Waveform Design for Cognitive Radar with Deterministic Extended Targets in the Presence of Clutter

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Abstract

Adjusting radar transmitted waveform to its environment is one of the most important roles in cognitive radar; having the capability of updating transmitted waveforms in different applications is a key point. It has been shown in many studies that if the waveform is designed according to the target and clutter characteristics, the detection performance will improve significantly. The uncertainty of the target radar signatures decreases via maximizing MI and the probability of extended target detection is increases via maximizing SNR. In this paper, a waveform design approach based on maximizing both SNR and MI and with regard to target and clutter shape is presented. The detection performance for proposed waveform is compared with previous proposed waveforms. The present paper compares different scenarios of target and clutter and using the probability of detection as a cost function to investigate the advantages and disadvantages of each waveform in different scenarios which are mainly discussed in this text. The desired waveform for cognitive radar is selected based on simultaneously making compromises between SNR and MI, which plays an important role in cognitive radar systems and based on the assumption addressed in the text, the best waveform transmitted into the environment.

Keywords

Signal to Noise Ratio, Mutual Information, Cognitive Radar, Deterministic Extended Target, Clutter

1. Introduction

Cognitive radar is a radar system which selects its transmitted waveform to adapt to the radar environment by

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using feedback structure from the receiver to the transmitter. In these systems waveforms can be adaptively optimized based on preceding knowledge about the targets and environments; it leads to the improvement of the total performance of system [1]. Design of transmitting waveform has an important effect on the performance and efficiency of radar system. Adaptive waveform design for target detection and recognition has been developed during the past decade, and also recently most studies have been devoted to radar waveform optimization. In these approaches, one method is based on signal-to-noise ratio (SNR) maximizing under a particular model of the system, interference, clutter and targets [2]. Another approach is based on mutual information which is first proposed by Bell [3]. Bell shows for estimating the parameters of a target from a given ensemble, the radar waveform should be designed to maximize the mutual information between the received signal and the target ensemble [4]. SNR-based optimum matched waveform for a specific target via frequency domain approach is proposed in [5]. An optimal waveform for T-72 and M1 main battle tanks detection is proposed in [6].

The information-based approach in the presence of signal-dependent clutter is investigated in [7]. In their work, optimum waveform is investigated both from SNR maximization and information-theoretic approaches. The optimal waveform for detecting extended target in signal-dependent interference is proposed in [8]. They derive optimal waveform energy spectral density (ESD) by maximizing SNR. A method for waveform design based on mutual information is proposed in [9] in which the general water-filling method is utilized to solve the waveform design for the recognition of multiple extended targets. They have shown that their proposed method has the higher classification rate at higher SNRs and higher detection performance in lower SNRs as compared to LFM and water-filling signals. In [10], the performance of waveform design in cognitive radar is discussed and a new iterative algorithm is proposed to synthesize a constant modulus waveform to maximize SNR and MI simultaneously. Designing matched waveforms based on maximizing SNR and MI for both deterministic and stochastic targets are discussed in [11] [12]; using multiple transmission of obtaining waveform a target identification problem is investigated. A new technique is proposed in [13], which improves the classification performance of SNR-based matched waveforms. In [7] [14], a closed-loop strategy is applied to discriminate target classes rather than a finite ensemble of known targets. In [15], optimization problem based on mutual information for waveform design in signal dependent clutter is discussed and a new waveform using interior-point method to carry out the optimization task is proposed. In previous papers such as [8] [16], SNR improvement for proposed waveforms over LFM waveform is investigated and in this paper, we evaluate SNR and MI values for different waveforms and compare the results with LFM waveforms and show the best performance of obtaining waveforms.

The contributions of this paper include an analysis of applying both the information-based and SNR-based approach to different deterministic extended targets and clutter scenarios considering the energy constraint. In this study, energy distribution for optimum waveform in clutter and noise scenario with the energy constraint have been addressed and we focus on the point that waveform should put a considerable amount of available energy on the frequency bands in which the target spectrum frequency components is considerable while the clutter is negligible. We derive various waveforms for each scenario and finally compare our results with linear frequency modulated (LFM) waveform to verify the performance of the proposed waveform.

