Importance of Generalized Logistic Distribution in Extreme Value Modeling

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ABSTRACT
We consider a problem from stock market modeling, precisely, choice of adequate distribution of modeling extremal behavior of stock market data. Generalized extreme value (GEV) distribution and generalized Pareto (GP) distribution are the classical distributions for this problem. However, from 2004, [1] and many other researchers have been empirically showing that generalized logistic (GL) distribution is a better model than GEV and GP distributions in modeling extreme movement of stock market data. In this paper, we show that these results are not accidental. We prove the theoretical importance of GL distribution in extreme value modeling. For proving this, we introduce a general multivariate limit theorem and deduce some important multivariate theorems in probability as special cases. By using the theorem, we derive a limit theorem in extreme value theory, where GL distribution plays central role instead of GEV distribution. The proof of this result is parallel to the proof of classical extremal types theorem, in the sense that, it possess important characteristic in classical extreme value theory, for e.g. distributional property, stability, convergence and multivariate extension etc.

Keywords: Financial Risk Modeling; Stock Market Analysis; Generalized Logistic Distribution; Generalized Extreme Value Distribution; Tail Equivalence; Maximum Stability; Random Sample Size; Limit Distribution

1. Introduction
An important problem from the field of stock market modeling is the determination of adequate model for extreme stock movement. In financial literature, the choice of using an appropriate probability model for financial returns are clearly exemplified rather than selecting a conventional model (see for ex. [2]). The fitted tale distribution is crucially important in financial studies. For Value at Risk (VaR) estimation, one requires appropriate probability distribution of extremes as input. A vast number of literature show the importance of best fitted distribution in VaR analysis (see [3]). Another important area of application of probability models of extremes is in hedging procedure. Hedging procedure is clearly based on the probability of fitted distribution (see [4]). Also measuring the risk attached to a share or portfolio will critically depends on the tale distribution. [5] largely illustrates the importance of appropriate probability models for extremes of financial returns data.

Initially, normal and lognormal distributions were used to model data which arise from financial sector. In the last five decades, different authors have been showing that the distribution of extreme daily returns is far from normal (see [5-11]). They used a number of distributions different from normal and lognormal to model large values of finance data. For example t-distribution, alpha stable distribution, etc. In 1990’s the interest in modeling large values of finance data have been diverted to extreme value theory where modeling maximum of the data, generalized extreme value distribution for maxima (GEV(max)) or generalized Pareto (GP) distribution are used and for minimum of the data, generalized extreme value distribution for minima (GEV(min)) is used. These distributions enjoy strong theoretical support for analyzing extreme movement of a data compared to other models. Below we give an outline of these theoretical properties of the distributions.

The theoretical representation for GEV(max) and GEV(min) have been established by Jenkinson and Von Mises (see von Mises (1954) and Jenkinson (1955)). We define GEV(max) below.

**Definition 1.1** A random variable $X$ is said to follow the generalized extreme value distribution for maximum $(GEV(max))$ if its distribution function is given by,

$$
G_x(x) = \begin{cases} 
\exp\left(-(1-kx)^{1/k}\right) & \text{if } k \neq 0 \\
\exp\left(-\exp(-x)\right) & \text{if } k = 0
\end{cases}
$$
and the supports are
\[
\begin{align*}
    x &> k^{-1} \quad \text{for } k < 0 \\
    x &< k^{-1} \quad \text{for } k > 0 \\
    x &\in R \quad \text{for } k = 0.
\end{align*}
\]

The related location-scale family can be introduced by replacing the argument \( x \) above by \( \frac{x - \mu}{\sigma} \) for \( \mu \in R \) and \( \sigma > 0 \). The parameter \( k \in R \) is known as the shape parameter of the distribution and different values of \( k \) lead to different well-known distributions. That is, for \( k = 0 \), it is the Gumbel (Type I) distribution which is interpreted as \( \lim_{k \to 0} G_k \). For \( k > 0 \), it is the reverse-Weibull (Type III) distribution, for \( k < 0 \), it is Frechet (Type II) distribution. Also GEV(min) can be defined as follows.

**Definition 1.2** A random variable \( X \) is said to follow the generalized extreme value distribution for minimum (GEV(min)), if its distribution function is given by,
\[
H_k(x) = \begin{cases} 
1 - \exp\left(-1 - k x\right)^{1/k} & \text{if } k \neq 0 \\
1 - \exp\left(-x\right) & \text{if } k = 0
\end{cases}
\]
and the supports are
\[
\begin{align*}
    x &> k^{-1} \quad \text{for } k < 0 \\
    x &< k^{-1} \quad \text{for } k > 0 \\
    x &\in R \quad \text{for } k = 0.
\end{align*}
\]

The parameter \( k \) is the shape parameter and \( k \in R \).

One can introduce the related location-scale family by replacing the argument \( x \) above by \( \frac{x - \mu}{\sigma} \) for \( \mu \in R \) and \( \sigma > 0 \). For \( k = 0 \) (which is interpreted as \( \lim_{k \to 0} F_k \)), the distribution is called reverse-Gumbel, for \( k > 0 \), it is called reverse-Frechet distribution and for \( k < 0 \), the distribution is the Weibull distribution.

The above two distributions possess the characterizing properties called max-stability and min-stability respectively. In the following we define max-stability for non-random sample size.

**Definition 1.3** A non-degenerate random variable \( X \) is said to be max-stable if, for each \( n = 2,3,\cdots \) there are constants \( a_n > 0 \) and \( b_n \) such that
\[
\max\left(X_1,X_2,\cdots,X_n\right) \overset{d}{=} \left(a_nX + b_n\right),
\]
where \( X_1,X_2,\cdots,X_n \) are same copies of \( X \).

Similarly, one can define min-stability. By the extremal types theorem, asymptotic distribution of maxima of independent and identically distributed random variables (i.i.d.r.v.’s) under proper normalization can be approximated by the GEV(max) distribution. Below we give an outline of the theorem.

**Theorem 1.1** (see [12]): Let \( \{X_n,n \geq 1\} \) be a sequence of i.i.d.r.v.’s and \( M_n = \max(X_1,X_2,\cdots,X_n) \). If there exist sequences of norming constants \( \{a_n > 0\},\{b_n\} \), and a non-degenerate d.f. \( G \) such that,
\[
P\left\{\frac{M_n - b_n}{a_n} \leq x\right\} \xrightarrow{n \to \infty} G(x),
\]
then \( G \), in Equation (1.1), is the GEV(max) distribution defined in Definition 1.4.

Since \( \min(X_1,X_2,\cdots,X_n) = -\max(-X_1,-X_2,\cdots,-X_n) \), the asymptotic distribution of minima of i.i.d.r.v.’s can be derived as \( 1 - G(-x) \), where \( G \) is the GEV(max). Hence the asymptotic distribution for minima is the GEV(min) distribution defined in Definition 1.2. These theories have been extended to multivariate case, where multivariate generalized extreme value distributions play central role (see [13,14]).

Another alternative model for maxima is the generalized Pareto distribution, has been suggested by two independent works [15] and [16]. Below we define GP distribution.

**Definition 1.4** A random variable \( X \) is said to follow the generalized Pareto (GP) distribution if its distribution function is given by,
\[
Q(x) = \begin{cases} 
1 - \left(\left(1 - k x\right)^{1/k}\right) & \text{if } k \neq 0 \\
1 - \exp\left(-x\right) & \text{if } k = 0
\end{cases}
\]
and the supports are
\[
\begin{align*}
    x &> k^{-1} \quad \text{for } k < 0 \\
    x &< k^{-1} \quad \text{for } k > 0 \\
    x &\geq 0 \quad \text{for } k = 0.
\end{align*}
\]

The parameter \( k \) is the shape parameter and \( k \in R \).

One can introduce the related location-scale family by replacing the argument \( x \) above by \( \frac{x - \mu}{\sigma} \) for \( \mu \in R \) and \( \sigma > 0 \). With respect to \( k = 0, k > 0 \) and \( k < 0 \) we get the exponential distribution, beta distribution and Pareto distribution.

GP distribution possess characterizing property called Peak over Threshold (POT) stability w.r.t non-random sample size. In the following we define POT stability for non-random sample size.

