Simulated Annealing Algorithm to Minimize Makespan in Single Machine Scheduling Problem with Uniform Parallel Machines

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Abstract

This paper presents a simulated annealing algorithm to minimize makespan of single machine scheduling problem with uniform parallel machines. The single machine scheduling problem with uniform parallel machines consists of \( n \) jobs, each with single operation, which are to be scheduled on \( m \) parallel machines with different speeds. Since, this scheduling problem is a combinatorial problem; usage of a heuristic is inevitable to obtain the solution in polynomial time. In this paper, simulated annealing algorithm is presented. In the first phase, a seed generation algorithm is given. Then, it is followed by three variations of the simulated annealing algorithms and their comparison using ANOVA in terms of their solutions on makespan.

Keywords: Uniform Parallel Machines, Measure of Performance, Heuristic, Simulated Annealing Algorithm, ANOVA

1. Introduction

The single machine scheduling problem is classified into single machine scheduling with single machine and single machine scheduling problem with parallel machines. The single machine scheduling problem with single machine consists of \( n \) independent jobs, each with single and same operations. The single machine scheduling with parallel machines is further classified into the following three categories.

- Single machine scheduling with identical parallel machines
- Single machine scheduling with uniform parallel machines
- Single machine scheduling with unrelated parallel machines

Let, \( t_{ij} \) be the processing times of the job \( j \) on the machine \( i \), for \( i = 1, 2, 3, \ldots, m \) and \( j = 1, 2, 3, \ldots, n \).

Then the three types of parallel machines scheduling problem are defined using this processing time.

1) If \( t_{ij} = t_{ij}/s_i \) for all \( i \) and \( j \), where \( s_i \) is the speed of the machine \( i \) and \( t_{ij} \) is the processing time of the job \( j \) on the machine 1, then the problem is termed as uniform (proportional) parallel machines scheduling problem.

This means that the parallel machines will have different speeds. Generally, we assume \( s_1, s_2, s_3, \ldots \), and \( s_m \) for the parallel machines 1, 2, 3,…, and \( m \), respectively with the relation \( s_1 < s_2 < s_3 < \ldots < s_m \). That is the machine 1 is the slowest machine and the machine \( m \) is the fastest machine. For a given job, its processing times on the parallel machines will be in the ratios as listed below.

\[
\frac{1}{s_1} : \frac{1}{s_2} : \frac{1}{s_3} : \ldots : \frac{1}{s_m}
\]

2) If \( t_{ij} \) is arbitrary for all \( i \) and \( j \), then the problem is known as unrelated parallel machines scheduling problem.

In this type of scheduling, there will not be any relation amongst the processing times of a job on the parallel machines.

In this paper, the single machine scheduling problem with uniform parallel machines is studied to minimize
the makespan. When \( n \) jobs with single operation are scheduled on \( m \) parallel machines, then each parallel machine will have its completion time of the last job in it. The maximum of such completion times on all the parallel machines is known as the makespan of the parallel machines scheduling problem, which is an important measure of performance, Panneerselvam [1].

The essential characteristics of the uniform parallel machines scheduling problem are as listed below.

- It has \( n \) single operation jobs.
- It has \( m \) parallel machines with different speeds \((s_1 < s_2 < s_3 < \ldots < s_m)\).
- \( m \) machines are continuously available and they are never kept idle while work is waiting
- \( t_{ij} \) is the processing time of the job \( j \) on the machine \( i \) for \( j = 1, 2, 3, \ldots, n \).
- For each job, its processing times on the uniform parallel machines are inversely proportional to the speeds of those parallel machines \((1/s_1 : 1/s_2 : 1/s_3 : \ldots : 1/s_m)\), where \( s_1 \) is the unit speed.
- \( t_i = t_1/s_1 \) for \( j = 1, 2, 3, \ldots, n \) and \( i = 2, 3, \ldots, m \).

A sample data of the uniform parallel machines scheduling problem is shown in Table 1, in which the speed ratio between the machine 1 and the machine 2 is 1:2.

In this paper, off-line, non-preemptive single machine scheduling problem with uniform parallel machines is considered.