This paper is organized as follows: first a radar system model is described in Section 2 and then the derivation of MI-based and SNR-based waveforms in the presence of Gaussian clutter and other scenarios are derived. In Section 3, using the obtained relations in Section 2, transmit waveform spectrum for two deterministic extended targets are illustrated and the energy allocation realized by obtaining waveforms are briefly discussed. Section 4 generally discusses the performance of obtaining waveforms and other predefined waveforms and a new closed-loop structure for detecting targets in different scenarios is proposed. Finally, in Section 5, we provide a general conclusion.

2. Problem Formulation

2.1. Signal, Clutter and Target Model

To analyze a radar system, all constituent blocks should be defined. We consider a signal model of a Gaussian extended target in the presence of clutter as shown in Figure 1. Now we define the essential target and clutter models to analyze the overall performance of a radar system.

Let $x(t)$ be a finite-energy waveform with duration $T$. We assume $x(t)$ is energy-limited and non-zero only in the time interval $|t| \leq T/2$ which has a bandwidth $w$; The energy content of this signal is:
Figure 1. Known Gaussian extended target model in the presence of clutter [7].

\[ E_x = \int_{-\tau/2}^{\tau/2} |x(t)|^2 \, dt \]  

\( c(t) \) is assumed to be sea clutter with known power spectral density (PSD) which can be approximated as follows:

\[ P_c(f) = g_c \exp \left( -\frac{(f-f_c)^2}{2\sigma_c^2} \right) \]  

Here \( f_c \) is the peak location of the Gaussian function; \( g_c \) and \( \sigma_c^2 \) are parameters which are specified according to problem conditions. \( h(t) \) is the impulse response of target. Once the impulse responses are generated, it is assumed that they are exactly known to the transmitter. In this study, target is assumed to have a Gaussian mixture shape with the following power spectral density:

\[ |H(f)|^2 = a_0 + \sum_{i=1}^{N} a_i \exp \left( -\frac{(f-f_i)^2}{2\sigma_i^2} \right) \]  

where \( a_i \) and \( f_i \) are respectively determined between a specific amplitude range and an appropriate interval due to clutter and noise specifications. The variance \( \sigma_i^2 \) is supposed to have a constant value. Finally \( n(t) \) denotes the noise, which is a complex zero mean WSS Gaussian random process with known PSD \( P_n(f) \). Now let \( r(t) \) be the received signal that is equal to:

\[ r(t) = x(t) * h(t) + x(t) * c(t) + n(t) \]  

2.2. Waveform Derivation

In this part, the Energy Spectral Density (ESD) of MI-based is computed with the assumption of known target in different scenarios and compared with SNR-based waveform discussed in [8]. Like [11], using Lagrangian multiplier, we have derived optimum waveform ESD based on MI criteria in both signal-dependent interference and signal-independent noise. The MI between a Gaussian target ensemble and the received signal without the presence of clutter is equal to:

\[ MI(r(t); h(t)) = \int_{-\tau}^{\tau} \ln \left[ 1 + \frac{|X(f)|^2 \sigma_h^2(f)}{P_n(f)} \right] \, df \]  

where \( \sigma_h^2(f) \) is the continuous target signature. Now let \( e_s(f) \) be the energy spectral density (ESD) of the waveform, so we have:

\[ MI = \int_{-\tau}^{\tau} \ln \left[ 1 + \frac{e_s(f) \sigma_h^2(f)}{P_n(f)} \right] \, df \]
The desired waveform ESD is found by solving the constrained optimization problem:

\[ \hat{e}_x(f) = \max_{e_x(f)} \text{MI} \]  

(7)

With the energy constraint:

\[ \int_w \hat{e}_x(f) df = E_x \]  

(8)

Now using the Lagrangian multiplier method, the waveform ESD will be obtained as follows:

\[
L(e_x(f)) = \int_w \ln \left[ 1 + \frac{e_x(f)}{P_x(f)} \right] df + \lambda \left( E_x - \int_w e_x(f) df \right) 
\]

\[ = \int_w \ln \left[ 1 + \frac{e_x(f)}{P_x(f)} \right] df + \lambda E_x \]  

(9)

We can equivalently maximize:

\[ \bar{L}(e_x(f)) = \int_w \ln \left[ 1 + \frac{e_x(f)}{P_x(f)} \right] df - \lambda e_x(f) \]  