**Definition 1.5** A non-degenerate random variable \( X \) is said to be POT-stable if, for each \( u > 0 \) there are constants \( a_u > 0 \) and \( b_u \) such that
\[
\left(X-u\right)/X \overset{d}{=} \left(a_uX + b_u\right).
\]

By Peak over threshold theorem, under proper normalization, the asymptotic distribution of the observations
above exceedences of a level u has a generalized pareto distribution iff asymptotic distribution of maximum of the observations, under proper normalization, is the GEV(max) distribution. We give an outline of the theorem below.

**Theorem 1.2** (see [15,16]) let \( \{X_n, n \geq 1\} \) be a sequence of i.i.d.r.v.’s with common continuous distribution function \( F(x) \). Suppose there exists a pair of sequences \( \{a_n\} \) and \( \{b_n\} \) with \( a_n > 0 \) for all n and a non-degenerate distribution function \( G(x) \) such that

\[
\lim_{n \to \infty} P \left( \left( M_n - b_n \right) / a_n \leq x \right) = \lim_{n \to \infty} F^n \left( a_n x + b_n \right) = G(x)
\]

for all \( x \) at which \( G(x) \) is continuous. Let

\[
P_x(x) = P \{ X > u + x | X > u \} = \frac{1 - F(u + x)}{1 - F(u)}.
\]

Then, under proper normalization, \( P_x(x) \) can be approximated by generalized Pareto (GP) distribution, when \( u \to x_r \) (where \( x_r = \sup \{ x: F(x) < 1 \} \)).

This theory also extended to multivariate case, where multivariate generalized Pareto distribution plays central role (see [17]).

Extremal types theorem (see [18]) and Peak over threshold theorem ([15,16]) facilitate a theoretical background to use generalized extreme value (GEV) distributions and GP distribution in modeling extreme movement of stock market indices. A number of researchers verified empirically that these models give sufficient fit to model extreme volatility in stock market, see for ex. [19,20]. Also many researches utilizes these models for measuring extremal behavior of stock markets, see for ex. [4,21,22].

However, from 2004, [1] and many other researchers have been empirically showing that generalized logistic (GL) distribution is a better model than GEV and GP in modeling extremal behavior of different stock market data, this includes US, UK, Germany, Japan, India, Athens, African stock markets etc. See for eg. [1,23,24] etc. Also [25] empirically showed that GL is better than GEV to model extreme movements in the stock, commodities and bond markets.

In this paper we show some theoretical motivation of this claim, that is, we present a theoretical framework of the role of GL distribution in extreme value modeling. In Section 2, we define logistic distribution and some of the known results of the logistic distribution which are important in extreme value theory. We also define generalized logistic distribution in this section. Section 3 introduces some of the notable properties of GL distribution, namely, tale equivalence with GEV and GP distributions and stability property w.r.t geometric distribution. We prove a general multivariate limit theorem in Section 4, and show multivariate central limit theorem, multivariate extremal types theorem and multivariate random sum convergence theorem are special cases of this theorem. In Section 5, we use the above general limit theorem to prove the convergence of random maxima and random minima to GL distribution. For an additional support to our claim, we present a data analysis in Section 6. We introduce a multivariate generalized logistic distribution in Section 7, and also we prove a characteristic property of this multivariate distribution by using the general multivariate theorem in Section 4.

To prove the results we require some basic concepts which we discuss below.

**Definition 1.6** The right end point and left end point of a d.f. \( F \), denoted by \( x_r \) and \( y_r \) respectively, are

\[
x_r = \sup \{ x: F(x) < 1 \}, \quad y_r = \inf \{ x: F(x) > 0 \}.
\]

**Definition 1.7** Two distributions \( F \) and \( G \) are equivalent in their right tail if they have the same right end point, i.e. \( x_r = x_g \), and

\[
\lim_{x \to y_r} \frac{1 - F(x)}{1 - G(x)} = 1.
\]

**Definition 1.8** Two distributions \( F \) and \( G \) are equivalent in their left tail if they have the same left end point, i.e. \( y_r = y_g \), and

\[
\lim_{x \to y_r} \frac{F(x)}{G(x)} = 1.
\]

For more details see [26]. Next, we introduce the max-stability w.r.t. a discrete distribution.

**Definition 1.9** (see [27]) Let \( F \) be a non-degenerate distribution function of a random variable \( X \) and \( N \) be a discrete random variable defined on set of positive integers with probability mass function \( \{ p_n \} \). That is,

\[
P\{ N = n \} = p_n, \quad n = 1, 2, 3, \ldots.
\]

Then \( F \) is said to be max-stable w.r.t. \( \{ p_n \} \) (or r. v. \( X \) is said to be maximum stable w.r.t. a r. v. \( N \) ) if there exist \( a_n > 0 \) and \( b_n \) such that

\[
\max \left( X_1, X_2, \ldots, X_n \right) - b_n \overset{d}{=} X
\]

where \( X_n, n \geq 1 \) are same copies of \( X \).

Similarly, one can define min-stability w.r.t. a discrete distribution.

### 2. Review of Logistic and Generalized Logistic Distribution

Logistic distribution is an important distribution used in statistical modeling. It is used for modeling in a number of research papers (see [28]). In literature, Logistic distri-
bution plays some important role in modeling of extremes of data. In this section, first, we define Logistic distribution and then discuss its importance in extreme value theory.

**Definition 2.1** A random variable $X$ is said to follow standard logistic distribution if its d.f is given by

$$F_X(x) = \frac{1}{1 + e^{-x}} \quad -\infty < x < \infty. \quad (2.1)$$

The following are some important results which connects logistic distribution and extreme value theory.

**Result 2.1** ([27]): Let $\{X_n, n \geq 1\}$ be a sequence of i.i.d.r.v.s with symmetric distribution function $F(.)$. Let $N$ be an integer valued random variable independent of $\{X_n\}$ and

$$P(N = k) = p(1 - p)^{k-1}, 0 < p < 1, \; k \geq 1. \quad (2.2)$$

Let $M_n = \max(X_1, X_2, \ldots, X_N)$ and there exist constants $a_n$ and $b_n$ such that

$$\frac{M_n - a_n}{b_n} = X_i$$

iff $F$ is the logistic distribution function.

The logistic distribution appears as a limiting distributions as described in the following result.

**Result 2.2** (see [28]): Let $\{X_n, n \geq 1\}$ be a sequence of independent and identically distributed random variables with distribution function $F(.)$. Let $N$ be an integer valued random variable which are not necessarily independent of $\{X_n\}$. Assume $F$ is in the domain of attraction of Gumbel distribution and

$$\lim_{N \rightarrow \infty} P(N \leq nz) = A(z), \quad z > 0,$$

where $A(z)$ is a proper distribution function. Then the limit distribution of $M_n$ is logistic iff

$$A(z) = 1 - \exp\{-az\}, a > 0.$$

The next result brings the connection between logistic distribution and the extreme value theory through midrange.

**Result 2.3** (see [28]): Let $\{X_n, n = 1, 2, \ldots\}$ be a sequence of independent and identically distributed random variables with $X_i$ follows $F(.)$. Let $M_n = \max(X_1, X_2, \ldots, X_n)$ and $m_n = \min(X_1, X_2, \ldots, X_n)$. Assume $F$ is symmetric distribution which belongs to the domain of attraction of Gumbel distribution then under proper normalization the midrange

$$\eta_n = \frac{m_n + M_n}{2}$$

converges to the random variable $Z$ which follows standard logistic distribution given in Definition 2.1.

In statistics literature, there are several ways of generalizing the logistic distribution (for more details see [29]). Among the various generalization of logistic distribution, the one given by Hosking (see [30]) is called the 5th generalized logistic distribution ([29]). This form of generalized logistic distribution is used for many real life applications, see for example [1,23,24,30,31]. Motivated by this we introduce the 5th generalized logistic distribution and call this generalization of logistic distribution as generalized logistic distribution.

**Definition 2.2** A random variable $X$ is said to follow the generalized logistic (GL) distribution if its distribution function is given by,

$$F_X(x) = \begin{cases} 
1 & \text{if } k \neq 0 \\
1 & \text{if } k = 0 
\end{cases}$$

and the supports are

$$\begin{align*}
&\begin{cases} 
&x > k^{-1} \quad \text{for } k < 0 \\
&x < k^{-1} \quad \text{for } k > 0 \\
&x \in R \quad \text{for } k = 0.
\end{cases}
\end{align*}$$

The parameter $k$ is known as the shape parameter of the distribution and $k \in R$. One can introduce the related location-scale family by replacing the argument $x$ above by $\frac{x - \mu}{\sigma}$ for $\mu \in R$ and $\sigma > 0$. For $k = 0$, $F_X$ can be identified as the logistic distribution. For $k > 0$, and some scale transform, we get loglogistic distribution as given in [27]. Similarly for $k < 0$, through some scale transform we get backward loglogistic distribution. The statistical properties and estimation issues of the GL distribution are discussed in [29].