To quote few practical examples of this uniform parallel machines scheduling problem, consider the machine shop of an automobile company. Over a period of time, machines of similar processing nature will be added to enhance the capacity of the shop. The machines which are added at the later stage will have higher speed when compared to the old existing machines. One can establish a speed ratio of the speeds of these two categories of machines. If \( n \) independent single operation jobs are scheduled on these two categories of machines collectively to minimize the makespan, this practical reality corresponds to single machine scheduling problem with uniform parallel machines with the objective of minimizing the makespan.

2. Review of Literature

In this section, the review of off-line, non-preemptive single machine scheduling problem with uniform parallel machines is presented.

Horowitz and Sahni [2] first presented dynamic programming algorithms for scheduling independent tasks in a multiprocessor environment in which the processors have different speeds. In this research, the objective is to minimize the finish time (makespan) and weighted mean flow time on two processors. Next, they presented approximation algorithms of low polynomial complexity for the above problem. Ibarra and Kim [3] have developed a heuristic for scheduling independent tasks on nonidentical processors. In their study, particularly, for \( m = 2 \), an \( n \log n \) time-bounded algorithm is given which generates a schedule having a finishing time of at most \((\sqrt{5} + 2)/2 \) of the optimal finishing time. They verified that the \( LPT \) algorithm applied to this problem gives schedules which are near optimal for larger \( n \).

Prabuddha De and Thomas E. Morton [4] have developed a new heuristic to schedule jobs on uniform parallel processors to minimize makespan. They found that the solutions given by the heuristic for the uniform parallel machines scheduling are within 5% of the solutions given by the branch and bound algorithm. Bullin and Parker [5] have considered the problem of scheduling tasks on a system consisting of two parallel processors such that the makespan is minimized. In particular, they treated a variety of modifications to this basic theme, including the cases of identical processors, proportional (uniform) processors and unrelated processors.

Friesen and Langston [6] examined the non-preemptive assignment of \( n \) independent tasks to a system of \( m \) uniform processors with the objective of reducing the makespan. It is known that \( LPT \) (longest processing time first) schedules are within twice the length of the optimum makespan. Graham [7] analyzed a variation of the \( MULFIT \) algorithm derived from the algorithm for bin packing problem and proved that its worst-case performance bound on the makespan is within 1.4 times of the optimum makespan. Gregory Dobson [8] has given a worst-case analysis while applying the \( LPT \) (longest processing Time) heuristic to the problem of scheduling independent tasks on uniform processors with the minimum makespan. Friesen [9] examined the nonpreemptive assignment of independent tasks to a system of uniform processors with the objective of minimizing the makespan. The author showed that the worst case bound for the \( LPT \) algorithm for this problem is tightened to be in the interval \((1.52 \text{ to } 1.67)\).

Hochbaum and Shmoys [10] devised a polynomial approximation scheme for the minimizing makespan problem on uniform parallel processors.

Chen [11] has examined the non-preemptive assignment of independent tasks to a system of \( m \) uniform processors with the objective of minimizing the makespan.
an. The author has examined the performance of \( LPT \) (largest processing time) schedule with respect to optimal schedules, using the ratio of the fastest speed to the slowest speed of the system as a parameter.

Mireault, Orlin, Vohra [12] have considered the problem of minimizing the makespan when scheduling independent tasks on two uniform parallel machines. Out of the two machines, the efficiency of one machine is \( q \) times that of the other machine. They computed the maximum relative error of the \( LPT \) (largest processing time first) heuristic as a function of \( q \). For the special case in which the two machines are identical (\( q = 1 \)), their problem and heuristic are identical to the problem and heuristic analyzed by Graham [7], respectively. Burkard and He [13] derived the tight worst-case bound \( \sqrt{5/2} + (1/2)^q \) for scheduling jobs using the \textit{MULTIFIT} heuristic on two parallel uniform machines with \( k \) calls of \textit{FFD} (first fit decreasing) within \textit{MULTIFIT}.

Burkard, He and Kellerer [14] have developed a linear compound algorithm for scheduling jobs on uniform parallel machines with the objective of minimizing makespan. This algorithm has three subroutines, which run independently in order to choose the best assignment among them. Panneerselvam and Kanagalingam [15] have presented a mathematical model for parallel machines scheduling problem with varying speeds in which the objective is to minimize the makespan. Also, they discussed industrial applications of such scheduling problem. Panneerselvam and Kanagalingam [16] have given a heuristic to minimize the makespan for scheduling \( n \) independent jobs on \( m \) parallel processors with different speeds.