(10)

The first and the second derivatives of \( \bar{L}(e_x(f)) \) with respect to \( e_x(f) \) are given by:

\[
\frac{d\bar{L}(e_x(f))}{de_x(f)} = \frac{\left| H(f) \right|^2}{P_x(f)} - \lambda \left( 1 + e_x(f) \right) \frac{\left| H(f) \right|^2}{P_x(f)} 
\]

(11)

\[
\frac{d^2\bar{L}(e_x(f))}{de_x(f)^2} = \frac{\left| H(f) \right|^2}{P_x(f)} \left( 1 + e_x(f) \right) \left( \frac{\left| H(f) \right|^2}{P_x(f)} \right)^2 
\]

Since the second derivative is negative for all \( e_x(f) \), \( \bar{L}(e_x(f)) \) is a concave function and by putting equating (10) to zero the desired \( e_x(f) \) is obtained as follows:

\[
\hat{e}_x(f) = \max_{0, \lambda P_x(f)} \left[ \frac{\left| H(f) \right|^2}{\lambda P_x(f)} - 1 \right] 
\]

(12)

where the parameter \( \lambda \) is found by solving the following equation:

\[ \int_w \max_{0, \lambda P_x(f)} \left[ \frac{\left| H(f) \right|^2}{\lambda P_x(f)} - 1 \right] df = E_x \]  

(13)

In Equation (12), we see that the waveform ESD will be equal to zero for those frequencies satisfying:

\[ \frac{\left| H(f) \right|^2}{\lambda P_x(f)} - 1 \leq 0 \quad \text{or} \quad \left| H(f) \right|^2 \leq \lambda P_x(f) \quad \forall f \]  

(14)
Thus, we can consider $\lambda P_n(f)$ as a threshold which depends on coefficient $\lambda$ which means the waveform only puts energy into those frequencies where $|H(f)|^2 > \text{Threshold}$. Thus, for a radar system to be cognitive, it should customize the transmit waveform in such a way that it emphasizes frequency bands where the target spectrum is greater than the obtained threshold and deemphasizes frequency bands where the target is negligible as compared with clutter.

The mutual information between the received signal and the target ensemble with the presence of clutter is:

$$MI \left( r(t), h(t) | x(t) \right) = \int_{w} \ln \left[ 1 + \frac{|X(f)|^2 \sigma_n^2(f)}{P_s(f) + P_r(f) |X(f)|^2} \right] df \quad (15)$$

And like previous step for deriving non-clutter case we have:

$$L(\varepsilon_s(f)) = \int_{w} \ln \left[ 1 + \frac{\varepsilon_s(f) \sigma_n^2(f)}{P_s(f) + P_r(f) \varepsilon_s(f)} \right] df + \lambda \left( E_s - \int_{w} \varepsilon_s(f) df \right)$$

$$= \int_{w} \ln \left[ 1 + \frac{\varepsilon_s(f) \sigma_n^2(f)}{P_s(f) + P_r(f) \varepsilon_s(f)} \right] df - \lambda \varepsilon_s(f) \quad (16)$$

We can equivalently maximize:

$$\tilde{L}(\varepsilon_s(f)) = \ln \left[ 1 + \frac{\varepsilon_s(f) \sigma_n^2(f)}{P_s(f) + P_r(f) \varepsilon_s(f)} \right] - \lambda \varepsilon_s(f) \quad (17)$$

Now the first and second derivatives of $\tilde{L}(\varepsilon_s(f))$ with respect to $\varepsilon_s(f)$ are computed and by following a procedure like the previous step for deriving MI-based waveform without the presence of clutter, leading to the waveform described by:

$$\hat{\varepsilon}_s(f) = \max \left[ 0, -A(f) + \sqrt{A^2(f) + B(f) \left( \frac{1}{\lambda} \frac{P_s(f)}{|H(f)|^2} \right)} \right] \quad (18)$$

where

$$A(f) = \frac{P_r(f) \left( 2P_s(f) + |H(f)|^2 \right)}{2P_r(f) \left( P_s(f) + |H(f)|^2 \right)} \quad (19)$$

$$B(f) = \frac{P_s(f) |H(f)|^2}{P_r(f) \left( P_s(f) + |H(f)|^2 \right)}$$

And the parameter $\lambda$ is found by solving the energy constraint equation:

$$\int_{w} \max \left[ 0, -A(f) + \sqrt{A^2(f) + B(f) \left( \frac{1}{\lambda} \frac{P_s(f)}{|H(f)|^2} \right)} \right] df = E_s \quad (20)$$