3. Some Notable Properties of GL Distribution

In this section we prove some characters of GL distribution which are important to extreme value theory. We study the tail behavior of GL distribution compared to other distributions. Also, as we see in GEV and GP distributions, we prove GL distribution is also characterized by a stable property.

3.1. Tail Equivalence of GL, GEV and GP

In this subsection, we compare tail distribution of GL with GEV(max), GP and GEV(min). Figures 1 and 2 gives the probability density functions and distribution functions of GL, GEV(max), GP and GEV(min) for $k = 0$ respectively. Figures 1 and 2 indicate that the right tails of the GEV(max), GP and GL distributions are similar and GEV(min) and GL are similar in left tails. This clearly indicates that these three distributions are asymptotically
equivalent in their tails, which we prove in the following theorems.

**Theorem 3.1** The distributions \( \text{GEV}(\max) \), \( \text{GP} \) and \( \text{GL} \) are equivalent at their right tails. The distributions \( \text{GEV}(\min) \) and \( \text{GL} \) are equivalent at their left tails.

### 3.2. Max-Stability and Min-Stability w.r.t. Geometric Distribution

From Result 2.1, the logistic distribution is characterized by max-stability property. Here we prove the property still remains with this generalization. Below theorem show that the GL distribution also characterized by max-stability and min-stability w.r.t geometric distribution.

**Theorem 3.2** The generalized logistic distribution given in Definition 2.2 characterizes max-stability w.r.t geometric distribution. That is, let \( X_1, X_2, \ldots \) be a sequence of i.i.d random variable follows GL distribution if and only if there exist real numbers \( a_n > 0 \) and \( b_n \) such that,

\[
\max(X_1, X_2, \ldots, X_N) - b_n \xrightarrow{a_n} X
\]

where \( N \) is a discrete random variable follows geometric distribution. Similarly, the result is true for minimum.

Hence GL satisfies the stability property. In the next Section we prove a theorem which gives a direct relation between stability property and limit distribution of a general class of functions. We use this theorem to prove a limit theorem in extreme value theory where GL plays the central role.

### 4. A General Multivariate Limit Theorem

Here we prove a limit theorem of general functions of independent identically distributed continuous multivariate random variables (i.i.d.c.m.r.v) which posses property \( Q \) (see Definition 4.1). Let \( g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta) \) be a Borel-measurable function of \( \tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta \), which is continuous. We use the multivariate norming function as \( \tilde{a}_\eta \tilde{x} + \tilde{b}_\eta = (a_{1,\eta} X_1 + b_{1,\eta}, a_{2,\eta} X_2 + b_{2,\eta}, \ldots, a_{p,\eta} X_p + b_{p,\eta}) \).

Below we define a property \( Q \) of a Borel-measurable function.

**Definition 4.1** Let \( g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta) \) be a Borel-measurable function then \( g \) satisfies property \( Q \) if,

\[
g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta) = g\left(g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta), g(\tilde{X}_{\eta+1}, \tilde{X}_{\eta+2}, \ldots, \tilde{X}_{2\eta}), \ldots, g(\tilde{X}_{(\eta-1)\eta+1}, \tilde{X}_{(\eta-1)\eta+2}, \ldots, \tilde{X}_{\eta^2})\right)
\]

where \( \eta, \eta_1 \) and \( \eta_2 \) are integer valued random variables or integers such that \( P[\eta = \eta_1 + \eta_2] = 1 \).

The functions \( \sum_{i=1}^\eta \tilde{X}_i, \max(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta), \prod_{i=1}^\eta \tilde{X}_i \) are some of the important examples of functions which satisfy Property \( Q \). By \( \max(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta) \) we mean the coordinate wise maximum. These functions with random sample size also satisfy Property \( Q \), for more details see [32].

**Theorem 4.1** Let \( \{\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta\} \) be a Borel-measurable function and \( g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta) \) be a Borel-measurable function such that \( g \) satisfies property \( Q \), and \( \eta \) is independent of each \( \tilde{X}_i \). Let \( \bar{Y} \) be a non-degenerate r.v. Then there exists sequences \( \{\tilde{f}_\eta\} \) and \( \{\tilde{e}_\eta\} \) such that

\[
F_{g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_\eta)}(\tilde{f}_\eta \bar{X} + \tilde{e}_\eta) \xrightarrow{w} F_{\bar{Y}}(\bar{X})
\]

iff \( Y \) satisfies the following equation.
4.1 Multivariate Version of Generalized Central Limit Theorem as a Special Case

Let \( \eta = n \) and \( g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_n) = \sum_{i=1}^{n} \tilde{X}_i \), then \( g \) satisfies property \( Q \) as described in Definition (4.1). Let \( X \) be the class of random variables which follows multivariate stable distributions. Then for all \( \tilde{X} \in X \) there exist a sequence \( \{\tilde{a}_n > 0\} \) and \( \{\tilde{b}_n\} \) such that, for each \( n \),

\[
F_{\sum_{i=1}^{n} \tilde{X}_i} (\tilde{a}_n \tilde{x} + \tilde{b}_n) = F_{\tilde{X}_i} (\tilde{x}), \forall \tilde{x} \in \mathbb{R} \text{ and } \forall \text{ values of } \eta
\]

for some sequences \( \{\tilde{a}_n > 0\} \) and \( \{\tilde{b}_n\} \), where \( \tilde{X}_i \) are same copies of \( X \).

Many important limit theorems in probability can be deduced as a special cases of Theorem 4.1, which includes multivariate central limit theorem, multivariate extremal types theorem and Random Sum Convergence theorem, which we show in the following subsections.

4.2 Multivariate Extremal Types Theorem as a Special Case

Let \( \eta = n \) and \( g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_n) = \max (\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_n) \), then \( g \) satisfies property \( Q \). Let \( X \) be the class of random variables which follows multivariate extreme value distributions with characteristic property,

\[
\left[ F_{\tilde{X}_i} (a_n \tilde{x} + b_n) \right]^n = F_{\tilde{X}_i} (\tilde{x}), \forall \tilde{x} \in \mathbb{R} \text{ and } \forall n \in N
\]

where \( \tilde{X}_i \) are same copies of \( X \). Let \( \{\tilde{Y}_n, n \geq 1\} \) be a sequence of i.i.d.c.r.v’s and \( \tilde{Z} \) be a non-degenerate r.v. Then there exist \( \{\tilde{c}_n > 0\} \) and \( \{\tilde{d}_n\} \) such that

\[
F_{\max(\tilde{Y}_1, \tilde{Y}_2, \ldots, \tilde{Y}_n)} (c_n \tilde{x} + d_n) \xrightarrow{w} F_{\tilde{Z}} (\tilde{x})
\]

iff \( \tilde{Z} \in X \).

4.3 Random Sum Convergence as a Special Case

Let \( \eta = N \), a r.v and \( g(\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_n) = \sum_{i=1}^{N} \tilde{X}_i \), then \( g \) satisfies property \( Q \). Let \( X \) be the class of random variables which follows multivariate strictly geometric stable distribution. Then for all \( X \in X \) there exist constants \( \{\tilde{a}_n > 0\} \) and \( \{\tilde{b}_n\} \) such that, for each \( n \),

\[
F_{\sum_{i=1}^{N} \tilde{X}_i} (\tilde{a}_n \tilde{x} + \tilde{b}_n) = F_{\tilde{X}_i} (\tilde{x}), \forall \tilde{x} \in \mathbb{R}^d
\]

where \( \tilde{X}_i \) are same copies of \( X \), see [33,34]. Let \( \{\tilde{Y}_n, n \geq 1\} \) be an i.i.d sequence of r.v’s and \( \tilde{Z} \) be a non-degenerate r.v. Then there exist \( \{\tilde{c}_n > 0\} \) and \( \{\tilde{m}_n\} \) such that

\[
F_{\sum_{i=1}^{N} \tilde{Y}_i} (\tilde{c}_n \tilde{x} + \tilde{m}_n) \xrightarrow{w} F_{\tilde{Z}} (\tilde{x})
\]

iff \( \tilde{Z} \in X \).