Chandra Chekuri and Michael Bender [17] designed a new and efficient polynomial \( 6 \) approximation algorithm for scheduling precedence-constrained jobs on uniform parallel machines. Chudak and Shmoys [18] gave an algorithm with an approximation ratio of \( O (\log m) \), significantly improving the earlier ratio of \( O (\sqrt{m}) \) due to Jaffe [19]. Their algorithm is based on solving a linear programming relaxation. Building on some of their ideas, Chandra Chekuri and Michael Bender [20] have presented a combinatorial algorithm that achieves a similar approximation ratio but in \( O (n^3) \) time. Ching-Jong Liao and Chien-Hung Lin [21] have considered the two uniform parallel machines problem with the objective of minimizing makespan. In this work, the two uniform parallel machines problem is converted into a special problem of two identical parallel machines from the viewpoint of workload instead of completion time. An optimal algorithm is developed for the transformed special problem. The proposed algorithm has an exponential time complexity.

Christos Koulamas and George J. Kyparisis [22] investigated the makespan minimization problem on uniform parallel machines in the presence of release times. They developed a heuristic for this NP-hard problem and derived a tight worst-case ratio bound for this heuristic independent of the machines speeds. Agarwal, Colak, Jacob and Pirkul [23] have proposed new heuristics along with an augmented-neural-netwrok (AugNN) formulation for solving the makespan minimization task-scheduling problem for the non-identical machine environment. Chein-Hung Lin and Ching-Jong Liao [24] have considered a classical scheduling problem with makespan minimization on uniform parallel machines. From the viewpoint of workload, instead of completion time, two important theorems are developed for the problem.

From the literature, it is clear that the objective of minimizing the makespan in single machine scheduling problem with uniform parallel machines comes under combinatorial category. Hence, development of heuristic is inevitable for this problem. Hence, a simulated annealing algorithm is presented in this paper.

3. Simulated Annealing Algorithm

This section presents a simulated annealing algorithm to minimize the makespan in the single machine scheduling problem with uniform parallel machines. The simulated annealing algorithm has emerged from annealing which is a heat treatment process. Annealing aims to bring back the metallurgical structure of components which are either hammered/cold drawn, etc. This heat treatment process is called annealing, which will release the internal stress and strain of the component, there by changing the misaligned grain structure to its original grain structure. The above process of annealing is mapped to solve optimization problems, especially combinatorial problems and it is termed as “simulated annealing algorithm”. The parameters of the simulated annealing algorithm are given as:

- \( T \) – temperature
- \( r \) – a range from 0 to 1 which is used to reduce the temperature
- \( \delta \) – a small positive number provided by the user

The skeleton of the simulated annealing algorithm applied to minimization problem is given as follows.

\( \text{Step 0: Input } T, r \text{ and } \delta \) 
\( \text{Step 1: Get an initial feasible solution } S_0 \text{ and compute } f(S_0) \) 
\( \text{Step 2: Get an initial temperature, } T > 0 \) 
\( \text{Step 3: Generate feasible solution } S_i \text{ in the neighbourhood of } S_0 \text{ and compute } f(S_i) \) 
\( \text{Step 4: Compute } d = f(S_0) - f(S_i) \)
Step 5: Update $S_0$.
5.1. If $d > 0$, set $S_0 = S_1$ and go to Step 6; else go to Step 5.2.
5.2. Generate uniformly distributed random number in the range 0 to 1 ($R$).
5.3. If $R < e^{\left(\frac{d}{T}\right)}$, then set $S_0 = S_1$ and go to Step 6; else go to Step 6.
Step 6: Set $T = r \times T$.
Step 7: If $T > \delta$, then go to Step 3; otherwise go to Step 8.
Step 8: Use local optimization to reach a local optimum starting from the last $S_0$ value.
Step 9: Stop

In simulated annealing, there are three schemes of perturbation as listed below.
1) Shifting a job from one machine to another machine.
2) Exchanging jobs between two machines.
3) Transferring a job from one of the existing machines to a new machine (This is an infeasible scheme in this type of scheduling).