In Equation (18), we see that the waveform ESD will put energy into those frequencies satisfying:

$$-A(f) + \sqrt{A^2(f) + B(f) \left( \frac{1}{\lambda} \frac{P_s(f)}{|H(f)|^2} \right)} \geq 0$$

$$\rightarrow A^2(f) + B(f) \left( \frac{1}{\lambda} \frac{P_s(f)}{|H(f)|^2} \right) \geq A^2(f)$$

$$\rightarrow B(f) \left( \frac{1}{\lambda} \frac{P_s(f)}{|H(f)|^2} \right) \geq 0 \quad \rightarrow |H(f)|^2 \geq \lambda P_s(f) \quad \forall f$$

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Here again the threshold \( \lambda P_n(f) \) is obtained by solving the energy constraint Equation (20) showing that the parameter \( \lambda \) is totally different for each energy constraint presented in this paper. A noteworthy point is that although the thresholds are absolutely similar, their values are different due to parameter \( \lambda \). Consequently, the waveform energy allocation is different from the non-clutter case. It has been shown in simulation results that this waveform distributes most of its energy into frequency bands which the target PSD is high and the clutter PSD is low.

The waveform ESD for SNR-based waveform for a known target with the presence of clutter is described in [8]. SINR for a deterministic target in the presence of clutter is computed as:

\[
\text{SINR} = \int \frac{|X(f)^*| |H(f)|^2}{P_n(f) + P_c(f)} df
\]  
(22)

And the waveform ESD using the Lagrangian multiplier technique is [8]:

\[
\hat{e}_x(f) = \max \left[ 0, \frac{|H(f)| \sqrt{\frac{P_n(f)}{\lambda} - P_c(f)}}{P_c(f)} \right]
\]  
(23)

where parameter \( \lambda \) is found by solving:

\[
\int \max \left[ 0, \frac{|H(f)| \sqrt{\frac{P_n(f)}{\lambda} - P_c(f)}}{P_c(f)} \right] df = E_x
\]  
(24)

As mentioned in [8], the obtained waveform only puts energy into those frequencies where \( |H(f)|^2 > \lambda P_n(f) \) as we derived for MI-based waveforms and \( \lambda P_n(f) \) is considered as a threshold with different values for all waveforms. The last waveform discussed here is the waveform ESD for SNR-based waveform without the presence of clutter. In this case by putting \( P_c(f) = 0 \), SNR expression in (22) is reduced to:

\[
\text{SINR} = \int \frac{|X(f)|^2 |H(f)|^2}{P_n(f)} df
\]  
(25)

Using the Lagrange multiplier technique, we form the objective function \( \hat{L} \left( e_x(f) \right) \) like previous steps, and we see that the first derivative of this function is independent of \( e_x(f) \) and simply implies that no solution exists using this technique. However, by the technique discussed in [2] and [11], the transmit waveform \( x(t) \) with time duration \( T \) that optimizes (25) is defined by:

\[
\hat{x}(t) = \frac{T}{\pi} \int_{-T/2}^{T/2} \hat{x}(\tau) M(t-\tau) d\tau
\]  
(26)

In summary, the transmit waveform \( x(t) \) that maximizes SNR is the Eigenfunction corresponding to the maximum eigenvalue of the kernel \( M(t) \) which is described by:

\[
M(t) = \int \frac{|X(f)|^2}{P_n(f)} e^{i2\pi \xi f} df
\]  
(27)

And finally the SNR has been just the product of this eigenvalue and the energy in the transmit waveform as follows:

\[
\text{SNR} = \lambda_{\max} E_x
\]  
(28)