5. GL as a Limit Distribution of Random Maxima and Minima

The limit theory of random maxima and random minima has been studied by many authors (see for ex. [35]). In this section we derive generalized logistic distribution as the limit of random maxima and random minima when sample size follows geometric distribution using Theorem 3.2 and 4.1.

**Theorem 5.1** Let \( \{X_i, n \geq 1\} \) be a sequence of i.i.d.c.r.v. Let \( M_N = \max(X_1, X_2, \ldots, X_N) \), \( m_n = \min(X_1, X_2, \ldots, X_n) \), and \( N \) is an integer variable which follows geometric distribution, independent of \( \{X_i\} \). Also let \( Y \) and \( Z \) be random variables with non-degenerate distribution functions \( G \) and \( H \) respectively, \( a_n > 0, b_n, c_n > 0 \) and \( d_n \) such that,

\[
\frac{M_N - a_N}{b_n} \xrightarrow{d} Y
\]

and

\[
\frac{m_n - c_n}{d_n} \xrightarrow{d} Z.
\]

Then

\[
G(x) = \begin{cases} 
1 & \text{if } k \neq 0 \\
1 + \left(1 - k \left(\frac{x - \mu}{\sigma}\right)\right)^{\frac{1}{k}} & \text{if } k = 0.
\end{cases}
\]

with supports are

\[
\begin{align*}
x > \mu + \sigma k^{-1} & \text{ for } k < 0 \\
x < \mu + \sigma k^{-1} & \text{ for } k > 0 \\
x \in \mathbb{R} & \text{ for } k = 0.
\end{align*}
\]

also \( H \) has the same distributional form of \( G \) with different parameters.

**Proof:** The proof consist of two parts. First, from Theorem 3.2, it is verified that GL posses characterizing property of max-stability and min-stability w.r.t geometric distribution. By using Theorem 4.1, where \( p = 1, \)
the random maxima and random minimum, when sample size follows geometric distribution, converge to the GL distribution, if it exists.

Theorem 5 identifies the limit distribution of geometric random maxima and geometric random minima, if it exists, as the GL distribution given in Section 2.2. That is, GL distribution can be used as an asymptotic model for maximum and minimum of a random number \( N \) of random variables, when \( N \) follows geometric distribution. Notably, unlike of GEV(max), GEV(min), and GP, GL distribution provides the theory for both maxima and minima. This is an alternative model for maxima and minima. The theory is parallel to generalized extreme value model and generalized Pareto model in the sense that the three models includes three important distributions which is decided by the shape parameter. Also tail of these models are asymptotically equivalent and three models have a characterizing stability property in different sense. Moreover, the three models can be considered as the limit distribution of extremes in different situations. These results justify the theoretical importance of the empirical findings, that GL can be a suitable model over GEV model for extremes of share market data, see for example [1,25,26]. Many papers also show that GL distribution provides an adequate distribution in hydrological application, for eg. [30,31] etc.

**Remark 5.1** It is also be noted that this theorem is somewhat similar to geometric stable theorem in the theory of partial sum of random variables where geometric stable (GS) distribution plays a central role. GS distribution is widely using in stock market modeling, and GS can be viewed as the weak limit distribution of sum of random number of random variables, whose random number follows geometric distribution.

### 6. Goodness of Fit Test for the BSE Data

In this section, we empirically study the performance of GL and GEV in modeling the behavior of minimum returns of Bombay stock exchange data. We use Anderson-Darling test for comparing goodness of fit of GEV and GL distributions in the extremal behavior of the data. Since the test is based on empirical distribution function (EDF) and among all the well known tests based on EDF, Anderson-Darling test has the highest power in testing normality against a number of alternatives when the parameters are unknown [36].

**Table 1. Performance of GEV(min) and GL distribution for weekly minimum data.**

<table>
<thead>
<tr>
<th>Intervals</th>
<th>n</th>
<th>GEVmin loca</th>
<th>scale</th>
<th>shape</th>
<th>p</th>
<th>GL loca</th>
<th>scale</th>
<th>shape</th>
<th>p</th>
<th>Best fit</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>78</td>
<td>0.006</td>
<td>0.006</td>
<td>0.226</td>
<td>0.396</td>
<td>-0.009</td>
<td>0.005</td>
<td>0.324</td>
<td>0.465</td>
<td>GL</td>
</tr>
<tr>
<td>2</td>
<td>78</td>
<td>0.004</td>
<td>0.007</td>
<td>0.270</td>
<td>0.000</td>
<td>-0.007</td>
<td>0.005</td>
<td>0.356</td>
<td>0.000</td>
<td>GL</td>
</tr>
<tr>
<td>3</td>
<td>78</td>
<td>0.014</td>
<td>0.011</td>
<td>-0.107</td>
<td>0.112</td>
<td>-0.019</td>
<td>0.007</td>
<td>0.103</td>
<td>0.869</td>
<td>GL</td>
</tr>
<tr>
<td>4</td>
<td>78</td>
<td>0.012</td>
<td>0.009</td>
<td>-0.207</td>
<td>0.672</td>
<td>-0.016</td>
<td>0.006</td>
<td>0.044</td>
<td>0.95</td>
<td>GL</td>
</tr>
<tr>
<td>5</td>
<td>78</td>
<td>0.010</td>
<td>0.012</td>
<td>0.204</td>
<td>0.395</td>
<td>-0.015</td>
<td>0.009</td>
<td>0.308</td>
<td>0.225</td>
<td>GEVmin</td>
</tr>
<tr>
<td>6</td>
<td>78</td>
<td>0.017</td>
<td>0.014</td>
<td>0.135</td>
<td>0.599</td>
<td>-0.023</td>
<td>0.010</td>
<td>0.26</td>
<td>0.938</td>
<td>GL</td>
</tr>
<tr>
<td>7</td>
<td>78</td>
<td>0.010</td>
<td>0.0082</td>
<td>-0.101</td>
<td>0.031</td>
<td>-0.014</td>
<td>0.005</td>
<td>0.106</td>
<td>0.152</td>
<td>GL</td>
</tr>
<tr>
<td>8</td>
<td>78</td>
<td>0.011</td>
<td>0.009</td>
<td>-0.235</td>
<td>0.176</td>
<td>-0.015</td>
<td>0.005</td>
<td>0.027</td>
<td>0.219</td>
<td>GL</td>
</tr>
<tr>
<td>9</td>
<td>78</td>
<td>0.010</td>
<td>0.011</td>
<td>0.071</td>
<td>0.701</td>
<td>-0.015</td>
<td>0.007</td>
<td>0.217</td>
<td>0.932</td>
<td>GL</td>
</tr>
<tr>
<td>10</td>
<td>78</td>
<td>0.013</td>
<td>0.011</td>
<td>0.012</td>
<td>0.052</td>
<td>-0.017</td>
<td>0.007</td>
<td>0.178</td>
<td>0.58</td>
<td>GL</td>
</tr>
<tr>
<td>11</td>
<td>78</td>
<td>0.015</td>
<td>0.014</td>
<td>0.0113</td>
<td>0.541</td>
<td>-0.021</td>
<td>0.009</td>
<td>0.177</td>
<td>0.254</td>
<td>GEVmin</td>
</tr>
<tr>
<td>12</td>
<td>78</td>
<td>0.008</td>
<td>0.007</td>
<td>0.090</td>
<td>0.009</td>
<td>-0.011</td>
<td>0.005</td>
<td>0.229</td>
<td>0.125</td>
<td>GL</td>
</tr>
<tr>
<td>13</td>
<td>78</td>
<td>0.008</td>
<td>0.008</td>
<td>0.183</td>
<td>0.107</td>
<td>-0.012</td>
<td>0.006</td>
<td>0.293</td>
<td>0.348</td>
<td>GL</td>
</tr>
<tr>
<td>14</td>
<td>78</td>
<td>0.006</td>
<td>0.007</td>
<td>-0.036</td>
<td>0.401</td>
<td>-0.019</td>
<td>0.006</td>
<td>0.293</td>
<td>0.494</td>
<td>GL</td>
</tr>
<tr>
<td>15</td>
<td>88</td>
<td>0.009</td>
<td>0.0117</td>
<td>0.117</td>
<td>0.003</td>
<td>-0.013</td>
<td>0.008</td>
<td>0.242</td>
<td>0.00</td>
<td>GEVmin</td>
</tr>
</tbody>
</table>
Table 2. Performance of GEV(min) and GL distribution for monthly minimum data.