Under the third scheme, a new machine will have to be included to accommodate the job which is transferred from any of the existing machines. The given problem has a fixed number of machines ($m$). Hence, the usage of the third scheme of perturbation is not possible. From the skeleton of the simulated annealing algorithm, it is clear that for good solution, researcher should use an efficient seed generation algorithm and it should be followed by the second phase to obtain global optimum solution.

### 3.1. Seed Generation Algorithm

The steps of a seed generation algorithm used in the simulated annealing algorithm are presented in this section.

Step 1: Input the following.
- Number of independent jobs with single operation ($n$)
- Number of uniform parallel machines ($m$) with speeds $s_1, s_2, s_3, \ldots, s_m$.
- Processing times of the jobs on the uniform parallel machines.
- Previous maximum makespan ($PMS$), a very high value (10^6).

Step 2: Rearrange the jobs as per their longest processing time order based on their processing times on the machine 1 (decreasing order of processing time from left to right).

Step 3: For each job $Q$ in the longest processing time order array, from left to right, perform the following.
3.1. Add the current job as the last job to each of the machines and compute the temporary completion time of that job on each machine.
3.2. Find the minimum (MIN) of the temporary completion times of that job on all the machines and identify the corresponding machine number ($P$).
3.3. Update the following:
a) Completion time of the last job on the machine $P$ to $MIN$.
b) Increment the number of jobs assigned to the machine $P$ by 1.
c) Store the current job $Q$ at the position $N(P)$ on the machine $P$ as shown below.

$$JOB_{P,N(P)} = Q$$

Step 4: Find the maximum of the completion times of the last jobs on all the machines and treat it as the makespan ($MS$) of the current schedule.

Let, the machine on which this maximum makespan occurs be $R$.
Step 5: If $MS \geq PMS$ then go to Step 9; otherwise, update $PMS = MS$ and go to Step 6.

Interchanging the jobs between machines is starting from machine R to Machine 1 if they yield reduction in makespan.
Step 6: Set $INDEX1 = 0$ and $INDEX2 = 0$
Step 7: For each job (job at the position I) from left to right on the machine R, perform the following.
7.1. Set $I = 1$
7.2. Store the immediate preceding machine (Slower machine) number with respect to the machine $R$ in $S$.

$$S = R - 1$$

7.3. If the completion time of the last job on the machine S is 0, then go to Step 7.5; otherwise, go to Step 7.4.
7.4. For each job (Job at the position J) in machine S from left to right, perform the following.
7.4.1. Set $J = 1$
7.4.2. Temporarily exchange the Job at the position I on the machine R with the Job at the position J on the machine S and find the maximum of the completion times of the last jobs on all the machines ($MAX_{MS}$).
7.4.3. If $MAX_{MS} < MS$, then exchange the job at the position I on the machine R and the job at the position J on the machine S and go to Step 7.4.4; otherwise, go to Step 7.4.5.
7.4.4. Update $PMS = MAX_{MS}$.
7.4.5. Update $INDEX1 = 1$ and $INDEX2 = 1$
7.4.5. Increment the job position on the machine S by 1 ($J = J + 1$).
7.4.6. If $J \leq$ the last position on the machine S, then go to Step 7.4.7; otherwise, go to Step 7.4.8.
7.4.7. If $INDEX2 = 0$ then go to Step 7.4.2; otherwise, set $INDEX2 = 0$ and go to Step 7.4.1.
7.5. Decrement slower machine number (S) by 1 ($S = S - 1$).
7.6. If $S \geq 1$, then go to Step 7.3; otherwise, go to Step 8.

Step 8: If $\text{INDEX1} = 1$, then go to Step 4; otherwise, go to Step 9.