Different methods are proposed to derive the optimum waveform for this scenario. One of them is the approach proposed in [16] whereby updating phase modulated waveform in such a way that the SNR at the receiver filter output is maximized and the performance of extended target detection is enhanced significantly. In this
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paper, we proposed a new waveform due to energy constraint and also the distribution of the target on specified bandwidth. Indeed, we are interested in waveforms which can follow the target spectrum and detect all peaks of the target in frequency domain. Regarding this assumption we defined the ESD of this waveform in such a way that is independent of noise and clutter power spectrum and only depends on the target spectrum. We name this waveform “Target Spectrum Follower (TSF)” [17]. Therefore, ESD of the proposed waveform is as follows:

\[
\varepsilon_{\text{TSF}}(f) = \lambda |H(f)|^2, \quad |f| \leq W/2
\]  

(29)

where the parameter \( \lambda \) is found by solving:

\[
\int_0^W \varepsilon_{\text{TSF}}(f) df = E_x
\]  

(30)

The ESD obtained using this method produces a waveform that totally follows the target spectrum. The energy of transmitted waveform is allocated to the target peaks in proportion to the amount of every peak; in other words, the proposed waveform allocates its energy in all of target spectrum frequency bands. This allocation is illustrated in Figure 3(d) and Figure 4(d). Unlike other waveforms, this waveform can detect lower target peaks which has some advantages and disadvantages that will be discussed later. Our main purpose to design such a waveform is to show the important role of energy allocation in radar transmitted waveform and the effect of this consideration on target detection scenarios.

The waveforms discussed in this paper are: SNR-based waveform in clutter (CSNR-based) [8], MI-based waveform without clutter (MI-based), MI-based waveform in clutter (CMI-based), target spectrum follower (TSF) and linear frequency modulation waveform (LFM).

3. Numerical Examples

3.1. Numerical Waveform Examples with Specified Gaussian Clutter

We cannot find a closed-form solution for the waveform derivations. In this section, we provide two numerical examples which can be obtained using the proposed waveforms. As it was mentioned in the previous section, target and clutter are supposed to have a Gaussian shape with the power spectrum \( |H(f)|^2 \) and \( P_c(f) \), respectively. Two targets for numerical examples are considered here. In example one, suppose that we have a Gaussian target and clutter shown in Figure 2. The ESD for CSNR-based, CMI-based, MI-based and TSF waveforms for target 1 are evaluated and shown in Figure 2. In the case of waveform design in signal-dependent interference, CSNR-based waveform tends to concentrate most of its energy on one dominant narrow frequency band in which the target PSD is comparable to clutter PSD putting the rest of its energy into frequency bands with great amount of target PSD. CMI-based waveform follows such a procedure with different amounts of energy allocation to each frequency band. Therefore, both waveforms place most of their energy where clutter power is low. We will briefly discuss the performance of CSNR-based waveform over CMI-based waveform later.
Figure 2. Corresponding ESD to Different Scenarios with Target 1. (a) ESD for CSNR-based waveform; (b) ESD for MI-based waveform; (c) ESD for CMI-based Waveform; (d) ESD for TSF Waveform.
shown in Figure 2(b) MI-based waveform without considering clutter shape puts its energy relative to the target peak values and finally TSF waveform unlike other waveforms follows all target peak energy allocation is done in each band where the target has either small or large peaks. As shown in this figure, CSNR-based waveform compared with other waveforms distributed less energy into the frequency band $[-0.2, 0]$, where the target is comparable to the clutter and instead puts more energy into the frequency band $[0.3, 0.4]$, where the clutter has smaller amounts of PSD compared with the target.

The target-to-noise ratio (TNR) is defined as the ratio of the area under target PSD to the area under noise PSD [17], and also the ratio of the area under the clutter PSD to noise PSD is called clutter-to-noise ratio (CNR). The last ratio is TCR which is the area under the target PSD to clutter PSD. In this example, TNR, CNR and TCR are 1.66 dB, 10.94 dB and −9.29 dB, respectively. As we expected, with specified energy constraint, these waveforms which are designed in such a way to focus their energy into frequency bands; the target has the largest PSD value and the clutter has the smallest PSD value. As can be seen in Figure 2 for target 1, the CSNR-based and CMI-based allocated most of their energy in the frequency sub-band $[0.3, 0.4]$, where the target is comparable in terms of PSD value with clutter while this point for MI-based and TSF waveforms are not considered. We will show later that this is the main reason for the improvement of CSNR-based and CMI-based on scenarios with low values of TCR.