<table>
<thead>
<tr>
<th>Intervals</th>
<th>n</th>
<th>Loca</th>
<th>Scale</th>
<th>Shape</th>
<th>p</th>
<th>Loca</th>
<th>Scale</th>
<th>Shape</th>
<th>p</th>
<th>Best Fit</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>26</td>
<td>0.015</td>
<td>0.006</td>
<td>0.323</td>
<td>0.324</td>
<td>−0.018</td>
<td>0.005</td>
<td>0.396</td>
<td>0.206</td>
<td>GEVmin</td>
</tr>
<tr>
<td>2</td>
<td>26</td>
<td>0.024</td>
<td>0.015</td>
<td>−0.060</td>
<td>0.708</td>
<td>−0.03</td>
<td>0.01</td>
<td>0.132</td>
<td>0.511</td>
<td>GEVmin</td>
</tr>
<tr>
<td>3</td>
<td>26</td>
<td>0.025</td>
<td>0.007</td>
<td>−0.153</td>
<td>0.255</td>
<td>−0.027</td>
<td>0.004</td>
<td>0.075</td>
<td>0.525</td>
<td>GL</td>
</tr>
<tr>
<td>4</td>
<td>26</td>
<td>0.034</td>
<td>0.020</td>
<td>0.137</td>
<td>0.551</td>
<td>−0.043</td>
<td>0.015</td>
<td>0.261</td>
<td>0.517</td>
<td>GEVmin</td>
</tr>
<tr>
<td>5</td>
<td>26</td>
<td>0.020</td>
<td>0.008</td>
<td>−0.054</td>
<td>0.419</td>
<td>−0.023</td>
<td>0.005</td>
<td>0.135</td>
<td>0.350</td>
<td>GEVmin</td>
</tr>
<tr>
<td>6</td>
<td>26</td>
<td>0.024</td>
<td>0.009</td>
<td>0.141</td>
<td>0.208</td>
<td>−0.027</td>
<td>0.006</td>
<td>0.264</td>
<td>0.339</td>
<td>GL</td>
</tr>
<tr>
<td>7</td>
<td>26</td>
<td>0.027</td>
<td>0.012</td>
<td>0.156</td>
<td>0.257</td>
<td>−0.032</td>
<td>0.009</td>
<td>0.274</td>
<td>0.258</td>
<td>GL</td>
</tr>
<tr>
<td>8</td>
<td>26</td>
<td>0.023</td>
<td>0.012</td>
<td>0.051</td>
<td>0.593</td>
<td>−0.028</td>
<td>0.008</td>
<td>0.204</td>
<td>0.625</td>
<td>GL</td>
</tr>
<tr>
<td>9</td>
<td>26</td>
<td>0.015</td>
<td>0.006</td>
<td>0.467</td>
<td>0.049</td>
<td>−0.018</td>
<td>0.005</td>
<td>0.507</td>
<td>0.122</td>
<td>GL</td>
</tr>
<tr>
<td>10</td>
<td>35</td>
<td>0.019</td>
<td>0.013</td>
<td>−0.081</td>
<td>0.695</td>
<td>−0.023</td>
<td>0.007</td>
<td>0.256</td>
<td>0.886</td>
<td>GL</td>
</tr>
</tbody>
</table>

Table 3. Performance of GEV(min) and GL distribution for quarterly minimum data. *Indicates neither distribution fit the data.

<table>
<thead>
<tr>
<th>Intervals</th>
<th>n</th>
<th>Loca</th>
<th>Scale</th>
<th>Shape</th>
<th>p</th>
<th>Loca</th>
<th>Scale</th>
<th>Shape</th>
<th>p</th>
<th>Best Fit</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>22</td>
<td>0.029</td>
<td>0.015</td>
<td>−0.074</td>
<td>0.419</td>
<td>−0.035</td>
<td>0.01</td>
<td>0.123</td>
<td>0.529</td>
<td>GL</td>
</tr>
<tr>
<td>2</td>
<td>22</td>
<td>0.034</td>
<td>0.015</td>
<td>0.3072</td>
<td>0.103</td>
<td>−0.04</td>
<td>0.012</td>
<td>0.383</td>
<td>0.186</td>
<td>GL</td>
</tr>
<tr>
<td>3</td>
<td>22</td>
<td>0.039</td>
<td>0.018</td>
<td>−0.073</td>
<td>0.054</td>
<td>−0.046</td>
<td>0.011</td>
<td>0.124</td>
<td>0.052</td>
<td>GEVmin</td>
</tr>
<tr>
<td>4</td>
<td>24</td>
<td>0.0252</td>
<td>0.010</td>
<td>0.263</td>
<td>0.01</td>
<td>−0.029</td>
<td>0.008</td>
<td>0.350</td>
<td>0.028</td>
<td>GL*</td>
</tr>
</tbody>
</table>

GL gives a good model in three out of four intervals, which shows both distribution can be used to model quarterly data and comparing these distributions GL is a better model.

On analysis of half yearly data, Table 4 clearly shows GL provides a good fit comparing to GEV(min). Finally, Table 5 illustrates GL provides a better for yearly minimum data compared to GEV(min). Both distribution fit for the data at 0.05 level.

The above analysis reveals that for analyzing the minimum returns in stock market data, GL provides a better fit than GEV distributions, which shows minimum behaves like a geometric minimum than the usual minimum in stock market data (for more details see [37]).

7. Multivariate Generalized Logistic Distribution and a Characterization Property

In Section 5, we identified that GL distribution is also a suitable model for extremes, moreover it plays better model than GEV in some situations. We also proved that the above theorem is parallel to the existing extremal types theorem and peak over threshold theorem. Naturally, one can think a multivariate version of GL distribution as parallel to the theory of multivariate extreme value distribution.

**Definition 7.1** Let \( \{\tilde{X}_n = (X_{1,n}, X_{2,n}, \ldots, X_{p,n}) \} \) \( n \geq 1 \) be a sequence of i.i.d.c.m.r.v and let \( M_N = \max (\tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_N) \), where \( N \) is random variable follows geometric distribution. Let \( \tilde{a}_n > 0 \) and \( \tilde{b}_n \) are \( p \)-dimensional real sequences such that

\[
\tilde{a}_N \tilde{x} + \tilde{b}_N = (a_{1,N} x_1 + b_{1,N}, a_{2,N} x_2 + b_{2,N}, \ldots, a_{p,N} x_p + b_{p,N})
\]

Suppose the following convergence occur,

\[
F_{M_N} (\tilde{a}_N \tilde{x} + \tilde{b}_N) \xrightarrow{w} G
\]

Then we called \( G \) as multivariate generalized logistic (MGL) distribution and \( F_{\tilde{X}_i} \in D(G) \), where \( D(G) \) is the domain of attraction of \( G \).

Notice that, the univariate margins of \( G \) must be a generalized logistic distribution, this includes all three types of the marginal distribution: \( k = 0 \), \( k > 0 \) and \( k < 0 \) correspond respectively to the logistic, loglogistic and backward loglogistic distributions. Below we prove a characterizing property of MGL distribution.

**Theorem 7.1** The MGL distribution is characterized by max-stability w.r.t geometric distribution. That is, let \( N \) be a random variable follows geometric distribution.
Table 4. Performance of GEV(min) and GL distribution for half yearly minimum data.

<table>
<thead>
<tr>
<th>Intervals</th>
<th>n</th>
<th>GEVmin</th>
<th>GL</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Loca</td>
<td>Scale</td>
</tr>
<tr>
<td>1</td>
<td>23</td>
<td>0.038</td>
<td>0.019</td>
</tr>
<tr>
<td>2</td>
<td>23</td>
<td>0.040</td>
<td>0.019</td>
</tr>
</tbody>
</table>

Table 5. Performance of GEV(min) and GL distribution for yearly minimum data.