Step 9: Print the following results.
   a) Assignment of jobs on the machines $\text{JOBi}$, $i = 1, 2, 3, ..., m$ and $j = 1, 2, 3, ..., N(i)$
   b) Makespan of the schedule, $MS$

3.2. Simulated Annealing Algorithm to Minimize Makespan

In this section, three different simulated annealing algorithms (SA1, SA2 and SA3) are presented to minimize the makespan in the single machine scheduling problem with uniform parallel machines. The differences in these algorithms are in terms of selection of the machines for exchanging the jobs as well as transferring a job from one machine to another machine. The details are shown in Table 2. Through experimentation, the parameters of the simulated annealing algorithm are set at: $T = 60$, $r = 0.85$ and $\delta = 0.01$.

3.2.1. Simulated Annealing Algorithm SA1

The steps of the simulated annealing algorithm SA1 are presented in this section. In this algorithm, while selecting two machines for exchanging jobs in them as well as transferring a job from one machine to another machine, they are selected with equal probability, which is equal to $1/m$, where $m$ is the total number of uniform parallel machines.

Step 1: Input the following.
   - Number of independent jobs with single operation ($n$)
   - Number of uniform parallel machines ($m$) with speeds $s_1, s_2, s_3, ..., s_m$
   - Processing times of the jobs on the uniform parallel machines.

Step 2: Obtain an initial feasible schedule ($S_0$) using the seed generation algorithm given in Subsection 3.1. Let the corresponding makespan of the schedule be $f(S_0)$.

Step 3: Set $T = 60$, $r = 0.85$ and $\delta = 0.01$.

Step 4: Generating feasible solution $S_1$ in the neighborhood of $S_0$ and computing corresponding make-span, $f(S_1)$.

4.1. Generate uniformly distributed random number, $R$ in between 0 to 0.99.
4.2. If $R \leq 0.49$ then go to Step 4.3; else go to Step 4.4.
4.3. Exchange of jobs between two machines.
4.3.1. Randomly select a machine ($P_1$), which is assigned with at least one job for transferring a job from that machine.

Table 2. Distinctions among the sa algorithms applied to minimize makespan.

<table>
<thead>
<tr>
<th>Algorithm</th>
<th>Probability of selection of machines for exchanging jobs</th>
<th>Probability of selection of machines for transferring a job from one machine to another machine</th>
</tr>
</thead>
<tbody>
<tr>
<td>SA1</td>
<td>Equal</td>
<td>Equal</td>
</tr>
<tr>
<td>SA2</td>
<td>Inverse of the speed of the machine</td>
<td>Equal</td>
</tr>
<tr>
<td>SA3</td>
<td>Inverse of the speed of the machine</td>
<td>Inverse of the speed of the machine</td>
</tr>
</tbody>
</table>

4.3.2. Randomly select a job from the machine $P_1$ and let it be $Q_1$.
4.3.3. Randomly select another machine ($P_2$), which is assigned with at least one job for transferring a job from that machine.
4.3.4. Randomly select a job from the machine $P_2$ and let it be $Q_2$.
4.3.5. Exchange the jobs $Q_1$ and $Q_2$ between the machines $P_1$ and $P_2$.
4.3.6. Compute the makespan of this schedule, $f(S_1)$.

Go to Step 5.

4.4. Transfer of a job from one machine to another machine.

4.4.1. Randomly select a machine ($P_1$), which is assigned with at least one job for transferring a job from that machine.
4.4.2. Randomly select a job from the machine $P_1$ and let it be $Q_1$.
4.4.3. Randomly select another machine ($P_2$) to which job $Q_1$ is to be transferred.
4.4.4. Transfer the job $Q_1$ from the machine $P_1$ to the machine $P_2$.
4.4.5. Compute the makespan of this schedule, $f(S_1)$.

Go to Step 5.

Step 5. Compute $d = f(S_0) - f(S_1)$.

Step 6. Updating $S_0$.
6.1. If $d > 0$, set $S_0 = S_1$ and go to Step 7; else go to Step 6.2.
6.2. Generate uniformly distributed random number ($R$) in the range 0 to 1.
6.3. If $R < e (d/T)$, then set $S_0 = S_0$ and go to Step 7; else go to Step 7.
   Step 7. Set $T = r \times T$
   Step 8. If $T > \delta$, then go to Step 4; otherwise go to Step 9.
   Step 9. Use the seed generation algorithm (local optimum procedure) to reach a local optimum starting from the last $S_0$ value and print the final schedule.
   Step 10: Stop.
3.2.2. Simulated Annealing Algorithm SA2
The steps of the simulated annealing algorithm SA2 are presented in this section. In this algorithm, while selecting two machines for exchanging jobs, each machine is selected with a probability equal to the inverse of its speed ratio. But, while transferring a job from one machine to another machine, each machine is selected with equal probability, which is equal to \(1/m\), where \(m\) is the total number of uniform parallel machines.