We repeat the experiment with target 2 and with the same clutter and noise PSD. For this target, we have TNR = 0.51 dB, CNR = 0.95 dB and TCR = −0.44 dB and corresponding waveforms for this target scenario are computed and illustrated in Figure 3. As seen in this figure, TSF waveform follows all target peaks and puts its energy due to each target peak not consider clutter and noise for this energy allocation. CMI-based and MI-based waveforms have approximately similar response to this target and just follow two great peaks of this target putting their energy equally into the corresponding frequency bands while CSNR-based puts its main energy into frequency band which has the smallest value of clutter PSD value; this could be a reason for better performance of this waveform compared with others.

### 3.2. SNR and MI Comparison between Different Waveforms

As shown before, solving optimization problem requires knowledge of the target and clutter spectrum. It was shown in [8] that the probability of detection is related to the probability of false alarm by:

$$P_D = 1 - \psi_h \left( \frac{g_0}{g_1} \psi^{-1}_h (1 - P_{fa}) \right)$$

(31)

where $\psi_h (\eta)$ is the cumulative density function of a chi-square random variable with $h$ degrees of freedom.

It has been shown that:
Figure 3. Corresponding ESD for different scenarios with target 2. (a) ESD for CSNR-based waveform; (b) ESD for MI-based waveform; (c) ESD for CMI-based waveform. (d) ESD for TSF waveform.
\[
\frac{g_0}{g_1} = \frac{1}{1 + D(x)}
\]

With a good approximation \(D(x)\) is equal to:

\[
D(x) = 2 \int \frac{|X(f)|^2 |H(f)|^2}{|X(f)|^2 P_x(f) + P_n(f)} df = 2SINR
\]

And finally we have:

\[
P_D = 1 - \Psi - \frac{1}{1 + 2SINR} \Psi^{-1} (1 - P_{fa})
\]

Using the above equation, since maximizing \(P_D\) for arbitrary values of \(P_{fa}\) depends on the values of SINR for each waveform and by maximizing SINR, we can achieve higher values of \(P_D\). Previous research has shown that SNR-based waveform and LFM waveform are compared through this method and shown that the proposed method had better performance in terms of maximizing the probability of detection. Here, we obtained different waveforms with both SNR and MI values and now we want to select the desired waveform based on achieving maximizing probability of detection for each target and clutter scenarios regarding the point that the desired waveform should have a sufficient MI value in comparison with other waveforms. MI and SINR which are defined in (14), (21) respectively, are considered as objective functions. We computed their values for three different targets.

For each target the corresponding waveform according to target, clutter and noise spectrum is generated and utilized for computing SNR and MI. Now we suppose a specific scenario with known target, clutter and noise PSDs. We are interested in investigating the effects of target, clutter and noise separately. So, we consider the scenario 1 which includes a specific Gaussian extended target, Gaussian clutter and AWGN noise with known PSDs, then compute CNR, TCR and TNR values for this scenario. Afterwards, by changing clutter (target and noise are fixed), scenario 2 is obtained and similarly scenario 3 and scenario 4 are obtained by changing the target and noise, respectively. Target, Clutter and Noise PSD for each scenario are illustrated in Figure 4 and also their CNR, TCR and TNR values are shown in Table 1.

After defining scenarios, ESD of each waveform in accordance with each scenario is computed due to the obtained relations. Eventually for each scenario corresponding SNR and MI values for investigating the applied changes in target, clutter and noise are evaluated by Equation (15), (22) as summarized in Table 2.

As indicated in Table 2, CSNR-based waveform compared with other waveforms has greater SNR amount for each scenario, and according to (34) this waveform should have the best performance in terms of maximizing the probability of detection. The point that should be considered is its MI value which is not maximum even
Figure 4. Target, clutter and noise PSD for each scenario. (a) Scenario 1; (b) Scenario 2; (c) Scenario 3; (d) Scenario 4.
<table>
<thead>
<tr>
<th>Scenario</th>
<th>CNR</th>
<th>TCR</th>
<th>TNR</th>
</tr>
</thead>
<tbody>
<tr>
<td>Scenario 1</td>
<td>10.95</td>
<td>−17.37</td>
<td>−6.42</td>
</tr>
<tr>
<td>Scenario 2</td>
<td>−6.62</td>
<td>0.2</td>
<td>−6.42</td>
</tr>
<tr>
<td>Scenario 3</td>
<td>10.95</td>
<td>−11.82</td>
<td>−0.87</td>
</tr>
<tr>
<td>Scenario 4</td>
<td>20.95</td>
<td>−17.37</td>
<td>3.58</td>
</tr>
</tbody>
</table>

Table 2. Corresponding SNR and MI values in dB for different waveforms in each scenario.