<table>
<thead>
<tr>
<th>Intervals</th>
<th>n</th>
<th>GEVmin</th>
<th>GL</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Loca</td>
<td>Scale</td>
</tr>
<tr>
<td>1</td>
<td>23</td>
<td>0.049</td>
<td>0.023</td>
</tr>
</tbody>
</table>

let \( \{\bar{X}_n = (X_{1,n}, X_{2,n}, \ldots, X_{p,n})\}, n \geq 1 \) be a sequence of i.i.d.c.m.r.v which follows MGL distribution iff there exist \( a_n > 0 \) and \( b_n \) are p-dimensional real sequences such that

\[
\tilde{a}_n \bar{x} + \tilde{b}_n = (a_{1,n} X_{1,n} + h_{1,n}, a_{2,n} X_{2,n} + b_{2,n}, \ldots, a_{p,n} X_{p,n} + b_{p,n})
\]

and,

\[
F_n(\tilde{a}_n \bar{x} + \tilde{b}_n) = F_n(\tilde{\bar{x}})
\]

Proof. The result is directly from Theorem 4.1.

7.1. Proof of Theorem 3.1

Since the proof contains only simple calculation, we only give proof for tail equivalence of GEV(max) and GP. We use notations \( G \) and \( F \) for distribution functions of GEV(max) and GL respectively.

As per the assumed notation for the distributions of GEV(max) and GL, to prove the asymptotic equivalence of their right tails, by Definition 1.7, it is enough to prove that \( x_G = x_F = \infty \) and

\[
\lim_{x \to \infty} \frac{1 - G(x)}{1 - F(x)} = 1, \quad \forall \eta \in \mathbb{R}.
\]

We prove this in the following three cases.

Case 1 \([\eta = 0]\). Here \( x_G = x_F = \infty \),

\[
\lim_{x \to \infty} \frac{1 - G(x)}{1 - F(x)} = \lim_{x \to \infty} \frac{1 - \exp\{-\exp(-x)\}}{1 - \exp(-x)} = 0
\]

This is \( 0 \) form. So applying L-Hospital’s rule we get,

\[
\lim_{x \to \infty} \frac{d}{dx} \left[ \frac{1 - G(x)}{1 - F(x)} \right] = \lim_{x \to \infty} \frac{d}{dx} \left[ \frac{1 - \exp\{-\exp(-x)\}}{1 - \exp(-x)} \right] = 1
\]
7.2. Proof of Theorem 3.2
To prove the max-stability of GL, we use the following lemma from [27].

Lemma B.1 Let \( F_x \) be a non-degenerate distribution function of a r.v. \( X \) which is maximum stable w.r.t \( \{ p_n, n \geq 1 \} \). If \( y_n = -\infty, x_p = \infty \), and for any real constant \( c \), and d.f's \( H_1 \) and \( H_2 \) defined by 
\[
F_x (x) = H_1 (c + \exp(x)) \quad \text{and} \quad F_x (x) = H_2 (c - \exp(-x)) \] 
for all real \( x \), then \( H_1 \) and \( H_2 \) are non-degenerate and maximum stable w.r.t \( \{ p_n, n \geq 1 \} \) with \( y_{H_1} = c \) and \( x_{H_2} = c \) respectively.

For detailed discussion see [27]. Below we prove Theorem 3.2.

Proof. Let \( F_x \) be the distribution function of generalized logistic distribution with \( k < 0 \), and location and scale parameters \( \gamma \) and \( \xi \) respectively. That is,
\[
F_x (x) = \frac{1}{1 + \left( \frac{k}{\xi} \right)^{1/k}} \exp \left( \frac{\gamma x}{\xi} \right), -\infty < x < \infty.
\]

Now take the transformation \( x_{H_1} + \exp(x) \), we get,
\[
F_x [x_{H_1} + \exp(x)] = \frac{1}{1 + \left( \frac{k}{\xi} \right)^{1/k}} \exp \left( \frac{\gamma x}{\xi} \right), -\infty < x < \infty
\]
which is the distribution function of Logistic distribution (see [27]). That is, \( F_x [x_{H_1} + \exp(x)] \) is logistic distribution function and by Lemma (B.1), the distribution function \( F_x \) is max-stable w.r.t geometric distribution. Similarly, for \( k > 0 \), the same proof works. That is, GL distribution satisfies max-stability w.r.t geometric distribution. To prove that GL is the only distribution with property of max-stability, let \( X \) be a random variable which follows GL distribution with shape parameter \( k \).

Now take the transformation
\[
Y = \begin{cases} \frac{X - \xi}{m} & \text{if } m \neq 0 \\ X & \text{if } m = 0 \end{cases}
\]

then for \( k > 0 \), \( Y \) follows loglogistic distribution with distribution function
\[
F_Y (y) = \begin{cases} 0 & \text{if } y \leq \gamma \\ 1 + \left( \frac{y - \gamma}{b} \right)^{-c} & \text{if } y > \gamma \end{cases}
\]

where \( b = \frac{\xi}{k} \) and \( c = \frac{1}{k} \). For \( k < 0 \), \( Y \) follows backward loglogistic distribution. By [27], we know that the class containing logistic, loglogistic and backward loglogistic has the characterizing property max-stability w.r.t to geometric distribution. The relation (B.1) is one to one implies the max-stability property w.r.t to geometric distribution characterize generalized logistic distribution. Similarly we can prove that min-stability characterizes GL distribution w.r.t geometric distribution.

Remark B.1 In the above proof, we give short steps mainly using Voorn’s idea (see [27]). One can directly prove the theorem.

7.3. Proof of Theorem 4.1
Let \( \{ \tilde{X}, \tilde{X}_n, n \geq 1 \} \) be a sequence of independent and identically distributed continues multivariate random variables (i.i.d.c.m.r.v) defined on some probability space \( \Omega, \mathcal{F}, P \). We use symbols \( \eta \), \( \tau \) and \( \kappa \) to denote both non random integer and integer valued random variable, particularly, we write \( n \) when we consider non random integer and \( N \), depends on some parameter \( p \), for integer valued random variable. When \( \eta = n \), non-random, then \( \eta \rightarrow \infty \) may be interpreted as \( n \rightarrow \infty \). To prove the theorem we need the following \( T_\eta \) function in multivariate case.

Definition C.1 Let \( \{ \tilde{X}, \tilde{X}_n, n \geq 1 \} \) be a sequence of i.i.d.c.m.r.v with \( F_\gamma \) represents distribution function of \( \tilde{Y} \) and \( g \) be a given Borel function. Define,
\[
D_\eta = \{(\tilde{X}, \eta) \mid \tilde{X} \in \mathbb{R}^n, \eta = F_\gamma (\tilde{X})\},
\]
and for every value of \( m \), where \( m \) is a positive integer, we get
\[
D_m = \{(\tilde{X}, z) \mid \tilde{X} \in \mathbb{R}^n, z = g(\tilde{X})\}.
\]

Also the cardinality of \( D_\eta \) and \( D_m \) are same. Let \( M_\eta \) be a sequence of class of functions such that,
\[
M_\eta = \{ f \mid D_\eta \rightarrow D_m \text{ and } f \text{ is a bijection} \}.
\]

Then for every value of \( \eta = m \), \( \exists \ a \ T_{\eta-m} \in M_\eta \) such that,
\[
(\tilde{X}, F_{\gamma}(\tilde{X})) = T_{\eta-m}(\tilde{X}, F_{\gamma}(\tilde{X})), \quad \forall \ \tilde{X} \in \mathbb{R}.
\]

Below we give a simple example of the above \( T_\eta \) function.

Example C.1 Let \( \{ \tilde{X}, \tilde{X}_n, n \geq 1 \} \) be a sequence of i.i.d.c.m.r.v and \( g(\tilde{X}_1, \tilde{X}_2, \cdots, \tilde{X}_n) = \max(\tilde{X}_1, \tilde{X}_2, \cdots, \tilde{X}_n) \) is given. Then the function \( T_\eta \) is,
Remark C1 Let \( \{ \bar{a}_i > 0 \} \) and \( \{ \bar{b}_i \} \) be given sequences and let \( D_0 \) be the following form,

\[
D_0 = \{(x, y) | x \in \mathbb{R}, y = F_\xi(x) \},
\]

which implies,

\[
D_m = \{(x, z) | x \in \mathbb{R}, z = F_{\bar{a}_m, \bar{z}_m}(\bar{a}_m, \bar{b}_m) \}.
\]

also \( M_m \) and \( T_\eta \) can define accordingly.