Step 1: Input the following.
- Number of independent jobs with single operation \((n)\)
- Number of uniform parallel machines \((m)\) with speeds \(s_1, s_2, s_3, \ldots, s_m\).
- Processing times of the jobs on the uniform parallel machines.

Step 2: Obtain an initial feasible schedule \((S_0)\) using the seed generation algorithm given in Section 3.1. Let the corresponding makespan of the schedule of the initial feasible solution be \(f(S_0)\).

Step 3: Set \(T = 60\), \(r = 0.85\) and \(\delta = 0.01\).

Step 4: Generating feasible solution \(S_1\) in the neighborhood of \(S_0\) and computing corresponding makespan, \(f(S_1)\).

4.1. Generate uniformly distributed random number, \(R\) in between 0 to 0.99.
4.2. If \(R \leq 0.49\) then go to Step 4.3; else go to Step 4.4.
4.3. Exchange of jobs between two machines.

4.3.1. Randomly select a machine \((P1)\), which is assigned with at least one job for transferring a job from that machine, by assuming inverse of the speed ratio as the probability of selection for each of the machines.
4.3.2. Randomly select a job from the machine \(P1\) and let it be \(Q1\).
4.3.3. Randomly select another machine \((P2)\), which is assigned with at least one job for transferring a job from that machine, by assuming inverse of the speed ratio as the probability of selection for each of the machines.
4.3.4. Randomly select a job from the machine \(P2\) and let it be \(Q2\).
4.3.5. Exchange the jobs \(Q1\) and \(Q2\) between the machines \(P1\) and \(P2\).
4.3.6. Compute the makespan of this schedule, \(f(S1)\).

Go to Step 5.
4.4. Transfer of a job from one machine to another machine.

4.4.1. Randomly select a machine \((P1)\), which is assigned with at least one job for transferring a job from that machine.
4.4.2. Randomly select a job from the machine \(P1\) and let it be \(Q1\).
4.4.3. Randomly select another machine \((P2)\) to which the job \(Q1\) is to be transferred.
4.4.4. Transfer the job \(Q1\) from the machine \(P1\) to the machine \(P2\).
4.4.5. Compute the makespan of this schedule, \(f(S1)\).

Go to Step 5.

Step 5: Compute \(d = f(S0) – f(S1)\).
Step 6: Updating \(S0\).
6.1. If \(d > 0\), set \(S0 = S1\) and go to Step 7; else go to Step 6.2.
6.2. Generate uniformly distributed random number \((R)\) in the range 0 to 1.
6.3. If \(R < e(d/T)\), then set \(S0 = S1\) and go to Step 7; else go to Step 7.
Step 7: Set \(T = r \times T\)
Step 8: If \(T > \delta\), then go to Step 4; otherwise go to Step 9.
Step 9: Use the seed generation algorithm (local optimum procedure) to reach a local optimum starting from the last \(S0\) value and print the final schedule.
Step 10: Stop.

3.2.3. Simulated Annealing Algorithm SA3
The steps of the simulated annealing algorithm SA3 are presented in this section. In this algorithm, while selecting two machines for exchanging jobs as well as transferring a job from one machine to another machine, each machine is selected with a probability equal to the inverse of its speed ratio.

Step 1: Input the following.
- Number of independent jobs with single operation \((n)\)
- Number of uniform parallel machines \((m)\) with speeds \(s_1, s_2, s_3, \ldots, s_m\).
- Processing times of the jobs on the uniform parallel machines.

Step 2: Obtain an initial feasible schedule \((S_0)\) using the seed generation algorithm given in Section 3.1. Let the corresponding makespan of the schedule of the initial feasible solution be \(f(S_0)\).

Step 3: Set \(T = 60\), \(r = 0.85\) and \(\delta = 0.01\).