<table>
<thead>
<tr>
<th>Waveform</th>
<th>MI-based Waveform</th>
<th>CMI-based Waveform</th>
<th>CSNR-based Waveform</th>
<th>TSF Waveform</th>
<th>LFM Waveform</th>
</tr>
</thead>
<tbody>
<tr>
<td>Scenario 1</td>
<td>SNR = 17.16</td>
<td>MI = 16.82</td>
<td>SNR = 17.94</td>
<td>SNR = 18.09</td>
<td>SNR = 18.26</td>
</tr>
<tr>
<td>Scenario 2</td>
<td>SNR = 18.16</td>
<td>MI = 17.75</td>
<td>SNR = 18.16</td>
<td>SNR = 17.66</td>
<td>MI = 17.53</td>
</tr>
<tr>
<td>Scenario 3</td>
<td>SNR = 19.93</td>
<td>MI = 21.51</td>
<td>SNR = 22.5</td>
<td>MI = 20.67</td>
<td>MI = 19.52</td>
</tr>
<tr>
<td>Scenario 4</td>
<td>SNR = 25.26</td>
<td>MI = 25.03</td>
<td>SNR = 26.75</td>
<td>SNR = 24.15</td>
<td>SNR = 17.63</td>
</tr>
</tbody>
</table>

in one scenario and this is the CMI-based waveform that has greater MI amounts compared with other waveforms. As mentioned in [18], LFM waveform is a good candidate for distinguishing point targets, and for an extended target case may not have good performance which we will discuss in the following paragraph.

In Table 2 for scenario 1, we have 9.84 dB SNR improvement for CSNR-based waveform over LFM waveform and 9.69 dB SNR improvement for CMI-based waveform over LFM waveform. This improvement for the waveform is proposed in [8] over LFM waveform was 3 dB and by the method proposed in [16] SNR of the proposed waveform was about 4 dB higher than the square pulse or the LFM pulse. For TSF waveform, we have 7.41 dB improvement which can be a good choice in some scenarios. For example, for high values of TCR, this waveform has a better performance in terms of MI and approximately the same performance in terms of SNR compared with CSNR-based waveform.

It is obvious from Table 1 and Table 2 that by decreasing the clutter PSD, SNR and MI value will increase from one scenario to another. This idea is true for the case of increasing the amounts of target spectrum and decreasing noise PSD.

To evaluate the performance, we used receiver operating characteristic (ROC) curves corresponding to the obtained waveforms and LFM. Figure 5 shows these ROC curves for all scenarios. As it is clear, the improvement of obtaining waveforms over LFM is shown in this Figure for all scenarios; we see that CSNR-based and CMI-based waveforms for all scenarios have a better performance compared with other waveforms.

4. Providing General Result and Defining an Appropriate Closed-Loop Structure

4.1. Numerical Results with Different Deterministic Extended Target, Clutter and Noise

Now to better demonstrate the importance of waveform design in cognitive radar, we simulate different targets, clutters and noise realizations. To reach an aggregation, we compute SNR and MI values for each waveform by changing TCR, TNR and CNR values in a specific range. For example in Figure 6(a) and Figure 6(b), SNR and MI changes in dB versus TCR for each waveform are illustrated. It can be concluded from this figure that all waveforms have a similar SNR performance with increasing TCR and as previously discussed have a better performance over LFM waveform.