In the following we prove Theorem 4.1.

Proof. Let \( G \) be a non-degenerate distribution function. Let \( \{ \bar{x}_n, n \geq 1 \} \) be a sequence of i.i.d.m.r.v such that \( \bar{x}_n \sim F_\xi \) (for notational convenience we use \( F_1 \) instead of \( F_{\bar{x}_1} \)) and define

\[
\Theta^\ast = \left\{ \{T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)) | x \in \mathbb{R}^d, T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)) \} \in \Theta^{\ast} \right\}
\]

with a metric \( d \) as

\[
d\left(T_m(x, H(\bar{a}_x, \bar{b}_y)), T_m(x, F_1(\bar{a}_x, \bar{b}_y)) \right) = \sup_{y} |y|,
\]

where \( y \) is from

\[
(\bar{y}, 0, y) = \left( T_m(x, H(\bar{a}_x, \bar{b}_y)) - T_m(x, F_1(\bar{a}_x, \bar{b}_y)) \right)
\]

and \( n, m \) are particular values of \( \eta \). It is easy to verify \( d \) follows metric conditions on \( \Theta^\ast \). We denote \( T_{m, \eta} \) for \( T_m(x, F_1(\bar{a}_x, \bar{b}_y)) \in \Theta^\ast \).

Next we define a relation \( M^\ast \) on \( \Theta^{\ast} \). That is, let \( \{ \bar{x}_n, n \geq 1 \}, \{ \bar{y}_n, n \geq 1 \} \) and \( \{ \bar{z}_n, n \geq 1 \} \) are three sequence of random variables each i.i.d. and \( \bar{x}_n \sim F_1 \), \( \bar{y}_n \sim F_2 \) and \( \bar{z}_n \sim F_3 \). Now let \( F_{1,2,m} \), and \( F_{2,1,m} \) are \( M^\ast \) related (denoted by \( F_{1,2,m} \sim F_{2,1,m} \)) if

\[
\lim d(T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)), T_\eta(x, F_2(\bar{a}_x, \bar{b}_y))) = 0. (C.3)
\]

Then below we show that the relation \( M^\ast \) is an equivalence relation on \( \Theta^{\ast} \). Let \( F_{1,2,\eta} \in \Theta^\ast \). Since

\[
\lim d(T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)), T_\eta(x, F_2(\bar{a}_x, \bar{b}_y))) = 0, \forall \bar{x}
\]

the relation is reflexive. Also let \( F_{1,2,\eta}, \) and \( F_{2,1,\eta} \in \Theta^{\ast} \) and \( F_{1,2,\eta} \sim F_{2,1,\eta} \). That is,

\[
\lim d(T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)), T_\eta(x, F_2(\bar{a}_x, \bar{b}_y))) = 0
\]

implies

\[
\lim d(T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)), T_\eta(x, F_2(\bar{a}_x, \bar{b}_y))) = 0
\]

or \( F_{2,1,\eta} \sim F_{1,2,\eta} \) so that the relation is symmetric. Now let \( F_{1,2,\eta}, F_{2,1,\eta} \) and \( F_{3,1,\eta} \in \Theta^{\ast} \), such that \( F_{1,2,\eta} \sim F_{2,1,\eta} \) and \( F_{2,1,\eta} \sim F_{3,1,\eta} \). That is,

\[
\lim d(T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)), T_\eta(x, F_2(\bar{a}_x, \bar{b}_y))) = 0
\]

and

\[
\lim d(T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)), T_\eta(x, F_2(\bar{a}_x, \bar{b}_y))) = 0
\]

Then,

\[
\lim d(T_\eta(x, F_1(\bar{a}_x, \bar{b}_y)), T_\eta(x, F_2(\bar{a}_x, \bar{b}_y))) = 0
\]

that is \( M^\ast \) is transitive.

So we have a partition on \( \Theta^{\ast} \) by the equivalence relation \( M^\ast \).

Now we show that \( T_{\eta}(x, F_1(\bar{x})) \) always exists and is a graph of a distribution function. Clearly for any \( x_n = -\infty, 1 \leq m \leq p \) then

\[
T_{\eta}^{-1}\left([x_1, x_2, \ldots, x_p], 0 \right) = \left([x_1, x_2, \ldots, x_p], 0 \right)
\]

and

\[
T_{\eta}^{-1}\left(\infty, \infty, \ldots, \infty, 0 \right) = \left(\infty, \infty, \ldots, \infty, 0 \right)
\]

Also \( T_{\eta} \) is one to one and onto function and each of its variable the function is monotone implies \( T_{\eta}^{-1} \) monotonically non decreasing for each of its variable and right continuous for each of its coordinates.

Then we prove the following equation,

\[
T_{\eta}(x, F_1(\bar{x})) = T_{\eta}T_{\eta}(x, F_1(\bar{x})) \forall x \text{ and } \forall \tau, \eta. \quad (C.4)
\]

Let \( \{ \bar{x}_n, n \geq 1 \} \) be i.i.d.m.r.v's and \( g(\bar{x}_1, \bar{x}_2, \ldots, \bar{x}_p) \) be a Borel measurable function. Now for \( i \geq 1 \), define

\[
U_i = g(\bar{x}_{(i-1)r+1}, \bar{x}_{(i-1)r+2}, \ldots, \bar{x}_{ir})
\]

then \( \{U_i, n \geq 1\} \) is also a sequence of i.i.d.m.r.v's. Let \( P\{\bar{x}_1 \leq \bar{x}\} = F_1(\bar{x}) \) and \( P\{\bar{U}_i \leq \bar{x}\} = H_i(\bar{x}) \). Then
\( \left( \bar{x}, P \left\{ g \left( \bar{U}_1, \bar{U}_2, \ldots, \bar{U}_n \right) \leq \bar{x} \right\} \right) = d_{\eta} (\bar{x}, H(\bar{x})). \)

which is same as,

\( \left( \bar{x}, P \left[ g \left( X_{11}, X_{22}, \ldots, X_{rr} \right), g \left( X_{r+1}, X_{r+2}, \ldots, X_{rr} \right), \ldots, \right. \right. \]
\( g \left( \bar{X}_{(r+1)r+1}, \bar{X}_{(r+1)r+2}, \ldots, \bar{X}_{rr} \right) \leq \bar{x} \right\} = d_{\eta} (\bar{x}, H(\bar{x})). \)

But we know that

\( (\bar{x}, H(\bar{x})) = (\bar{x}, P \left\{ \bar{U}_1 \leq \bar{x} \right\}) \)
\( = (\bar{x}, P \left[ g \left( \bar{X}_{11}, \bar{X}_{22}, \ldots, \bar{X}_{rr} \right) \leq \bar{x} \right\]) = d_r (\bar{x}, F_r(\bar{x})). \)

Hence,

\( d_{\eta} (\bar{x}, F_r(\bar{x})) = d_r (\bar{x}, F_r(\bar{x})) \forall \bar{x} \) and \( \forall r, \eta. \) (C.5)

Now we can show existence of a special property in the function space. That is, there exist a special member, we call this member as stable member, in each equivalent class.

Given that in every equivalent class, there exist at least one \( F_{1,a,b} \) such that

\( T_\eta \left( \bar{x}, F_1 \bar{a}_q \bar{x} + \bar{b}_q \right) \rightarrow \left( \bar{x}, F_1(\bar{x}) \right). \)

which implies

\( T_k \left( \bar{x}, F_{k+1} \bar{a}_q \bar{x} + \bar{b}_q \right) \rightarrow \left( \bar{x}, F_1(\bar{x}) \right). \)

for every \( k = 1, 2, \cdots. \) By using Equation (C.5) we get

\( T_\eta T_k \left( \bar{x}, F_1 \bar{a}_q \bar{x} + \bar{b}_q \right) \rightarrow \left( \bar{x}, F_1(\bar{x}) \right). \)

That is,

\( T_\eta \left( \bar{x}, F_1 \bar{a}_q \bar{x} + \bar{b}_q \right) \rightarrow T_{\eta}^{-1} \left( \bar{x}, F_1(\bar{x}) \right). \)

Putting \( T_\eta F_\delta = F_\gamma \) we get

\( \left( \bar{x}, F_\gamma \bar{a}_q \bar{x} + \bar{b}_q \right) \rightarrow T_{\eta}^{-1} \left( \bar{x}, F_1(\bar{x}) \right). \)

then by using multivariate version of Khintchine's theorem, there exist sequence \( \left\{ f_\eta > 0 \right\} \) and \( \left\{ c_\eta \right\} \) such that

\( T_{\eta}^{-1} \left( \bar{x}, F_1(\bar{x}) \right) = \left( \bar{x}, F_\eta \left( \bar{f}_\eta \bar{x} + \bar{c}_\eta \right) \right) \forall \bar{x}. \)

Here we need the assumption of weak convergence. Which implies

\( \left( \bar{x}, F_\eta \left( \bar{x} \right) \right) = T_\eta \left( \bar{x}, F_\eta \left( \bar{f}_\eta \bar{x} + \bar{c}_\eta \right) \right). \) (C.6)

So that \( F_{1,a,b} \) satisfies stability property.

