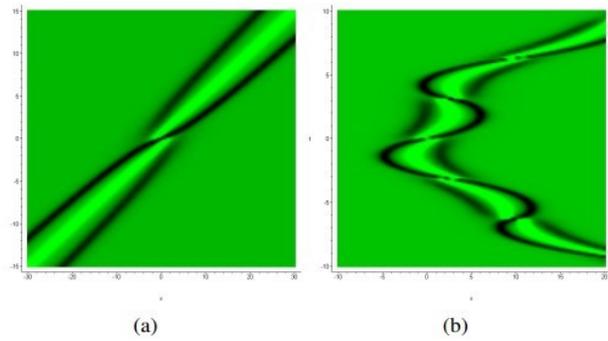


Figure 3. The density plots of two-positon of the vc-mKdV Equation (1) with (a) $\lambda_1 = -0.5, \delta = 0, \alpha = 1, \gamma = 1$; (b) $\lambda_1 = -0.8, \delta = 0, \alpha = \cos(t), \gamma = 0.5t$.

Specifically, the one-positon, soliton-positon and two-positon solutions are all nonsingular. From the **Figures 1-3**, it's interesting to observe that these solutions exhibit the following novelty: when the variable coefficients depend on t , their profiles are changeful and the orbits are quite flexible rather than a straight line. We sincerely hope that these will be of use in the future study.

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