From MI consideration, as we expected, CMI-based and MI-based have better performance with a little difference compared with CSNR-based and TSF waveforms. Finally, we can conclude that indifferent values of TCR, all waveforms have 9 dB and 7 dB improvement in SNR and MI, respectively over LFM waveform.
Figure 6(c) and Figure 6(d) show the SNR and MI value changes in dB for different TNR values. As indicated in this Figure, CSNR-based and CMI-based waveforms are completely similar in low TNRs but in high TNR values in terms of MI, CMI-based waveform is slightly better. TSF waveform also shows a moderate performance and better than MI-based and LFM waveforms especially in moderate TNRs.

The last case shows the SNR and MI value changes in dB for different CNRs. As indicated in Figure 6(e) and Figure 6(f) for different values of CNRs, similar to those we have for TNR and TCR values, CSNR-based and CMI-based waveforms are completely similar. A noteworthy point is that in low CNR values, MI-based waveform has a good performance but with increasing CNR, its performance declines and TSF waveform performance outperform this waveform in high CNR values. Finally, LFM waveform is fairly constant with CNR and performs the poorly as compared with other waveforms. So, according to the mentioned features for each waveform and due to each application, we should propose a good structure which considers all aspects of the problem conditions. Due to each waveform feature, it should utilize the best waveform to transmit into the environment.
Therefore, a cognitive radar should be designed in such a way that firstly evaluates the TCR, TNR and CNR values and considering to the application and also waveform features which are mainly discussed in this paper, chooses the best waveform to transmit into the environment and achieve the maximum probable values of $P_D$.

### 4.2. Determine a New Closed-Loop Structure for Detecting Deterministic Extended Targets

In Figure 7, new closed-loop structure for detecting M targets indifferent scenarios is proposed. In this structure, SNR and MI values are considered as the cost function. This means that in the transmitter, the desired waveform are selected based on its MI and SNR values.
Figure 6. Comparison of SNR and MI versus TCR, TNR and CNR with deterministic extended target. (a) SNR versus TCR; (b) MI versus TCR; (c) SNR versus TNR; (d) MI versus TNR; (e) SNR versus CNR; (f) MI versus CNR.
Figure 7. Modelling a new structure of cognitive radar for detecting targets in different noise and clutter scenarios.

As indicated in this figure, the proposed cognitive radar structure includes an adaptive transmitter based on the feedback from the receiver and the interactions with a defined database. The radar transmitted its initial waveform into the environment. If the target is detected in the receiver, we have reached our goal; otherwise, cognitive radar loop is established using a feedback from the receiver to the transmitter and this procedure is done as long as the target of interest is identified. Surely, we can set the number of transmitting signals to a pre-determined value to prevent the cognitive radar from being in an infinitive loop.

5. Summary and Conclusion

In this paper, we considered a deterministic Gaussian extended target with Gaussian clutter case for our experiments. The transmitted waveform optimization is done by maximizing the signal to noise ratio and mutual information between the target frequency responses of different targets and the received signal. This helps achieve a better performance in target recognition. We derived different MI-based, SNR-based and TSF waveforms and used an approximate analytical expression for the probability of detection for different waveforms and compared the performance of these waveforms based on this idea. The remarkable features for designing these waveforms for deterministic extended targets, are energy allocation in which waveforms should allocate their energy into frequency bands where target has the greatest PSD value and clutter has the smallest PSD value. This idea will cause the product of target and transmitted waveform got the maximum amount and then the performance of target detection in the presence of clutter will increase.

The derivations of MI-based waveforms for deterministic Gaussian extended targets and in the case of Gaussian clutter are new results. Moreover, TSF waveform in signal-dependent interference is a new result derived to show that depending on the application such as deterministic extended target, energy allocation is not done well. In fact for the scenarios outlined in the text, it is better to allocate most of transmitting waveform energy into frequency bands in which target has considerable peak amount and clutter amount is negligible instead of distributing energy into all target spectrum peaks. In this paper, different values of SNR and MI are obtained in different TCR, CNR and TNR amounts and it is proven that the obtained waveforms have various performances in different TCR, CNR and TNR and in cognitive radar. We propose a new closed-loop structure considering all features discussed in this paper and for each scenario of target, clutter and noise intelligently find the optimum solution. This work just uses deterministic Gaussian targets case in Gaussian clutter. Future work will attempt to investigate methods of waveforms designing for stochastic extended targets in Gaussian and non-Gaussian environments and suggest a general method for each clutter and target scenarios.
References