Now, we have a partition on \( \Theta^* \) and we know that every equivalent class contains a stable member. Let \( \Theta_0 \) be one of the equivalent class introduced by the relation \( M^* \) and \( F_{1,a,b} \in \Theta_0 \) is a stable member in \( \Theta_0 \). That is,

\( T_\eta \left( x, F_1 \left( \bar{a}_q \bar{x} + \bar{b}_q \right) \right) \rightarrow T_\eta \left( x, F_1(\bar{x}) \right), \forall x \in \mathbb{R} \) and \( \forall \eta. \)

Then for all \( F_{2,r,d} \in \Theta_0 \),

\( T_\eta \left( x, F_2 \left( \bar{r}_q \bar{x} + \bar{s}_q \right) \right) \rightarrow T_\eta \left( x, F_1(\bar{x}) \right), \) as \( \eta \rightarrow \infty. \) (C.7)

Since, \( F_{1,a,b}, \ F_{2,r,d} \in \Theta_0 \) implies,

\( \lim d \left( T_\eta \left( \bar{x}, F_1 \left( \bar{a}_q \bar{x} + \bar{b}_q \right) \right), T_\eta \left( \bar{x}, F_2 \left( \bar{r}_q \bar{x} + \bar{s}_q \right) \right) \right) = 0. \)

But

\( T_\eta \left( \bar{x}, F_1 \left( \bar{a}_q \bar{x} + \bar{b}_q \right) \right) = T_\eta \left( \bar{x}, F_1(\bar{x}) \right) \forall \bar{x} \in \mathbb{R}^d \)

and \( \forall \) values of \( \eta. \)

The above two equation implies,

\( \lim d \left( T_\eta \left( \bar{x}, F_1 \left( \bar{r}_q \bar{x} + \bar{s}_q \right) \right), T_\eta \left( \bar{x}, F_1(\bar{x}) \right) \right) = 0. \)

Therefore,

\( T_\eta \left( \bar{x}, F_1 \left( \bar{r}_q \bar{x} + \bar{s}_q \right) \right) \rightarrow T_\eta \left( \bar{x}, F_1(\bar{x}) \right), \)

as \( \eta \rightarrow \infty \) and \( \forall \bar{x}. \)

Hence, in the function space, every equivalent class contains at least a stable member and all other members of that class will converge to that stable member. It is easy to prove that the limiting member is unique in every class, if it exist. This complete the proof.

**Remark C.2** In Equation (C.6), we introduce a property called multivariate stability property for some of the members in \( \Theta^* \). This is a multivariate extension of stability property in [32]. Below we give an exact definition and some examples of this property.

**Definition C.2** Let \( \left\{ T_\eta \right\} \) be a given one to one functions. We say that \( F_{1,a,b} \in \Theta^* \) satisfies stability property if it is a constant sequence in \( \Theta^* \). In other words, \( F_{1,a,b} \in \Theta^* \) satisfies stability property if for each \( \eta \),

\( d \left( T_\eta \left( \bar{x}, F_1 \left( \bar{a}_q \bar{x} + \bar{b}_q \right) \right), T_\eta \left( \bar{x}, F_1(\bar{x}) \right) \right) = 0, \forall \bar{x} \in \mathbb{R}^d. \)

That is for each \( \eta \),

\( T_\eta \left( \bar{x}, F_1 \left( \bar{a}_q \bar{x} + \bar{b}_q \right) \right) = T_\eta \left( \bar{x}, F_1(\bar{x}) \right), \forall \bar{x} \in \mathbb{R}^d. \)

A member \( F_{1,a,b} \in \Theta^* \) is called a stable member if it is a constant sequence in \( \Theta^* \). Using Equation (C.1) the stability property can be rewritten for sequence \( \left\{ \bar{X}_n \right\} \) in terms of the function \( g \) as follows.
Definition C.3 Let \( \{ \tilde{X}_n \} \) be a sequence of i.i.d.c.m.r.v and \( g \) be a Borel function of \( \tilde{X}_1, \tilde{X}_2, \ldots, \tilde{X}_n \). Then we say that \( \{ \tilde{X}_n, i \geq 1 \} \) satisfies stability property for the given function \( g \) if, for every \( \eta \),
\[
F_{\tilde{X}_n}(\tilde{x}_1, \ldots, \tilde{x}_n) \left( \tilde{a}_{\eta} + \tilde{b}_{\eta} \right) = F_{\tilde{X}_1}(\tilde{x}), \forall \tilde{x} \in \mathbb{R}.
\]

Example C.2 Let \( \{ \tilde{X}_n, n \geq 1 \} \) be a sequence of i.i.d.c.m.r.v. and \( \tilde{X}_1 \) follows strictly multivariate geometric stable distribution and \( N \) be a random variable, independent of \( \tilde{X}_1 \), and \( N \) follows geometric distribution. Let \( g(X_1, X_2, \ldots, X_n) = \sum_{i=1}^{N} \tilde{X}_i \). Then there exist a sequence \( \{ p^{1/n} > 0 \} \), depends on \( N \), such that \( \sum_{i=1}^{N} \tilde{X}_i \) is a stable member since,
\[
F_{\sum_{i=1}^{N} \tilde{X}_i}(p^{1/n} \tilde{x}) = F_{\tilde{X}_1}(\tilde{x}), \forall \tilde{x} \in \mathbb{R}^k.
\]

see [38].

Remark C.3 By Equation (C.7), each equivalent class forms the domain of attraction of a stable member. Below we define domain of attraction.

Definition C.4 Let \( T_\eta \) be a given one to one functions. Let \( \Theta_0 \subseteq \Theta^* \). For any distribution function \( G \) such that \( T_{\eta,1,1} \in \Theta \), we say that \( \Theta_0 \) is the domain of attraction of \( T_{\eta,1,1} \) if for every \( F_{\eta,a,b} \in \Theta_0 \),
\[
d \left( T_{\eta}(\tilde{x}, F_1(\tilde{a}_{\eta} + \tilde{b}_{\eta})), T_1(\tilde{x}, G(\tilde{x})) \right) \to 0 \text{ as } \eta \to \infty.
\]

That is,
\[
T_{\eta}(\tilde{x}, F_1(\tilde{a}_{\eta} + \tilde{b}_{\eta})) \to T_1(\tilde{x}, G(\tilde{x})) \text{ as } \eta \to \infty.
\]

Therefore for each stable member, there exist an equivalent class of \( \Theta^* \) which is the domain of attraction of the stable member. Below remark gives a distance measure between domain of attractions.

Remark C.4 Let \( \Psi \) be the class of all domain of attractions for a given sequences of functions \( \{ T_\eta \} \). Then \( \Psi \) is a complete metric space with metric \( \tau \), which is defined as, if \( \Theta_0 \) and \( \Theta_1 \) are two elements of \( \Psi \), then
\[
\tau(\Theta_0, \Theta_1) = \lim_{\eta \to \infty} d \left( T_\eta(\tilde{x}, F_1(\tilde{a}_{\eta} + \tilde{b}_{\eta})), T_\eta(\tilde{x}, F_2(\tilde{a}_{\eta} + \tilde{b}_{\eta})) \right)
\]
where \( \left( T_\eta(\tilde{x}, F_1(\tilde{a}_{\eta} + \tilde{b}_{\eta})) \right) \in \Theta_0 \) and \( \left( T_\eta(\tilde{x}, F_1(\tilde{a}_{\eta} + \tilde{b}_{\eta})) \right) \in \Theta_1 \). For the proof see Theorem 27 in [39] and a complete proof see Page (202,203) in [40].

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