Step 4: Generating feasible solution \(S1\) in the neighborhood of \(S_0\) and computing corresponding makespan, \(f(S1)\).

4.1. Generate uniformly distributed random number, \(R\) in between 0 to 0.99.
4.2. If \(R \leq 0.49\) then go to Step 4.3; else go to Step 4.4.
4.3. Exchange of jobs between two machines.

4.3.1. Randomly select a machine \((P1)\), which is assigned with at least one job for transferring a job from that machine, by assuming inverse of the speed ratio as the probability of selection for each of the machines.
4.3.2. Randomly select a job from the machine \(P1\) and let it be \(Q1\).
4.3.3. Randomly select another machine \((P2)\), which is assigned with at least one job for transferring a job from that machine, by assuming inverse of the speed ratio as the probability of selection for each of the machines.
4.3.4. Randomly select a job from the machine \(P2\) and let it be \(Q2\).
4.3.5. Exchange the jobs \(Q1\) and \(Q2\) between the machines \(P1\) and \(P2\).
4.3.6. Compute the makespan of this schedule, \(f(S1)\).

Go to Step 5.
4.4. Transfer of a job from one machine to another machine.

4.4.1. Randomly select a machine \((P1)\), which is assigned with at least one job for transferring a job from that machine.
4.4.2. Randomly select a job from the machine \(P1\) and let it be \(Q1\).
4.4.3. Randomly select another machine \((P2)\) to which the job \(Q1\) is to be transferred.
4.4.4. Transfer the job \(Q1\) from the machine \(P1\) to the machine \(P2\).
4.4.5. Compute the makespan of this schedule, \(f(S1)\).

Go to Step 5.

Step 5: Compute \(d = f(S0) – f(S1)\).
Step 6: Updating \(S0\).
6.1. If \(d > 0\), set \(S0 = S1\) and go to Step 7; else go to Step 6.2.
6.2. Generate uniformly distributed random number \((R)\) in the range 0 to 1.
6.3. If \(R < e(d/T)\), then set \(S0 = S1\) and go to Step 7; else go to Step 7.
Step 7: Set \(T = r \times T\)
Step 8: If \(T > \delta\), then go to Step 4; otherwise go to Step 9.
Step 9: Use the seed generation algorithm (local optimum procedure) to reach a local optimum starting from the last \(S0\) value and print the final schedule.
Step 10: Stop.
assigned with at least one job for transferring a job from that machine, by assuming inverse of the speed ratio as the probability of selection for each of the machines.

4.3.4. Randomly select a job from the machine P2 and let it be Q2.

4.3.5. Exchange the jobs Q1 and Q2 between the machines P1 and P2.

4.3.6. Compute the makespan of this schedule, \( f(S_1) \).

Go to Step 5.

4.4. Transfer of a job from one machine to another machine.

4.4.1. Randomly select a machine (P1), which is assigned with at least one job for transferring a job from that machine, by assuming inverse of the speed ratio as the probability of selection for each of the machines.

4.4.2. Randomly select a job from the machine P1 and let it be Q1.

4.4.3. Randomly select another machine (P2) to which the job Q1 is to be transferred, by assuming inverse of the speed ratio as the probability of selection for each of the machines.

4.4.4. Transfer the job Q1 from the machine P1 to the machine P2.

4.4.5. Compute the makespan of this schedule, \( f(S_1) \).

Go to Step 5.

Step 5: Compute \( d = f(S_0) - f(S_1) \).

Step 6: Updating \( S_0 \).

6.1. If \( d > 0 \), set \( S_0 = S_1 \) and go to Step 7; else go to Step 6.2.

6.2. Generate uniformly distributed random number (R) in the range 0 to 1.

6.3. If \( R < e^{-d/T} \), then set \( S_0 = S_1 \) and go to Step 7; else go to Step 7.

Step 7: Set \( T = r \times T \).

Step 8: If \( T > \delta \), then go to Step 4; otherwise go to Step 9.

Step 9: Use the seed generation algorithm (local optimum procedure) to reach a local optimum starting from the last \( S_0 \) value and print the final schedule.

Step 10: Stop.

4. Experimentation with the Algorithms

As stated earlier, in this paper, three simulated annealing algorithms are presented. So, the next step is to compare them in terms of their solutions. Hence, an experiment is designed using randomized complete block design to compare the algorithms. In this experiment, the number of machines is varied form 2 to 4 and the number of jobs is varied from 5 to 25. For each of the combinations of the number of uniform parallel machines and the number of jobs which are to be scheduled in them, data on processing times have been randomly generated by assuming the speed ratio of 1 for the machine-1 and speed ration of m for the machine-m. The results on makespan using the algorithms are summarized in Table 3.

The model of the randomized complete block design used to analyze the data shown in Table 3 is shown below.

\[
Y_{ij} = \mu + B_i + T_j + e_{ij}
\]

where, \( Y_{ij} \) is the makespan w. r. t. \( i^{th} \) block (problem) under the \( j^{th} \) treatment of algorithm.

\( \mu \) is the overall mean

\( B_i \) is the effect of the \( i^{th} \) block (Problem) on the makespan.

\( T_j \) is the effect of the \( j^{th} \) algorithm on the makespan.

\( e_{ij} \) is the random error associated with the makespan w. r. t. \( i^{th} \) block(problem) and \( j^{th} \) algorithm.

Factor: Algorithm

\( H_0: \) There is no significant difference between the algorithms (SA1, SA2 and SA3) in terms of the makespan.

\( H_1: \) There is significant difference between the algorithms (SA1, SA2 and SA3), for at least one pair of algorithms in terms of the makespan.

Block: Problem

\( H_0: \) There is no significant difference between the problems in terms of makespan.

\( H_1: \) There is significant difference between the problems, for at least one pair of the problems in terms of the makespan.

The results of this ANOVA are summarized in Table 4.

Inference:

The calculated F ratio of the factor “Algorithm” is 0.0252 which is less than the table F ratio of 3, at a significance level of 0.05. Hence, the null hypothesis w. r. t. this factor is accepted. This means that there is no significant difference between the algorithms in terms of the makespan.

The calculated F ratio of the block “Problem” is 36199.49 which is more than the table F ratio of 1.319667, at a significance level of 0.05. Hence, the null hypothesis w. r. t. this block is rejected. This means that there is significant difference between problems in terms of the makespan.

Since, it is proved that there is no significant difference between the algorithms, it is suggested to use each of the three algorithms (SA1, SA2 and SA3) for a given problem and select the best result. As per this suggestion, the results shown in Table 3 are analyzed as shown in Table 5. From Table 5, it is seen that the percentage number of best solutions for the algorithms SA1, SA2 and SA3 are 77.78%, 87.3, and 77.78%, respectively. If the best of the results of the three algorithms is selected as the solution for each problem, the percentage number of best solutions is 100%.

From the analysis, it is clear that solving a given problem
Table 3. Results on makespan of the problems using three algorithms.

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<tr>
<th>Problem Size</th>
<th>Algorithm</th>
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using all the three algorithms and then selecting the best of the results of these algorithms as the solution for the problem is more effective, when compared to the individual usage of the three algorithms.

5. Conclusions

The objective of minimizing the makespan in single machine scheduling problem with uniform parallel machines is a combinatorial problem. Hence, in this paper, a simulated annealing approach is presented. In the first phase, a seed generation algorithm is presented. In the second phase, three different seed generation algorithms (SA1, SA2 and SA3) are presented. An ANOVA using
Table 4. Results of ANOVA.

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<th>Degrees of freedom</th>
<th>Mean sum of squares</th>
<th>F ratio (Computed)</th>
<th>F Ratio at α = 0.05</th>
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Table 5. Makespan results with analysis.

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The randomized complete block design is carried out for the problems with number of machines from 2 to 4 and the number of jobs from 5 to 25. Through ANOVA results, it
is found that there is no significant difference among the three algorithms in terms of their solutions. Hence, it is suggested to use all the three algorithms (SA1, SA2 and SA3) for a given problem and select the best result for implementation. The analysis as per this suggestion shows that the combined use of the three algorithms gives very good results for the problems in the experimentation. The simulated annealing approach presented in this paper is a significant contribution to schedule independent jobs on m uniform parallel machines such that the makespan is minimized.

6. References